

Full Mueller Imaging

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Outline

- A brief overview of Imaging
- The role of antenna primary beams in Imaging
- Full Mueller Imaging
 - Who needs it
 - Its implementation in CASA as a general Imager.
- Modelling the antenna Aperture Illumination Pattern (AIP)
 - Zernike basis modelling (VLA example)



Measurement Equation



Snapshot





2 Hr synthesis



4 Hr synthesis





4 Hr Multi Frequency Synthesis



Measurement Equation





Imaging in Practice



Standard, Mosaic, W-projection, A-Projection AW-projection

CS-Clean, Hogbom, MT MFS, Multiscale





Convolutional gridding



Gridding Convolution Function

- Prolate Spheroidal CSClean
- Fresnel Kernel W-Projection
- Aperture Illumination Function –

A-Projection

Prolate Spheroidal



Fresnel Kernel





Wide-field Imaging



Small FoV

w-value per baseline is small. 2D vCZ holds. Large FoV or Non-Coplanar Array

Large w-values. Need to account for w in imaging Algorithms – facetting, w-projection



W-Projection





Antenna Primary Beam

Varies with time, frequency and direction on the sky



Time

Frequency



Courtesy: S. Bhatnagar



Antenna Primary Beam



FM AW-Projection -I

Observed Visbilities Continuous Coherence Function Sampling Function

$$A_k^{\circ^{-1}} = \frac{adj(A_k^{\circ})}{det(A_k^{\circ})}$$

Correction Matrix is applied in two steps.





Full Mueller A-Projection - Convolution Functions



Aperture Real

Aperture Imaginary





Full Mueller A-Projection – Mueller Matrix

The cross correlation of two antenna jones matrices is the mueller matrix

In data domain the mueller matrix tranforms into the ~unitary A matrix.

 $\begin{pmatrix} J_i^R J_j^{R*} & -J_i^R J_j^{RL*} & -J_i^{RL} J_j^{R*} & J_i^{RL} J_j^{RL*} \\ J_i^R J_J^{LR*} & J_i^R J_j^{L*} & -J_i^{RL} J_j^{LR*} & -J_i^{RL} J_j^{L*} \\ J_i^{LR} J_j^{R*} & -J_i^{LR} J_j^{RL*} & J_i^L J_j^{R*} & -J_i^L J_j^{RL*} \\ J_i^{LR} J_j^{LR*} & J_i^{LR} J_j^{L*} & J_i^L J_j^{LR*} & J_i^L J_j^{L*} \end{pmatrix}$







FM AW-Projection - II

Gridding with the hermitian conjugate transpose of A

$$\vec{V}_k^M = \sum_k A^{M^{\dagger}} \star (A_k^{\circ} \star \vec{V}^{\circ}) \delta_k$$

Accumulating the averaged convolution function for normalization

$$\overline{A^M} = \sum_k A^M_k$$

Normalized Residual Image - End of Major cycle

$$\vec{I}^R = \frac{F\sum_k \vec{V}_k^{Obs} - \vec{V}_k^M}{\det(F\overline{A^M})}$$





HUDF – Standard gridder 3GHz



0.4 microJy



HUDF – AWP gridder 3GHz



0.4 microJy



Full Mueller A-Projection - In practice

- As shown in the algorithm above it is a major cycle algorithm applied in two steps.
- A gridding kernel that is the conjugate transpose of the A matrix.
 - We call these convolution functions
 - Ray traced models based on Grasp 8 simulations
 - Oversampled in the data domain
 - In the Full-Mueller Case
- Anti-diagonal is negligible so 12 instead on 16.
- Rotate cache for the corresponding parallactic angle on the fly, else one unique set of convolution functions for each parallactic angle.
- Gridding in serial takes very long even for small data sets. Only feasible when done in parallel.



FM AW-Projection – III



4.4 microJy



4 microJy theoretical sensitivity





FM AW-Projection – IV – Polarized Intensity



RM~120 rad/m/m



RMSF Polarized Source RM=100





Who needs FM AW-Projection

- What fraction of the field of view contains your source of interest
 50% in power and beyond at reference frequency
- 2. What is your bandwidth ratio?
 - Bandwidth/(Reference Frequency) > 0.2
- 3. Did you make a pointed mosaic for sensitvity?
 - Narrow band mosaic ?
 - Broad band mosaic ?
- 4. Did you integrate for a very long time for increased senstivity?
- 5. What fidelity do you require in your source flux density and spectral index ?
- 6. Do you need wide-field polarization leakage correction ?





PART II Modelling Aperture Illumination Pattern

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Aperture Illumination Pattern

- High fidelity and high dynamic range imaging requires
 - Accurate convolution functions to project out WB A term.
 - Reach true thermal noise across the wide FOV.
 - A good model of off-axis polarization leakage.
- Convolution Functions
 - In feed basis
 - Aperture Illumination Pattern (AIP) of the antenna
 - In CASA they are produced through Ray tracing.



Reality Check

- Does ray tracing reproduce the aperture illumination pattern
 ?
 - Mostly Correct in Stokes I as a function of Frequency.
 - Stokes Q and U only approximately
- How do we compare the efficacy of ray tracing ?
 - We compare the ray traced AIP, and look at its FT, the antenna far field voltage pattern, also called the primary beam.
 - Primary beam of an interferometric array is measured through holography.
 - The VLA carried out holography measurements. (Perley, VLA Memo 195). Data were re-reduced in CASA.



Holographic Measurements





Holographic Measurements





Making the model mimic reality

- Fix stokes I side-lobe levels by tweaking the model.
- Tweaks must be physically motivated.
 - Apparent blockage due to the antenna secondary.(Moves power from main-lobe into the side-lobes)
 - Feed Illumination taper.(alters side-lobe power)





Minimization - (Model - Measurement)

- Multi parameter minimization
 - Apparent illumination blocked by secondary
 - Feed Illumination taper polynomial
 - Pointing offset
- A stand alone C++ code to tweak the ray traced beam was created.
- Python wrappers to access the convolution functions and run the minimization in parallel using multi-processes.
- Serial run time of 4-6 hours for one channel in an antenna.
- Parallel implementation moved to two AWS clusters and 1024 channels reduced in 8 hours time, accounting for spot pricing. (Erik Bryer and James Robnett).



Aperture Blockage





Zernike Modelling of the Aperture

- Purely python code does minimization for the coeffecients per channel in under 6seconds.
- All minimization was carried out on a single node on a single thread within CASA.
- Six orders of Zernike polynomials were used to model the AIP without having to transform into PB ever.
- Measured AIP were obtained by padding and FT of the measured PB through Holography
- 3 Different telescope AIP were modelled this way, VLA, ALMA and MeerKAT.



Zernike Modelling VLA



0.01	0.02	0.03	0.04	0.05	0.06	0.07	0.08	0.09	





R



Fit





Zernike Modelling ALMA







Zernike Modelling MeerKAT







Х



Conclusions

- Full Mueller AWP required for wide field Polarimetry. A requirement for most deep surveys with current and future radio interferometric arrays.
- In the absence of FM AWP the beam leaks flux from Stokes I to Stokes Q and U and alters the true polarized signal and for short integrations reduced RM signal and P due to depolarization.
- Extremely important to have the correct full polarization convolution functions for performing Full Mueller AWP.
- Ray-tracing has proved very useful in the Stokes-I case but falls short of modelling the off-diagonal leakage terms
- Zernike polynomial modelling reproduces the AIP of quickly and accurately across all polarization and is basis agnostic.





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