



Giant Metrewave Radio Telescope (GMRT): A System Overview

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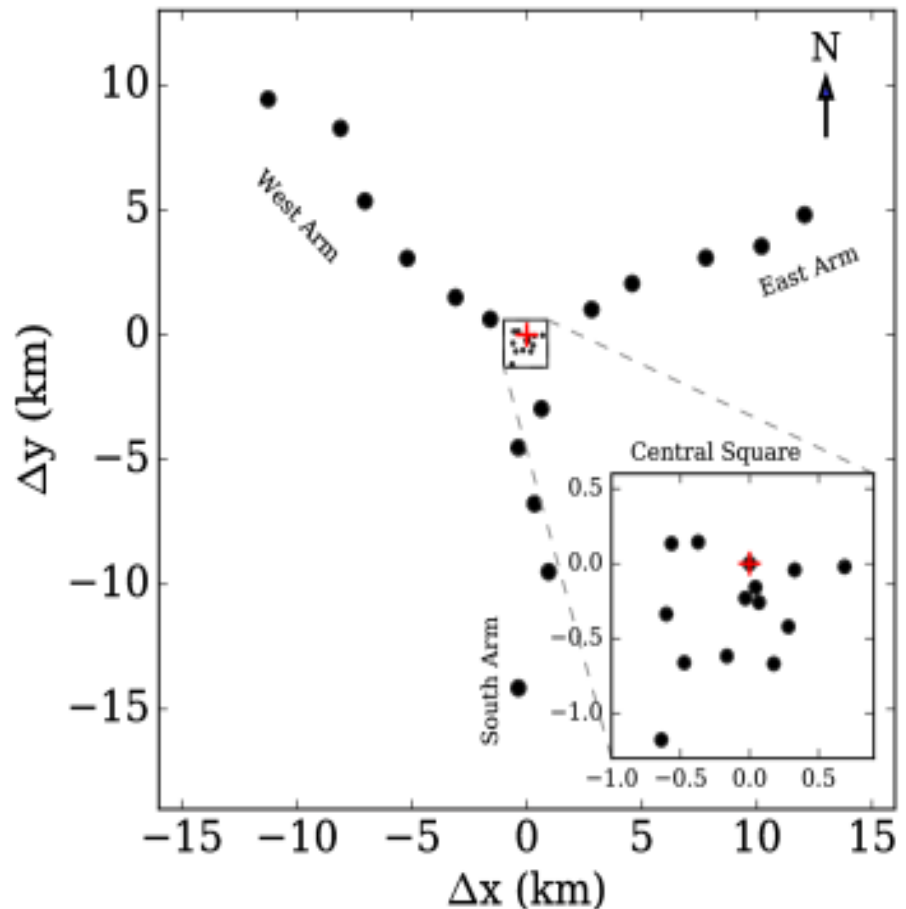
Radio Astronomy School - 2024

November 23 2024

GMRT

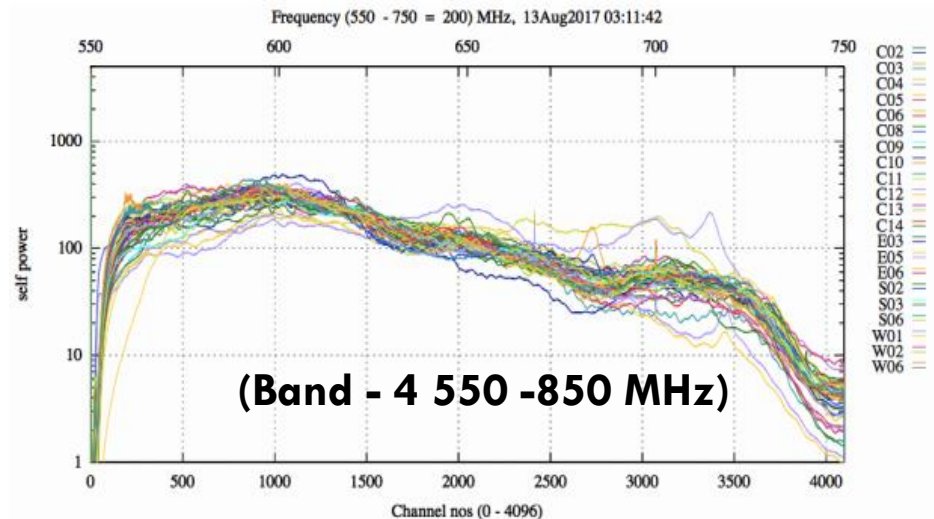
Giant Metrewave Radio Telescope

- Sensitive telescope operating between 120 to 1450 MHz. A national project of the Govt. of India
- Located 80 km north of Pune, 160 km east of Mumbai
- Array telescope: 30 antennas, each of 45 m diameter. 14 antennas in 1 sq. km. region, other spread in a Y-shaped array
- Central square (C00 – C14, except C07), E-arm (E02-E06), W-arm (W01-W06), S-arm (S01-S06, except S05)



The Upgraded GMRT

- Near seamless observing (120 – 1450 MHz)
- Four observing bands:
 - ▣ Band -2 (120 – 240 MHz)
 - ▣ Band -3 (250-500 MHz)
 - ▣ Band -4 (550-850 MHz)
 - ▣ Band -5 (1050-1450 MHz)
- 400 MHz instantaneous bandwidth
- Improved sensitivity ($P=kTB$ watts, for noise-like signals)



Angular Resolution: resolving distant objects

Resolve two distant objects in the sky

$$\theta \sim \lambda/D$$

For a given wavelength, depends on the diameter of the telescope or maximum separation between two antennas

GMRT best resolution (L-band Synthesized beam): $\sim 2''$

Two Radio Telescopes with the same angular resolution

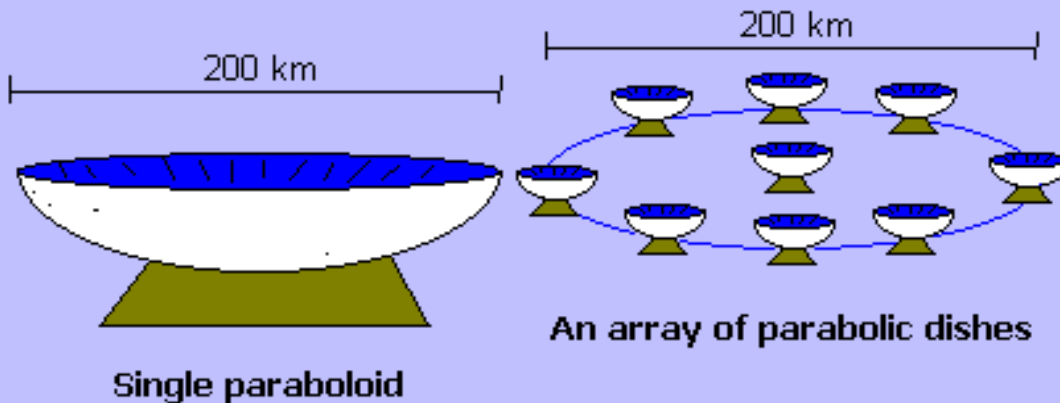


Image Source: Internet



Sampling the source signal through different apertures

Short Spacing Antennas of GMRT



Shortest spacing $\sim 100\text{m}$; largest spacing $\sim 25\text{km}$

Image Courtesy: NCRA Archives

GMRT Systems

GMRT Engineering Groups

Front-End

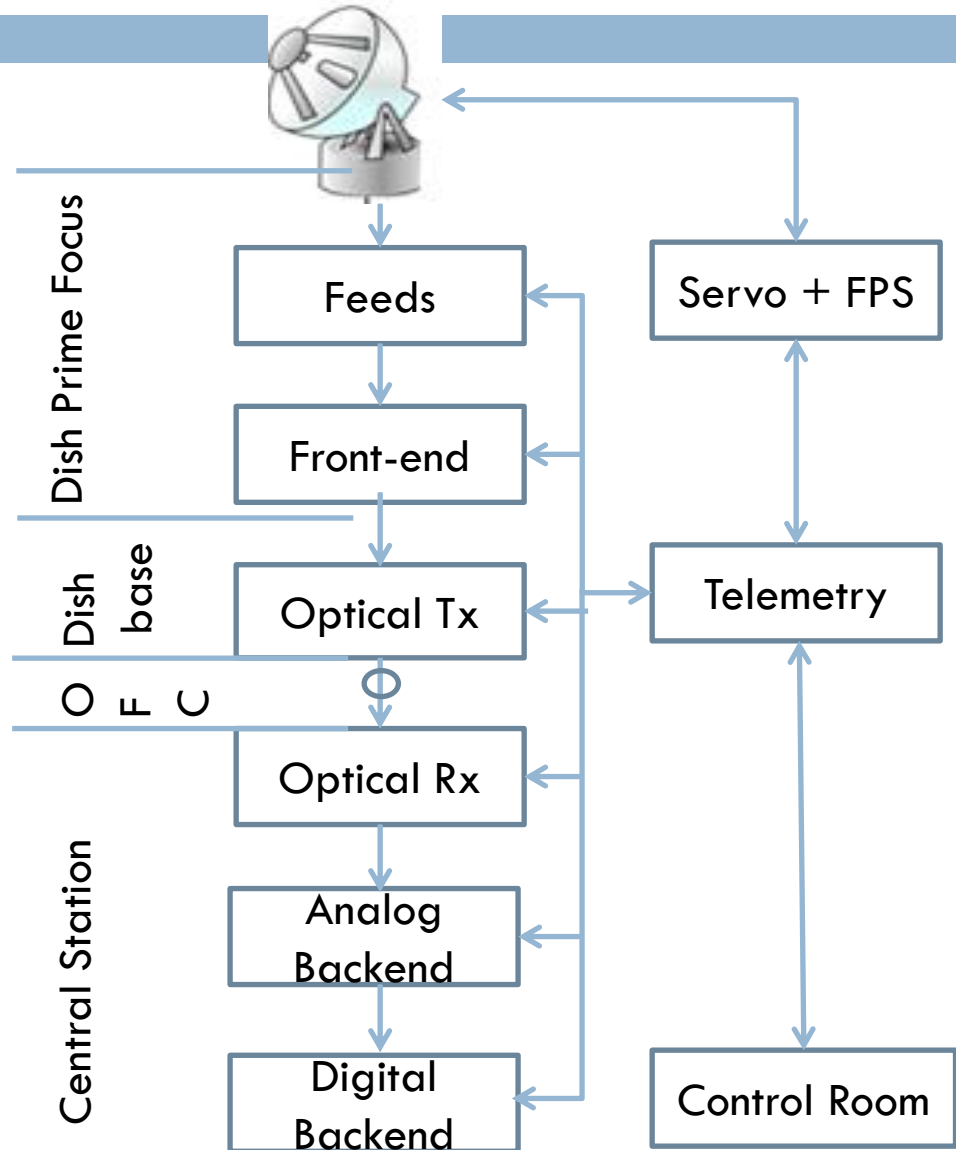
Backend

Servo

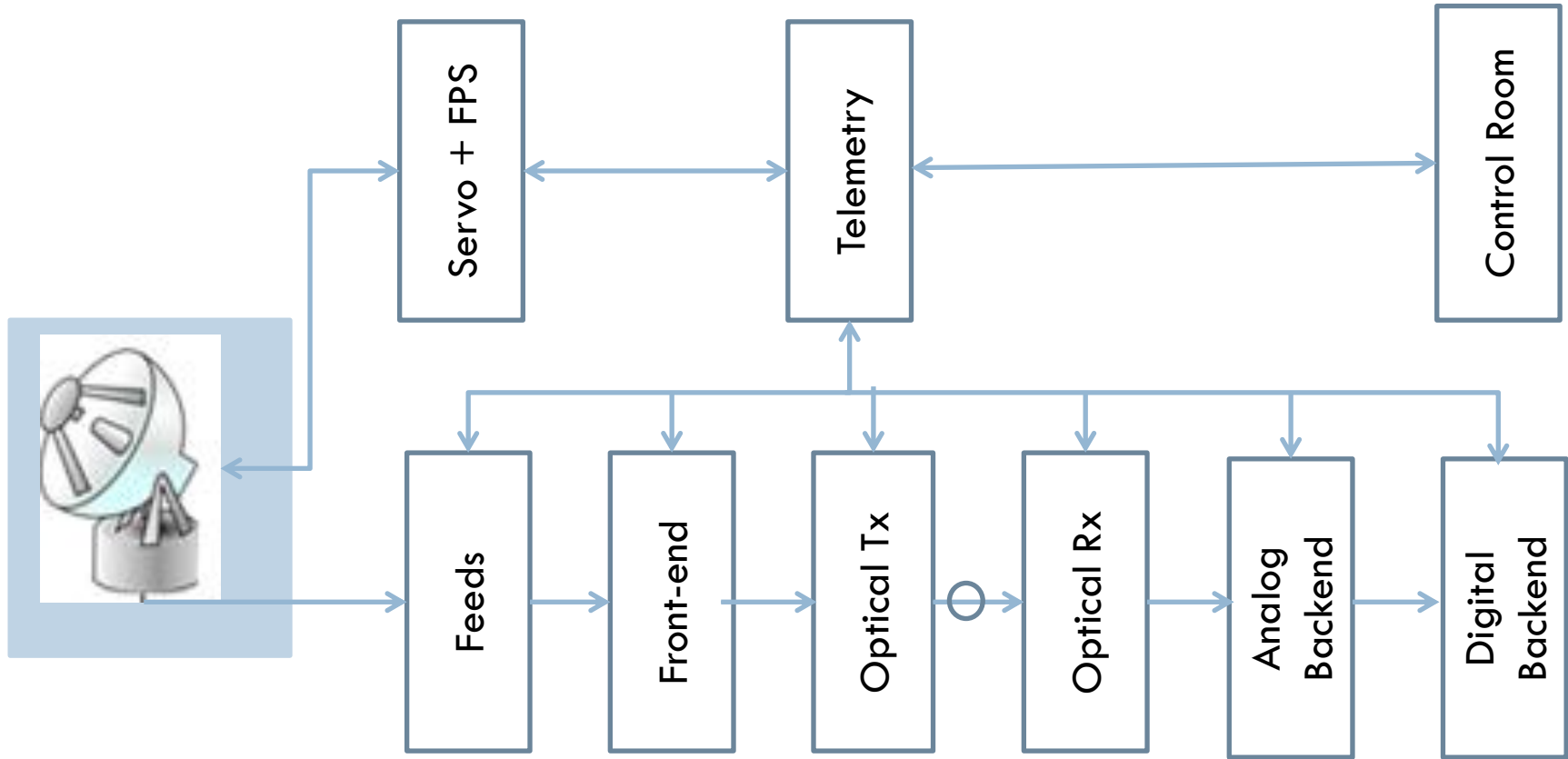
Mechanical

Electrical and Civil

Telemetry



GMRT Systems



GMRT Antenna

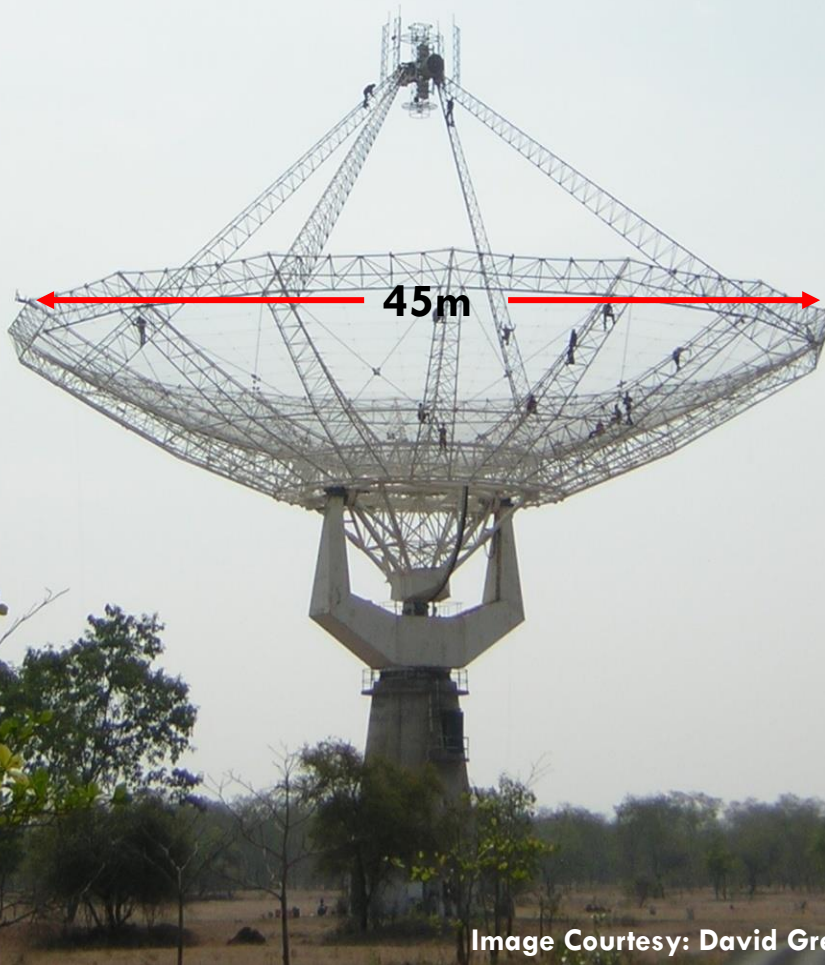


Image Courtesy: David Green

- Prime-focus parabolic reflector dish antenna of 45m diameter
- Physical aperture depends on the dish area illuminated by the feed – ~60% up to L-band; ~40% in L-band
- Wire mesh as reflecting surface
- Three sectors with different mesh sizes: 10x10 mm (innermost), 15x15 mm and 20x20 mm (outermost)
- Effective collecting area (GMRT)
30,000 sq m at lower frequencies
20,000 sq m at highest frequencies
- Four feeds mounted on a turret

One of the 30 dishes of GMRT

GMRT Antenna Parameters

Parameter	Value
Focal Length	18.54 m
Physical Aperture	1590 m ²
f/D ratio	0.412
Mounting	Altitude – Azimuth
Elevation Limits	17 to 110 degrees
Azimuth Range	± 270 degrees
Slew Rates	Alt – 20 degree / min Az - 30 degree / min
Weight of moving structure	82 tons + counter weight of 34 tons
Survival wind speed	133 km/hour
RMS surface error	10 mm (typical)
Tracking and Pointing Error	< 1' arc (up to 20 kmph) Few arc min(> 20 kmph)

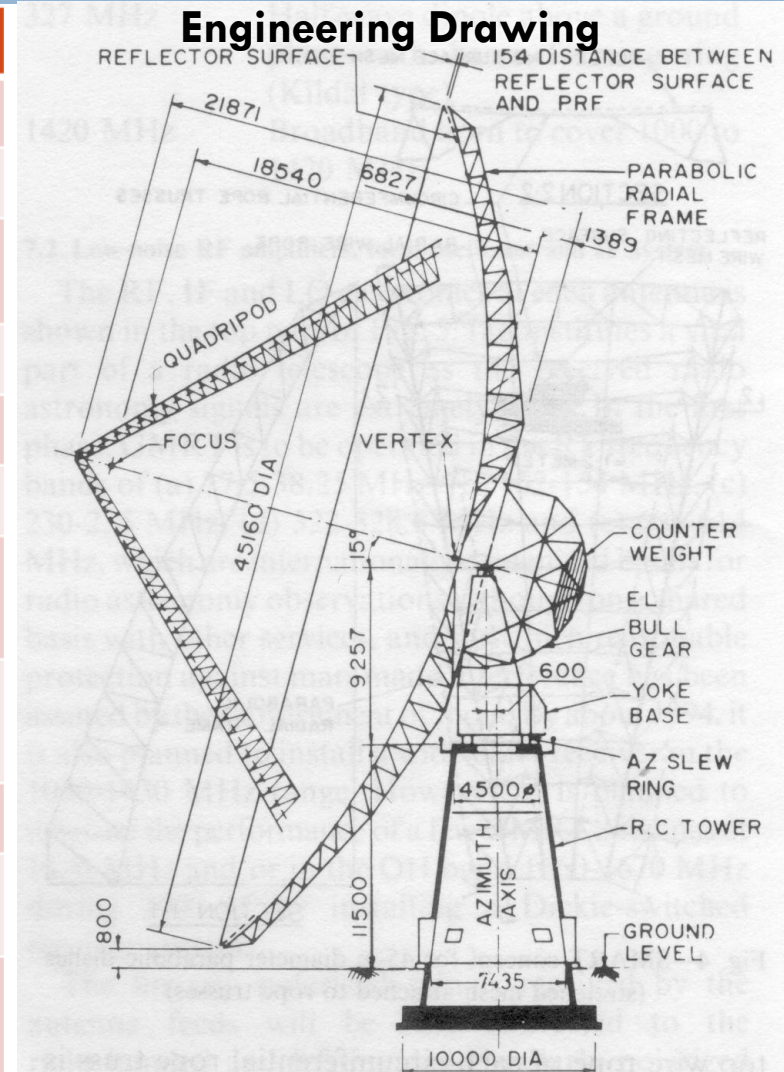


Image Courtesy: Mechanical Group

Dish and Reflecting Surface



- 7% solidity with 0.55 mm diameter Stainless Steel (SS) wires spot-welded at junction point to form a surface with 10x10 / 15x15/ 20x20 mm wire-grid.

- Mesh panel supported by SS rope trusses attached to tubular parabolic frame: SMART (Stretched Mesh Attached to Rope Trusses) concept to form the parabola.

Radio Telescope: Overall Picture

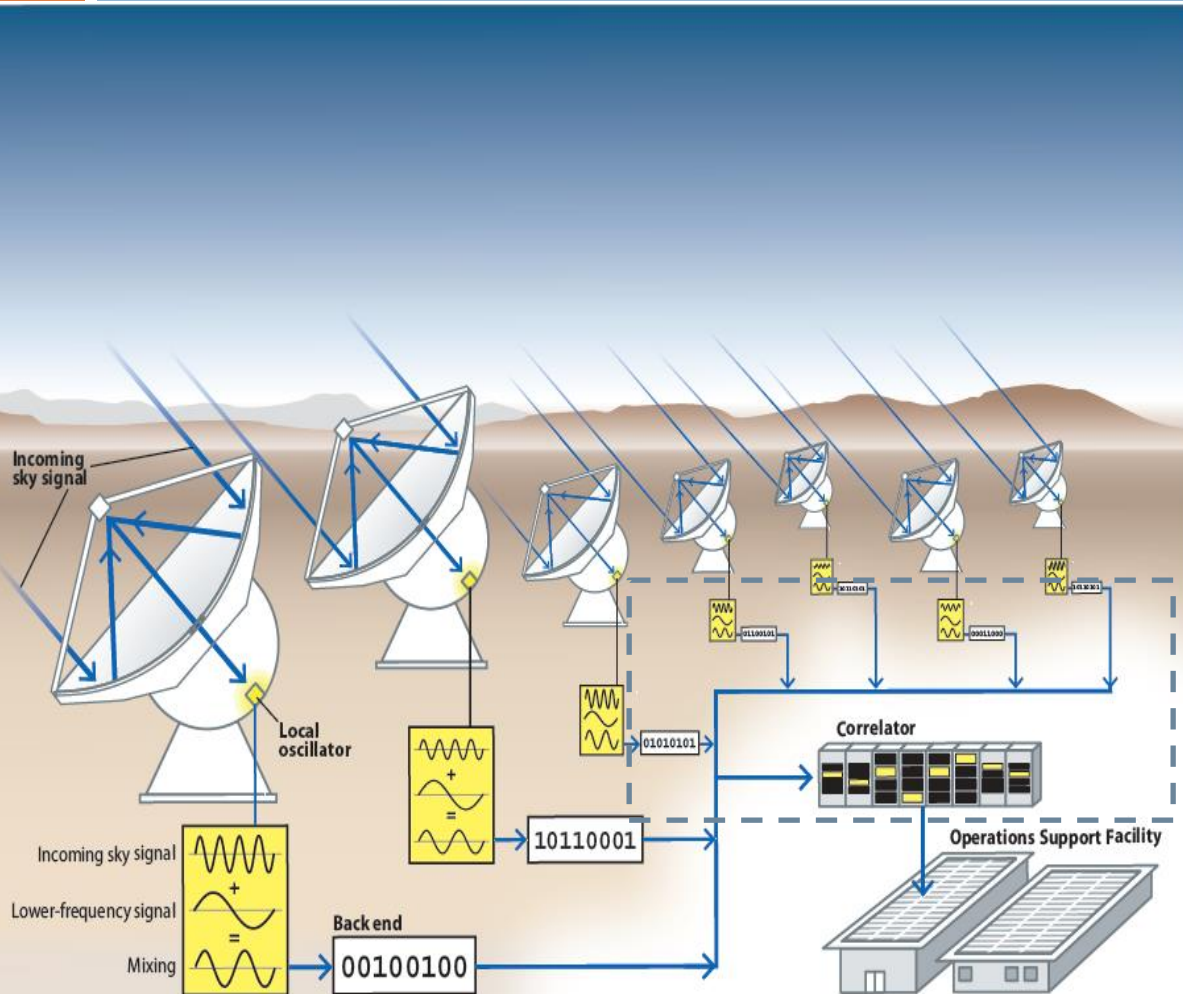


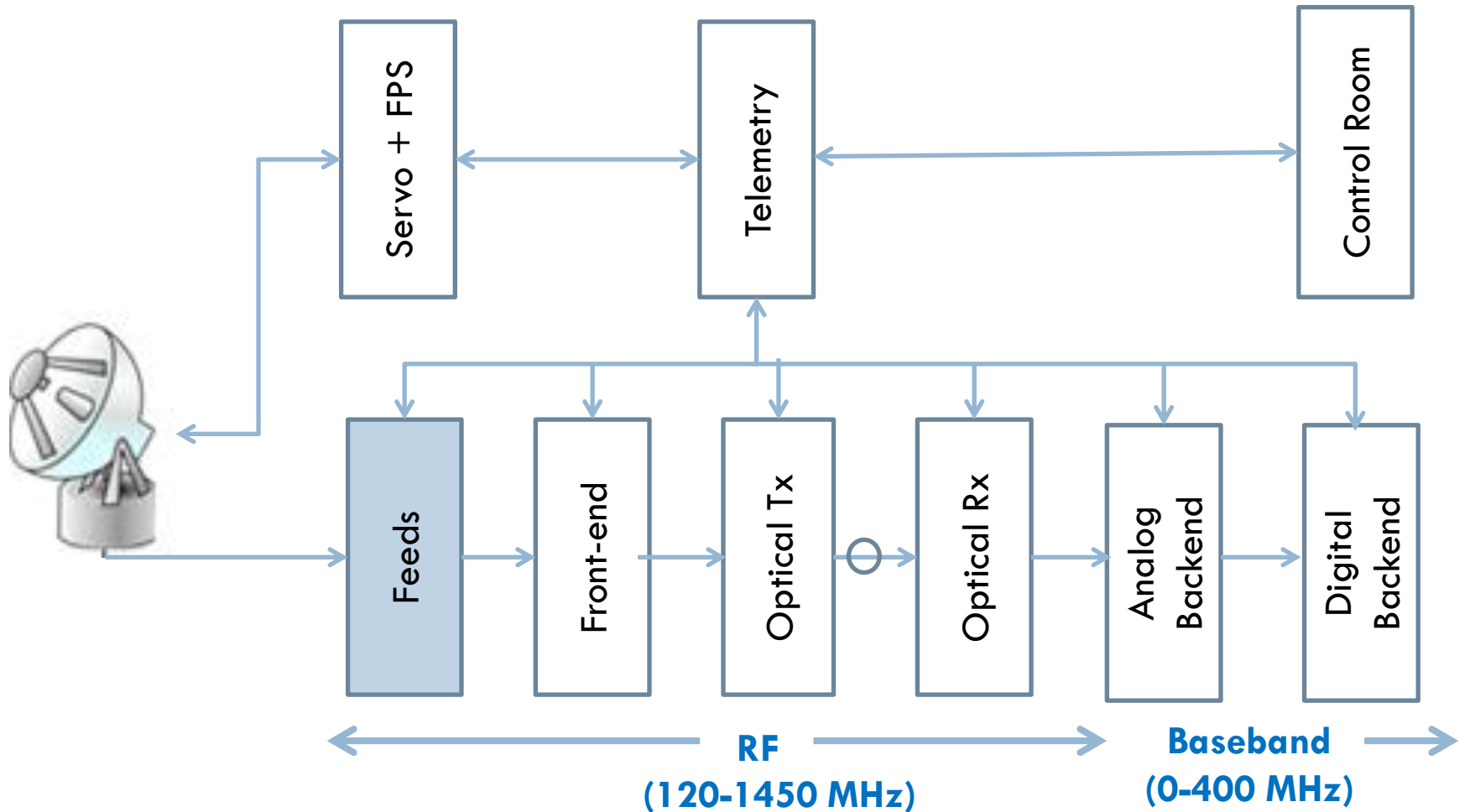
Image Source: Internet

- Converting EM to electrical signals
- Signal Conditioning (amplification, filtering, frequency down-conversion)
- Signal transport (optical fiber) to a common location
- Digitization
- Correlation
- Beamforming
- Recording

Additional systems:

- Servo rotation – accurate pointing
- Telemetry – remote control of various systems from a common location

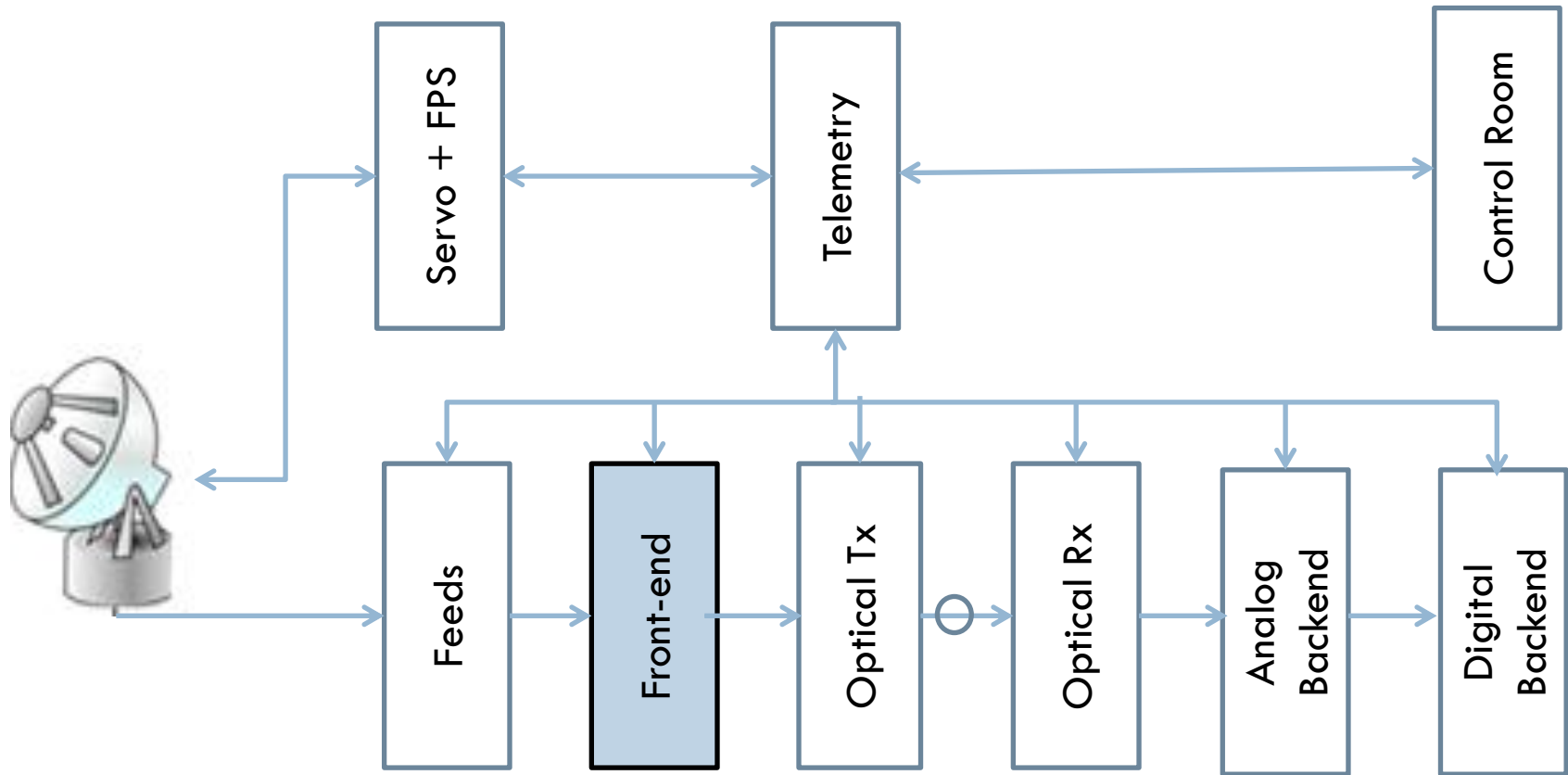
GMRT Systems



Feeds and Front-end Electronics



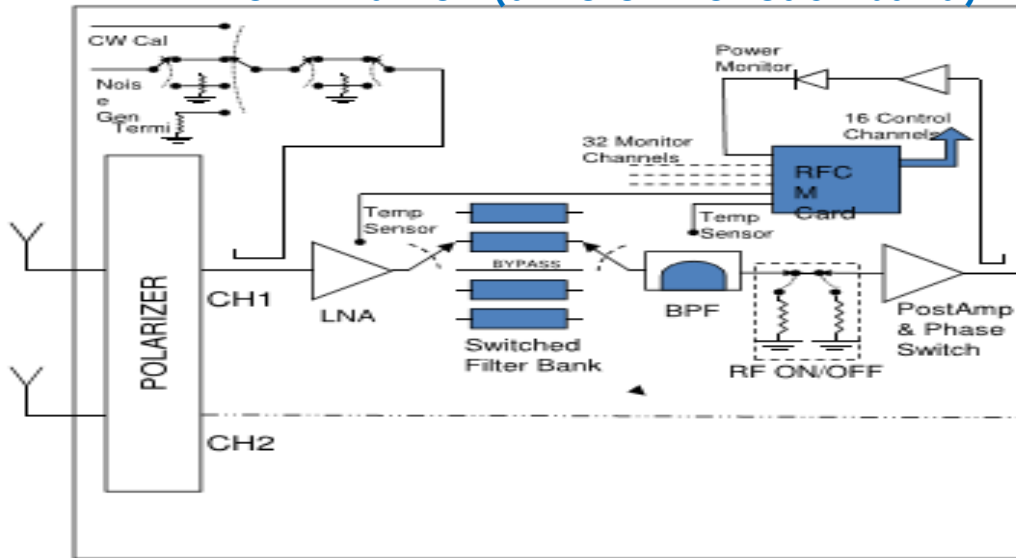
GMRT Systems



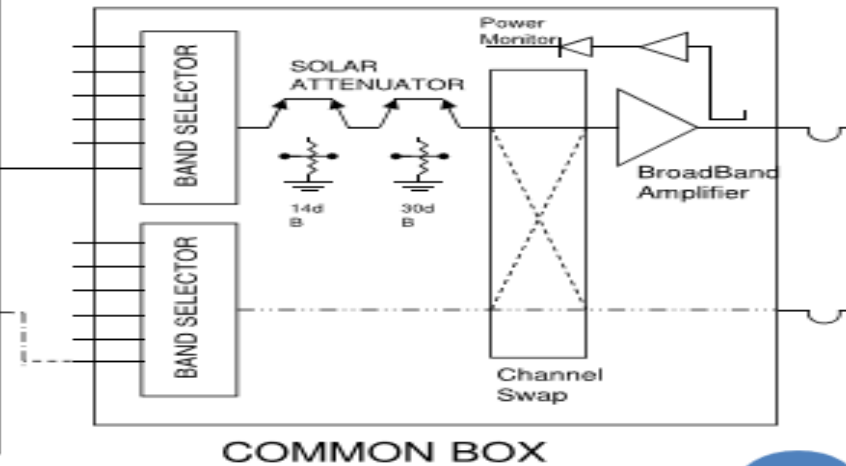
Challenges: Sensitivity and Dynamic Range

Front-end Systems

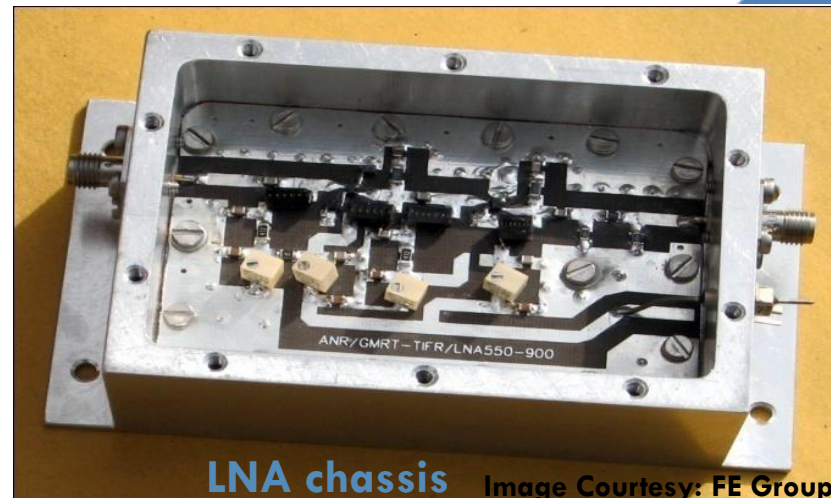
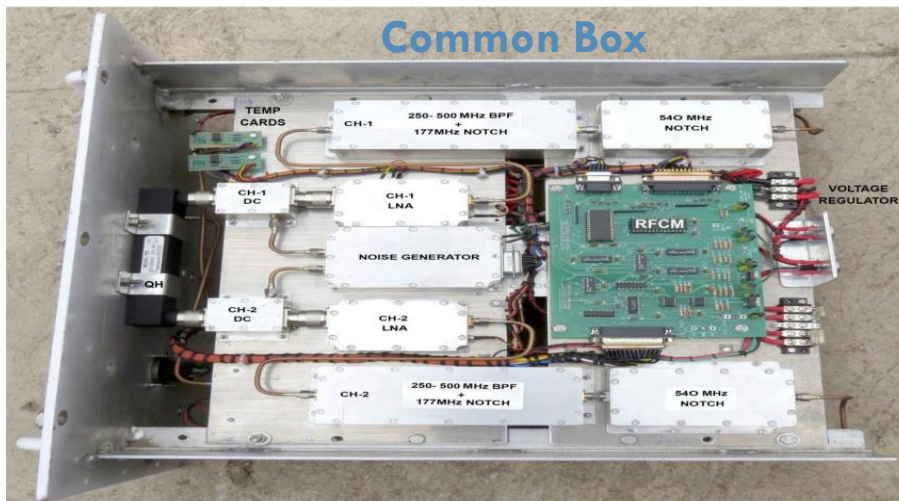
Front End Box (different for each band)



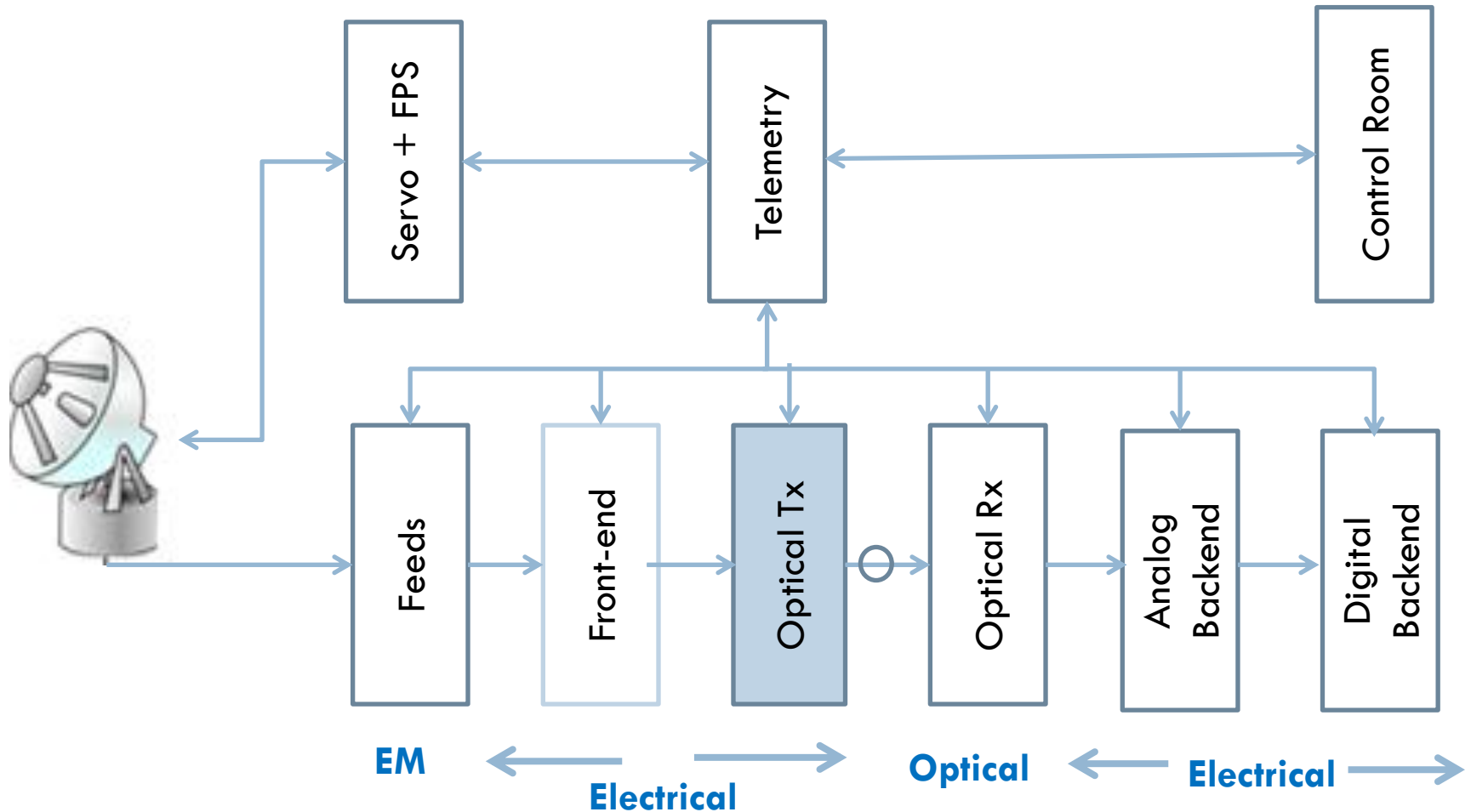
Common Box



Common Box



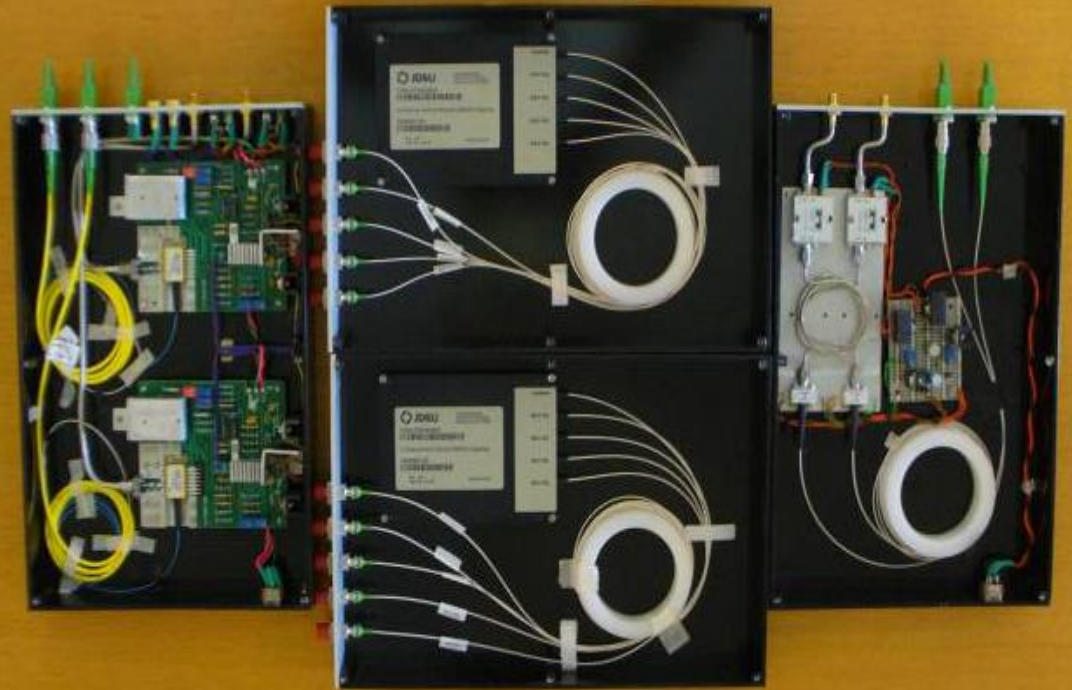
GMRT Systems



Fiber Optics System

- First radio telescope to use analog fiber optic link for signal transport.
- Fiber buried at a depth of 1.5m below the ground to reduce the effect of temperature on phase stability of the link.
- Link distances vary from 200 m to 22 km.
- Dense wavelength division multiplexing (DWDM) to accommodate multiple data and control channels on a single fiber.

Forward link: Central Electronics Building to Antenna
Reverse link: Antenna to Central Electronics Building

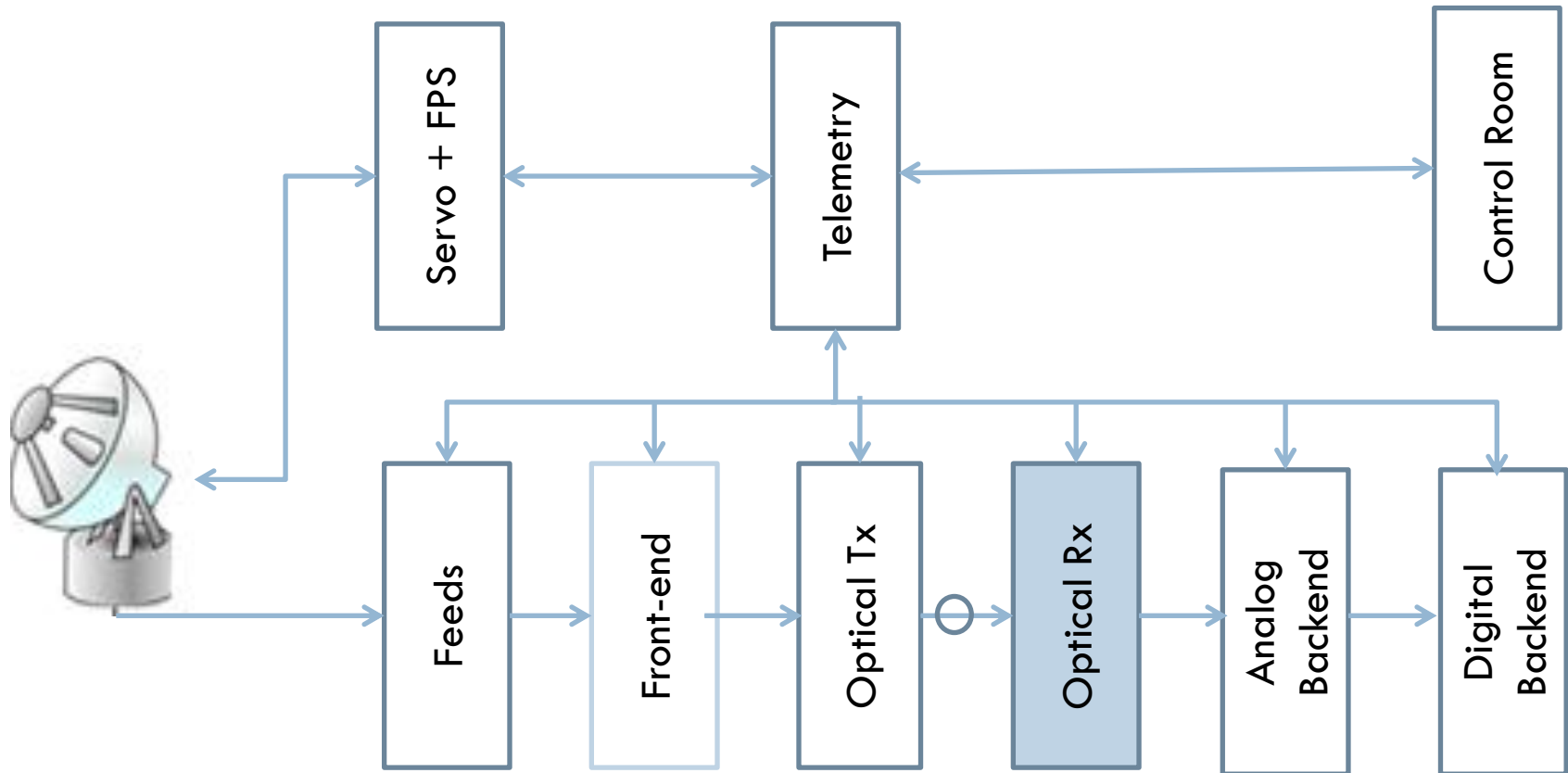


Signal Processing in the Central Electronics Building

(Optical Rx, Analog Backend, Digital Backend, Control Room)

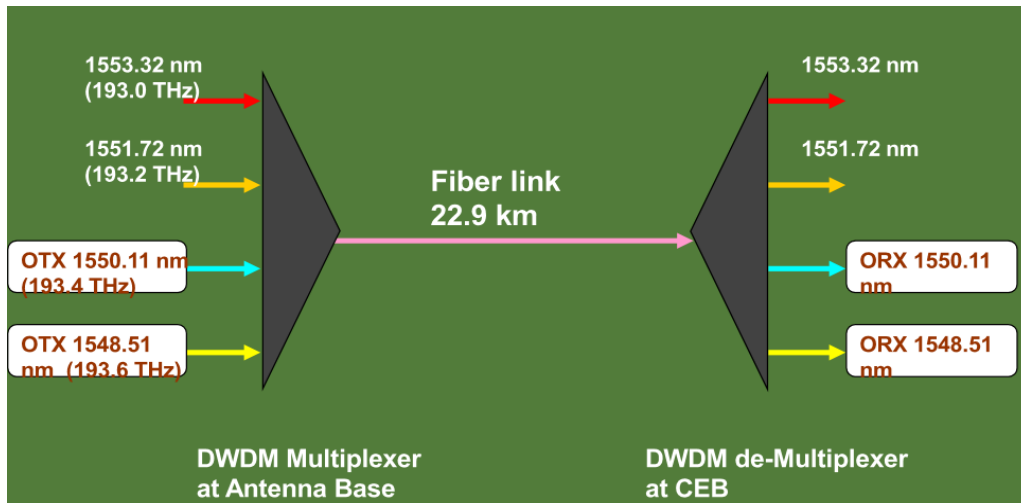


GMRT Systems

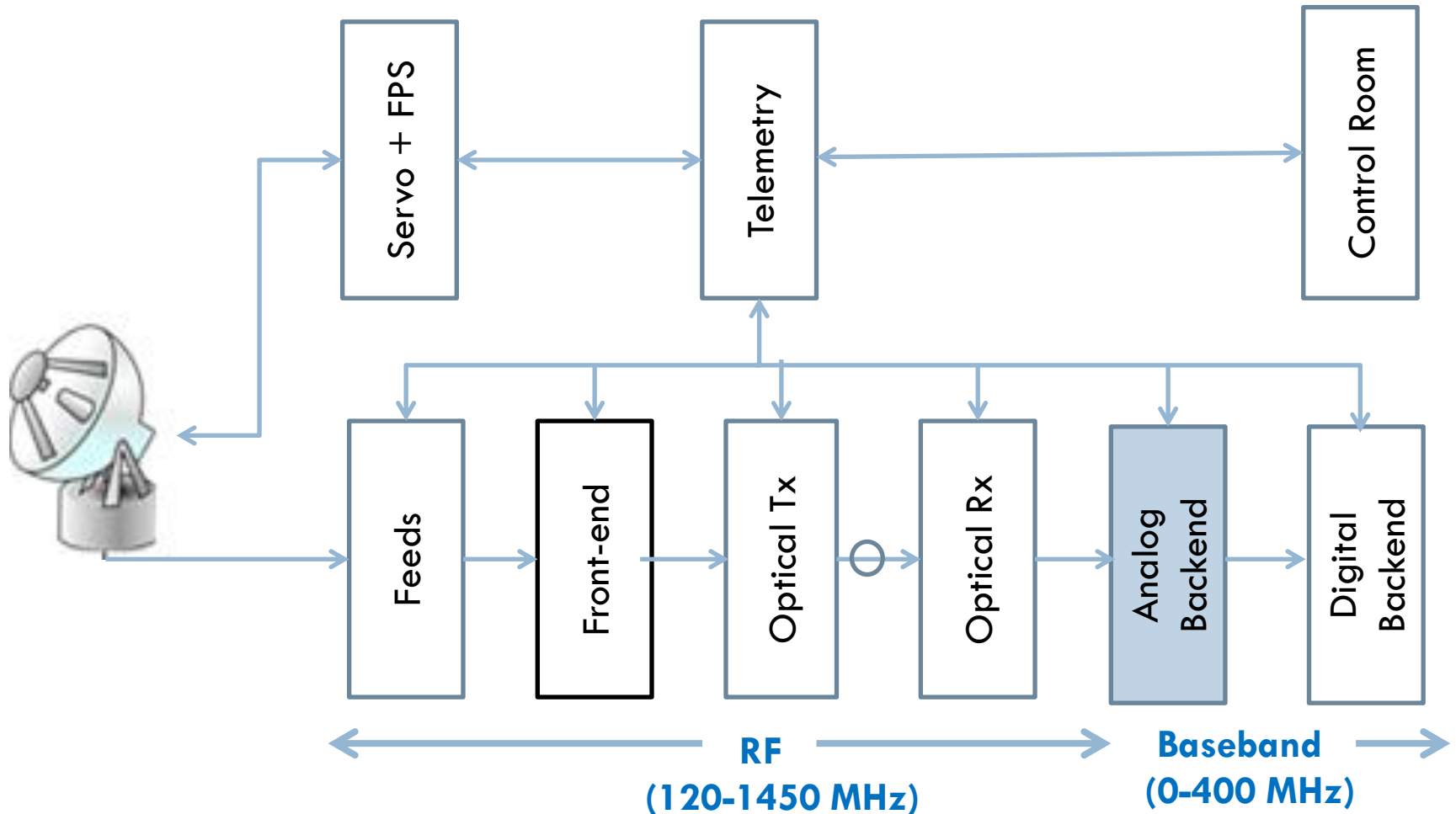


Challenges: Dynamic Range and Phase Stability

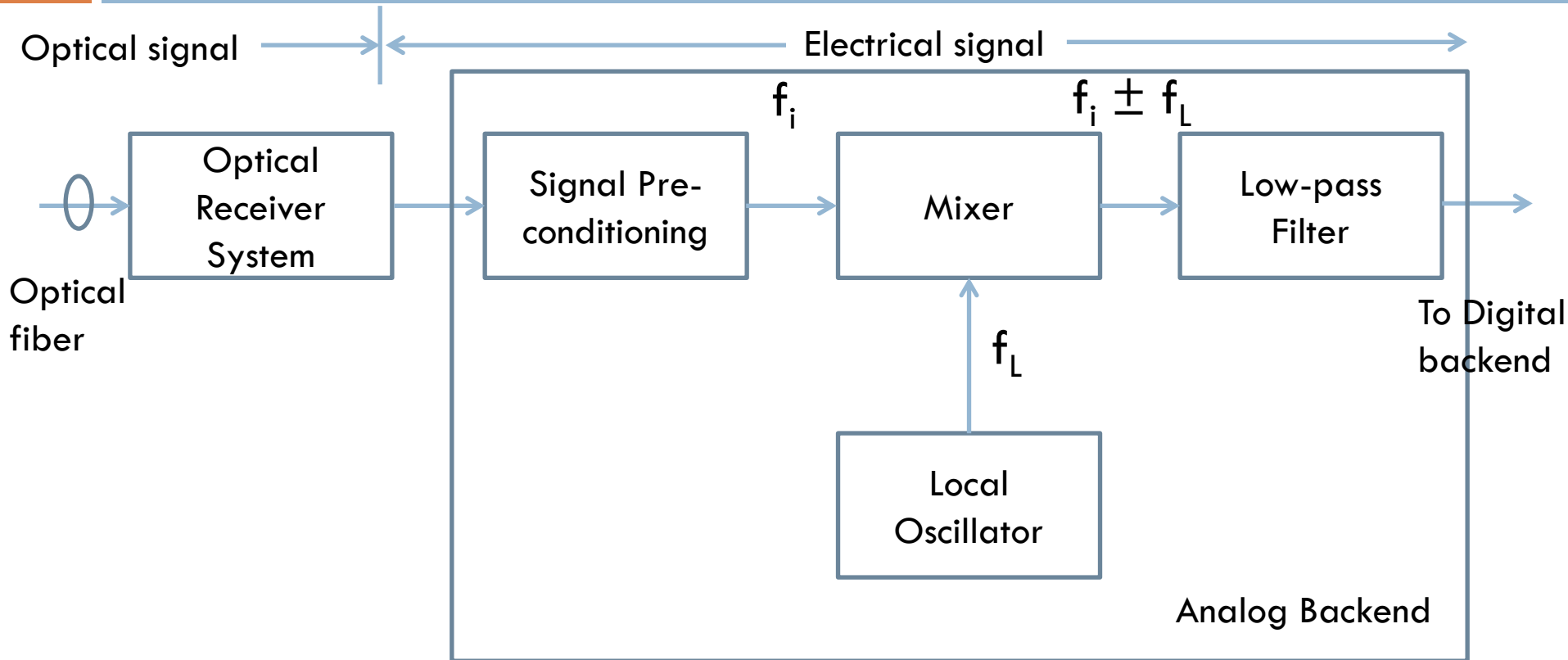
Optical Receiver System



GMRT Systems



Signal Processing in Receiver Room



Analog backend amplifies the signal, converts from radio frequency (120 -1450 MHz) to baseband (0-400 MHz) through frequency heterodyning and provides desired bandwidth signal to the digital system

Baseband System - Installation



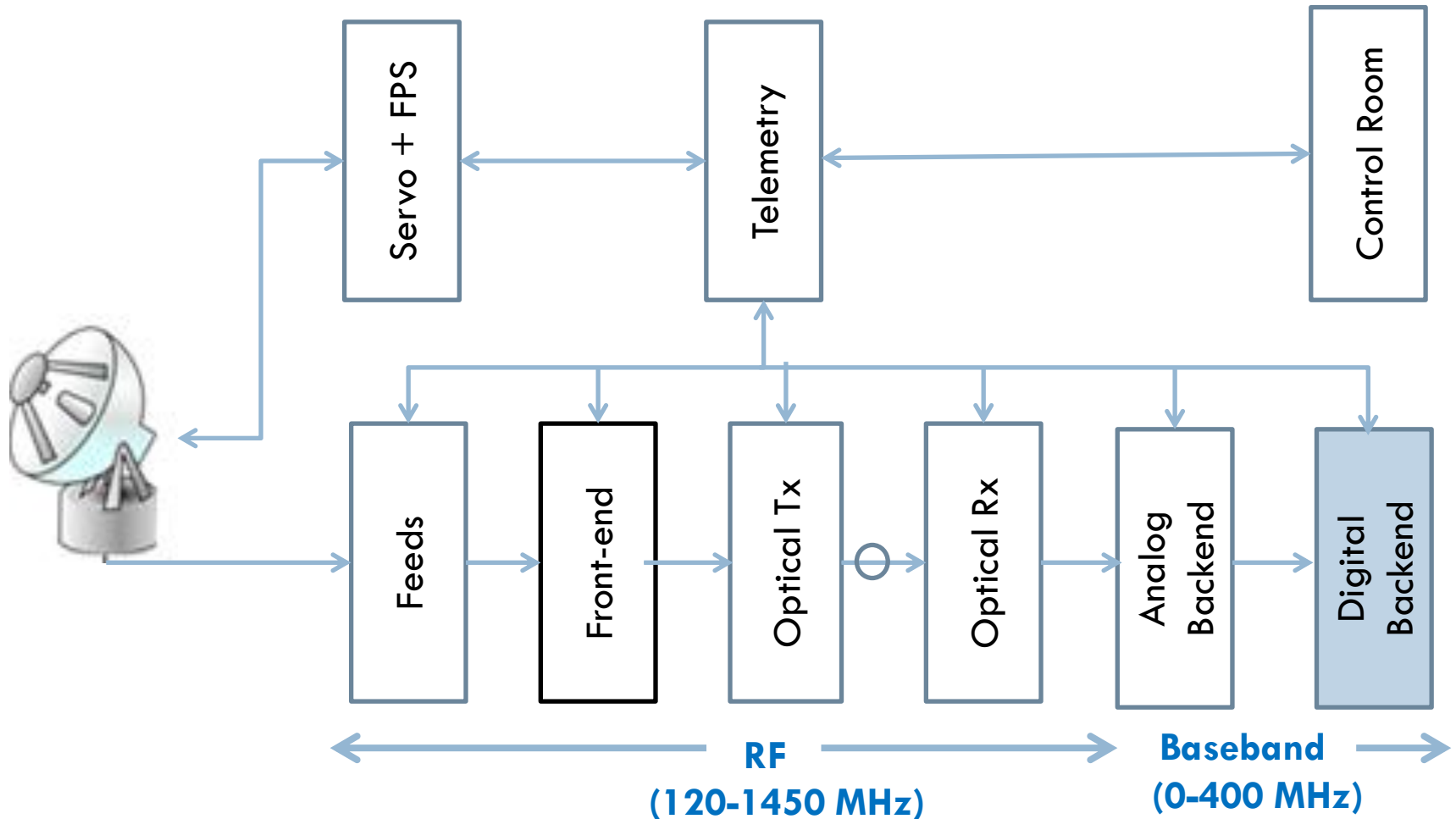
Plug-in Units



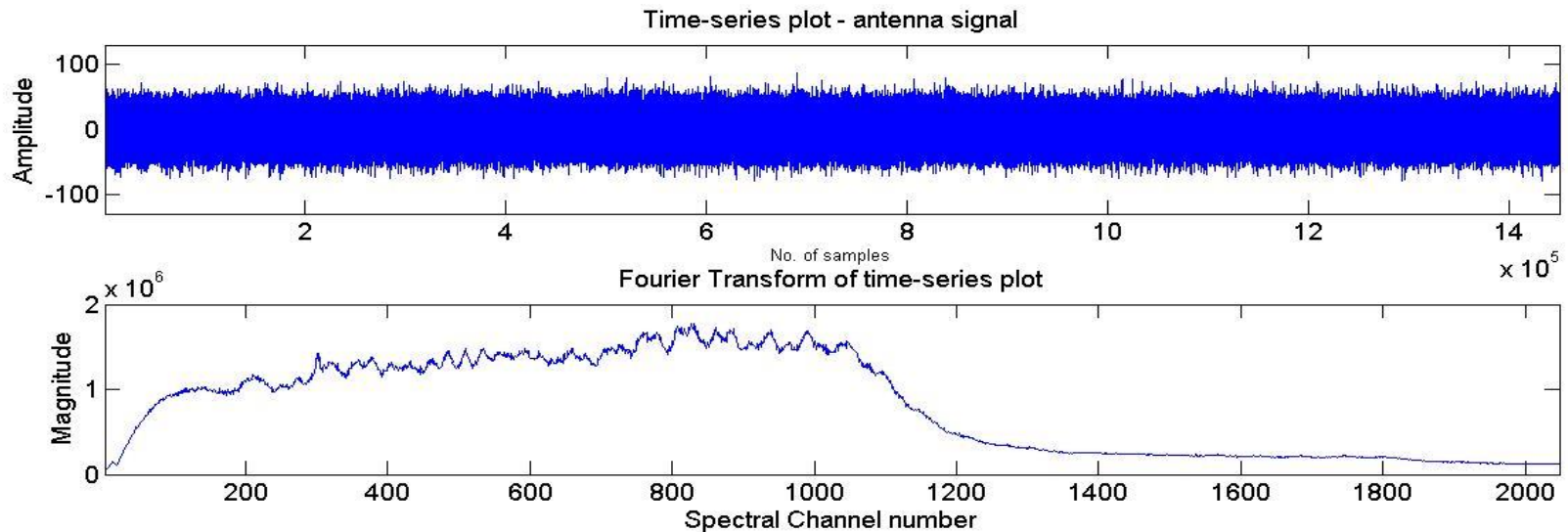
Image Courtesy: Analog Backend Group

GMRT Systems

Challenges: Real-time Signal Processing



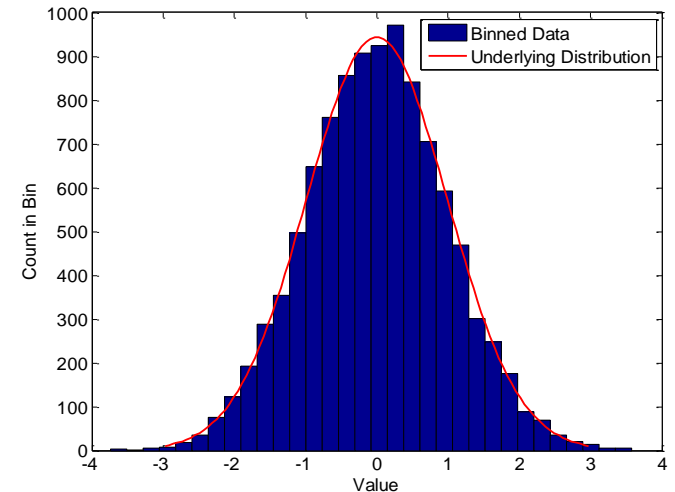
Astronomical Signal



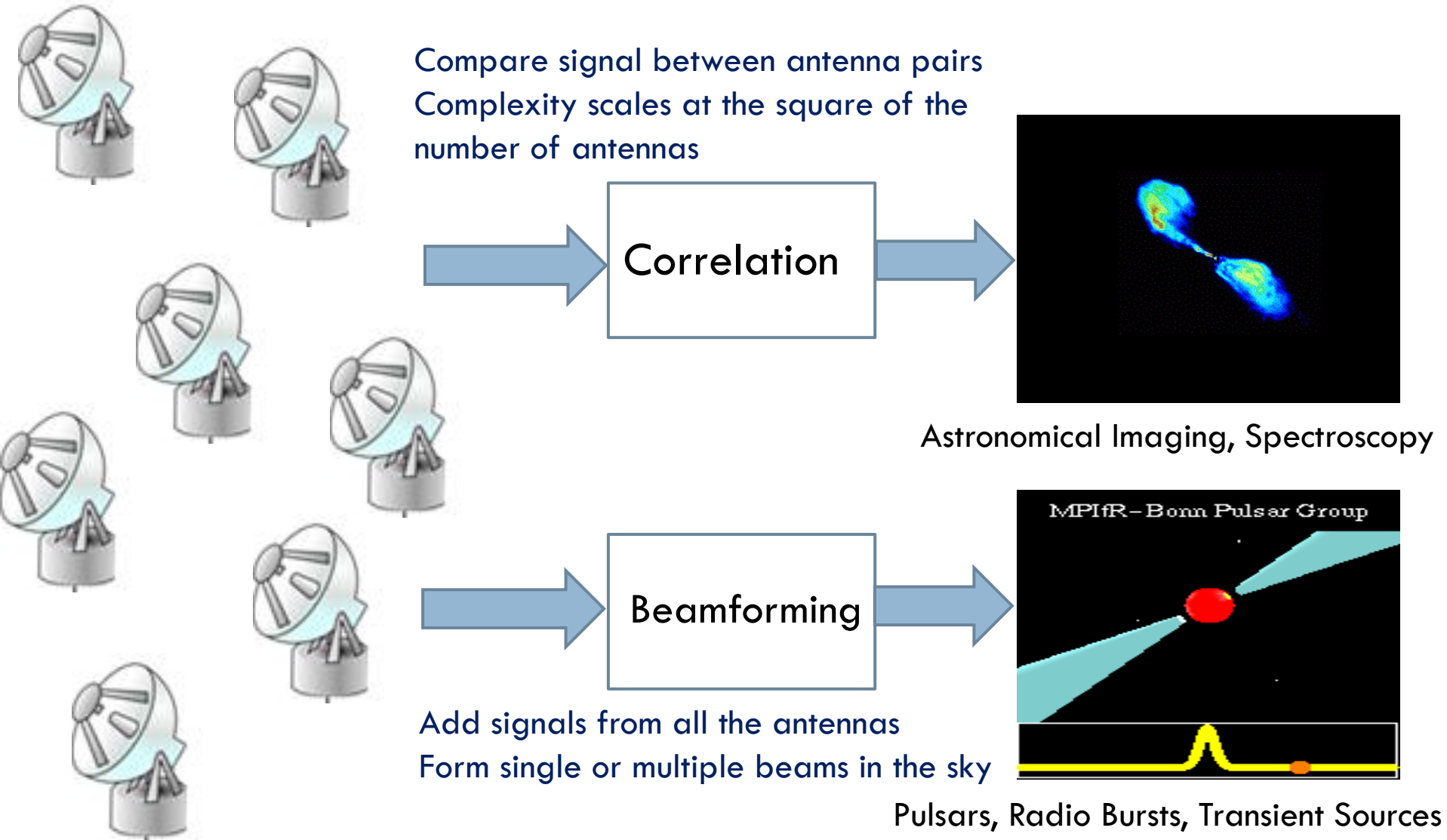
- Zero mean Gaussian distributed random signal
- Stationary random process – mean and autocorrelation do not change with time (under ideal conditions)
- Noise power measured over bandwidth

$$P = kTB \text{ Watts}$$

K = Boltzmann constant, T = Temperature, B = Bandwidth



Correlation & Beamforming



Signal Correlation

Radio Source



Digitized signal from Antenna#1



Digitized signal from Antenna#2

$$R_{xy}(\tau) = \sum_{n=0}^T x[n]y[n + \tau]$$

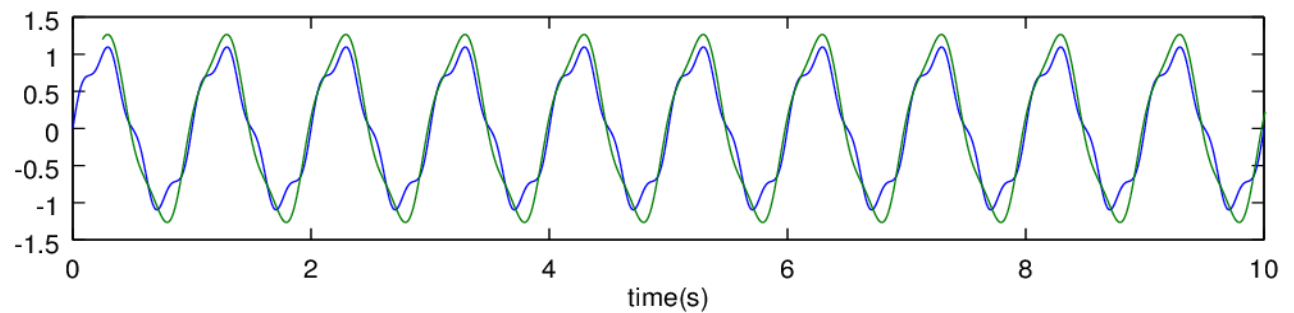
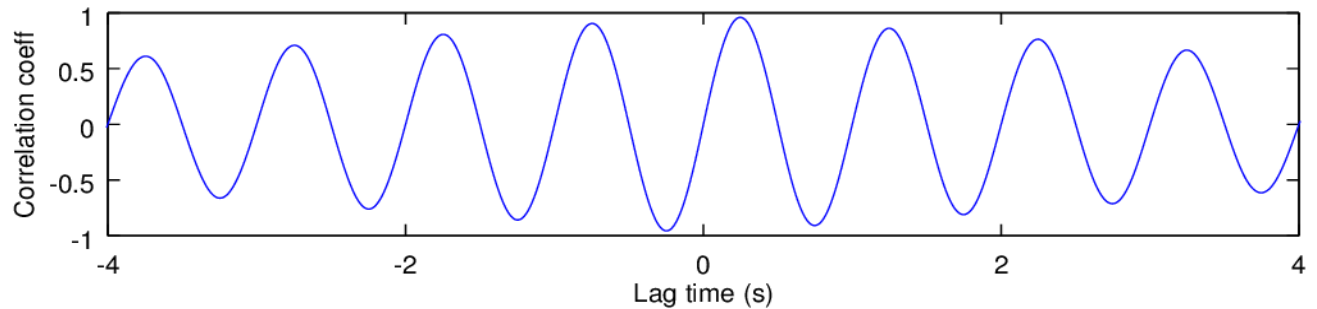
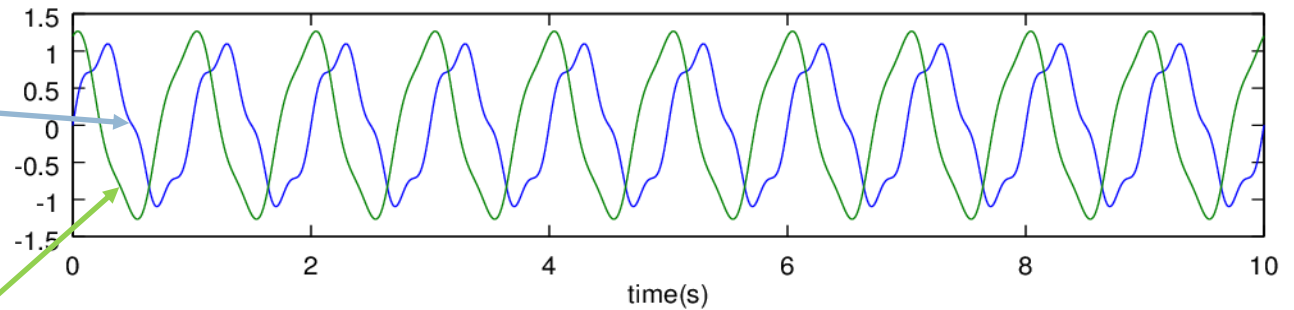
Cross Correlate signals from antennas after correcting for the delay between them (τ).

For N antennas, $n(n-1)/2$ cross-correlation operations are required. That makes it really complicated!

A computationally efficient method is to transform signals to frequency domain and multiply

Correlation gives information about the similarity between two signals - the common component contributed by the source

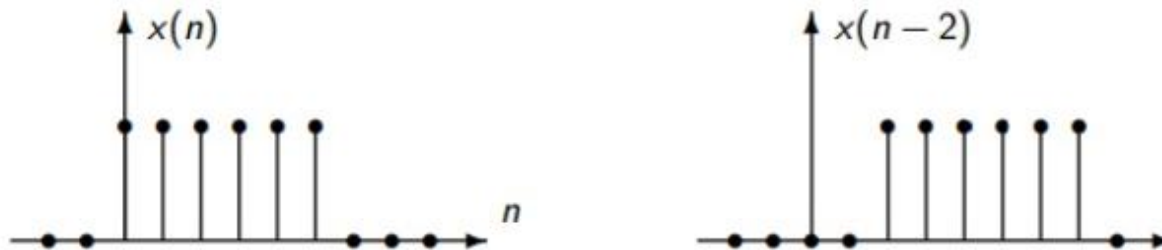
Correlation as a function of lag



Delay Correction

(A)

Time delay can be corrected by appropriately sliding the sequences in time domain
Useful when the delay is integer multiple of the clock period



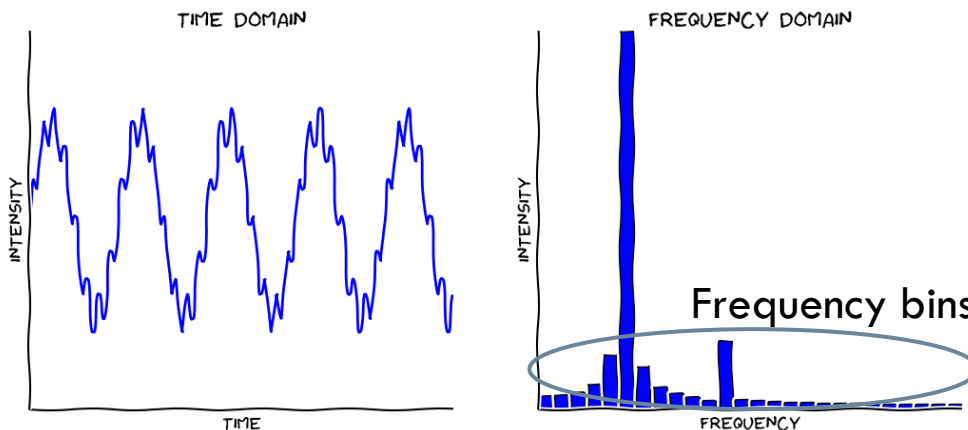
(B)

Can also be corrected by phase multiplication in the frequency domain
Useful for correcting delays that are sub-multiple of the clock period

$$x(t - t_0) \xleftrightarrow{FT} e^{-j\omega t_0} X(j\omega)$$

Correlation in the Fourier Domain

- ❑ Perform Discrete Fourier Transform (DFT) on the antenna signals
- ❑ Fast Fourier Transform – computationally efficient algorithm for computing DFT (N^2 vs $N \log_2 N$)
- ❑ N-point transform provides a frequency resolution of (sampling freq. / N) Hz.



- ❑ Implementation resources and complexity increases with the number of points
- ❑ Frequency resolution depends on the type of observation. Usually the no. of points is of the range of 2048 to 32768 for wideband receivers

Signals in the Fourier domain are multiplied $X(\omega)Y(\omega)$ for getting the cross-correlation – this is done for each bin of antenna#1 with antenna#2 and so on.

Correlation of Complex Signals

- ❑ The output of FFT is complex number
- ❑ Complex multiplication is required for this - each operation needs 4 multiplications and 2 additions

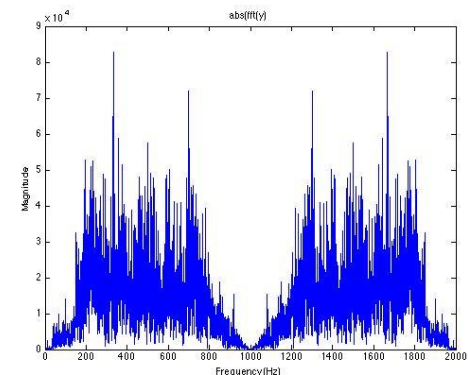
$$\begin{aligned}z_1 z_2 &= (x_1 + iy_1)(x_2 + iy_2) \\ &= x_1 x_2 + ix_1 y_2 + ix_2 y_1 + i^2 y_1 y_2 \\ &= (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)\end{aligned}$$

Image courtesy: <http://www.thefouriertransform.com/math/complexmath.php>

- ❑ Since the input signal is real, the number of frequency bins contain redundant information are not used for further processing or correlation (conjugate symmetry property of DFT)

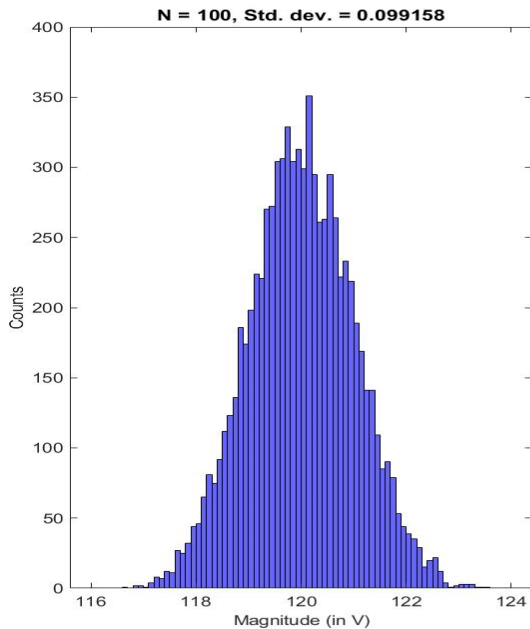
$$X(j\omega) = X^*(-j\omega)$$

- ❑ Note: The above property does not hold if the input is a complex signal

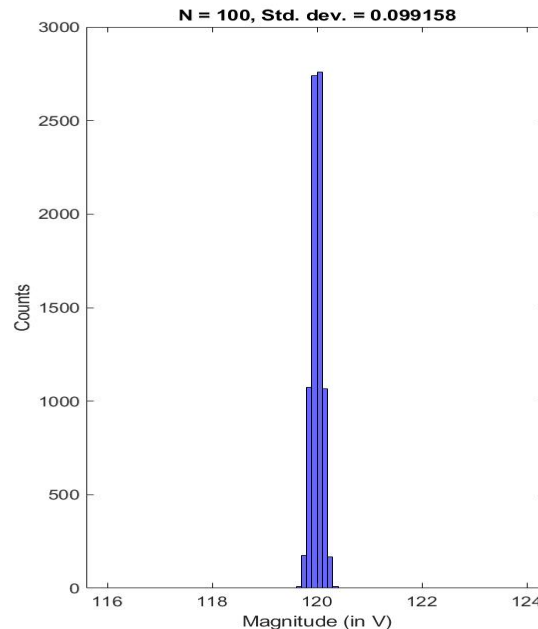


Integration

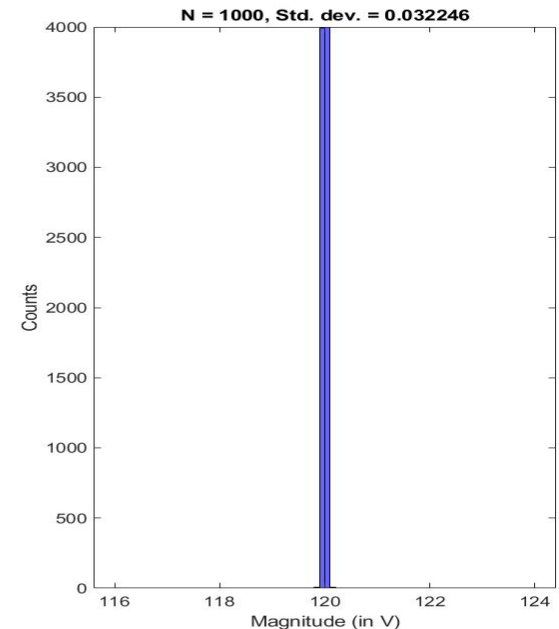
$N = 1, \sigma = 0.99$



$N = 100, \sigma = 0.1$



$N = 1000, \sigma = 0.03$

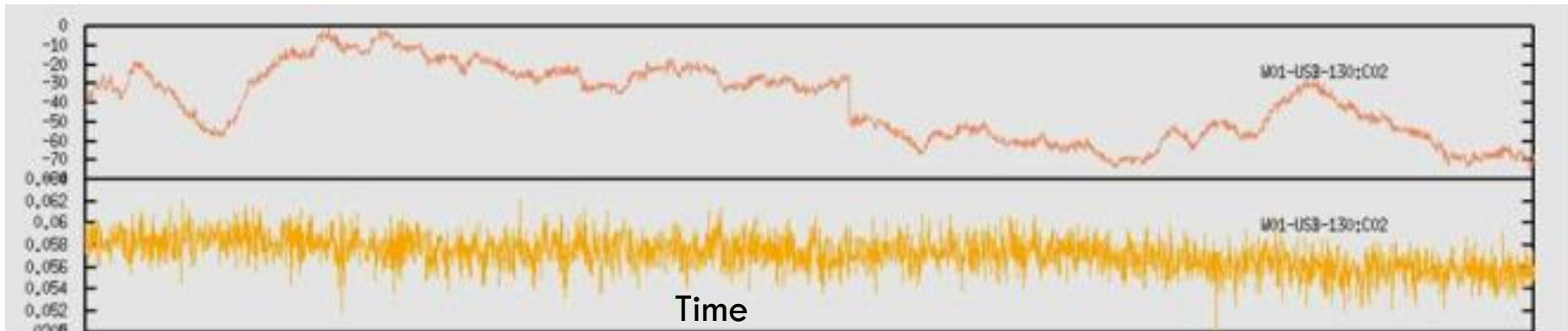
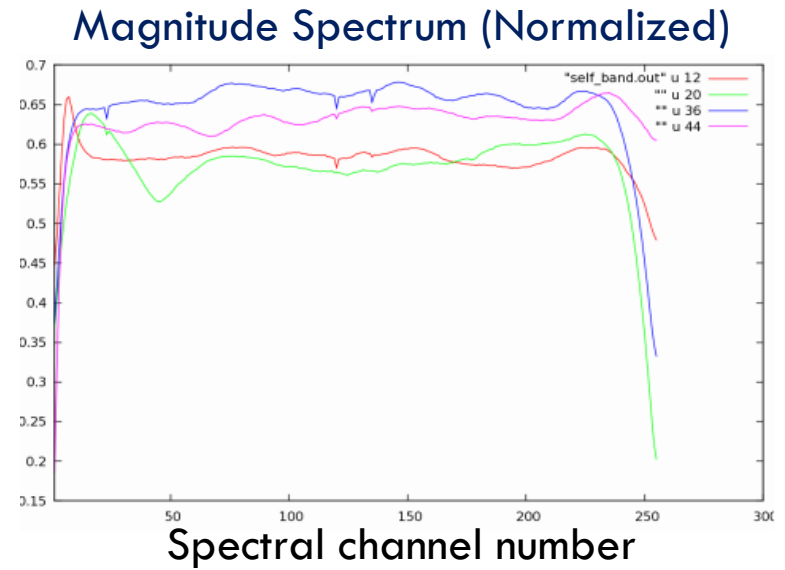
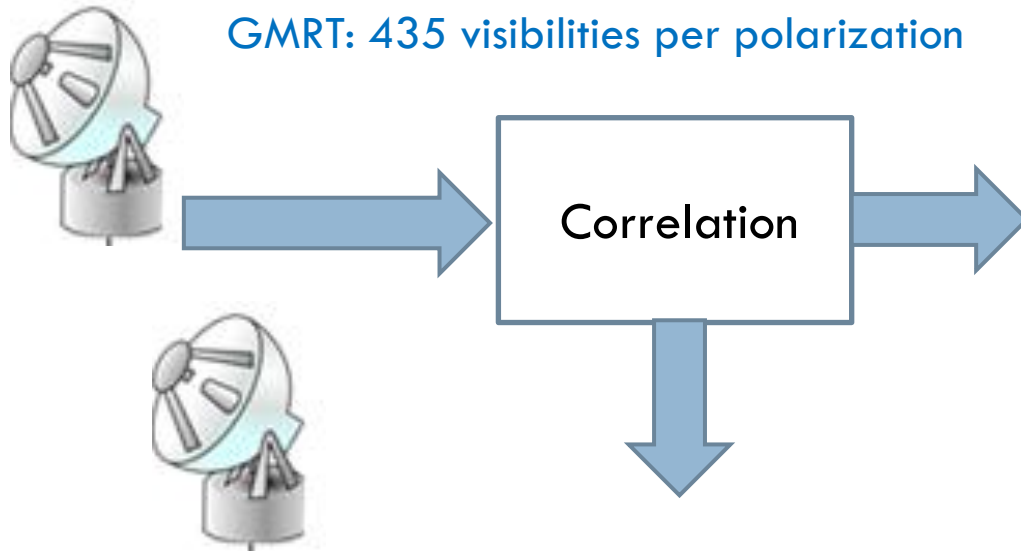


- Averaging leads to reduction in noise variance.
- Signal-to-Noise ratio improves by a factor of $N^{0.5}$
- Deterministic signal adds coherently while noise adds incoherently
- Increases the ability to detect a weak signal buried in noise !

$$\sqrt{B * \tau}$$

Reduces uncertainty in the measurement parameter

Correlation: Typical Output



W01-C02 baseline cross-correlation amplitude (normalized) and phase for a single spectral channel (frequency) as a function of time

Beamformer

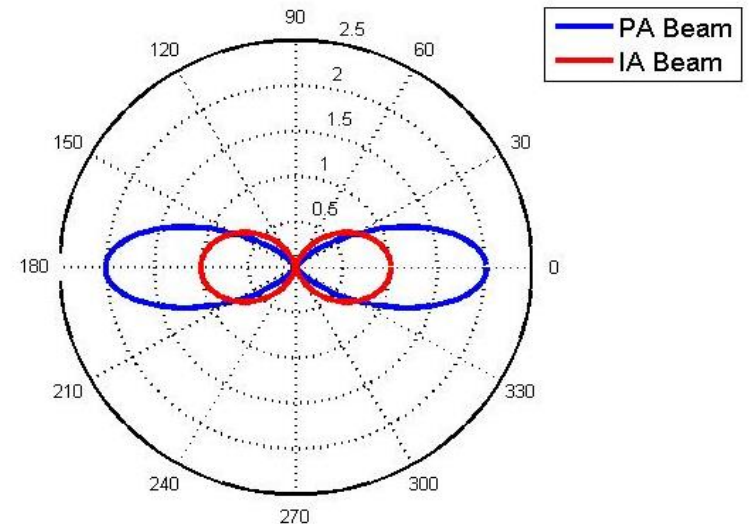
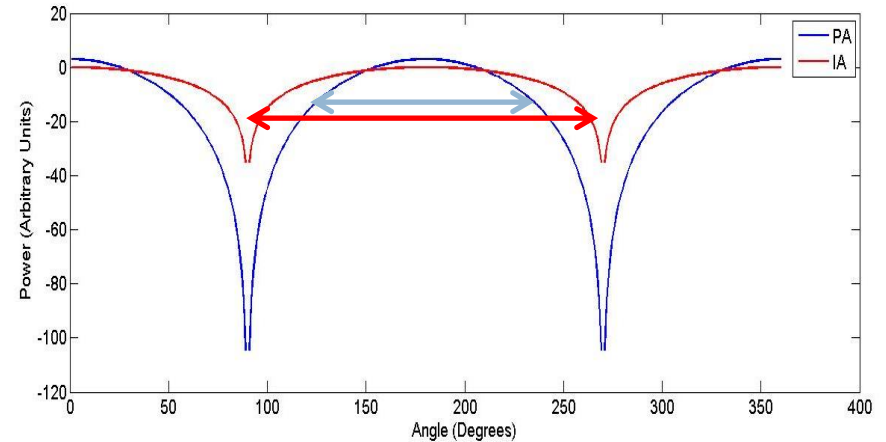
- Power from individual antennas is added to form the incoherent beam (scalar addition)

$$B_i = \sum_{i=0}^N (V_1^2 + V_2^2 + \dots + V_N^2)$$

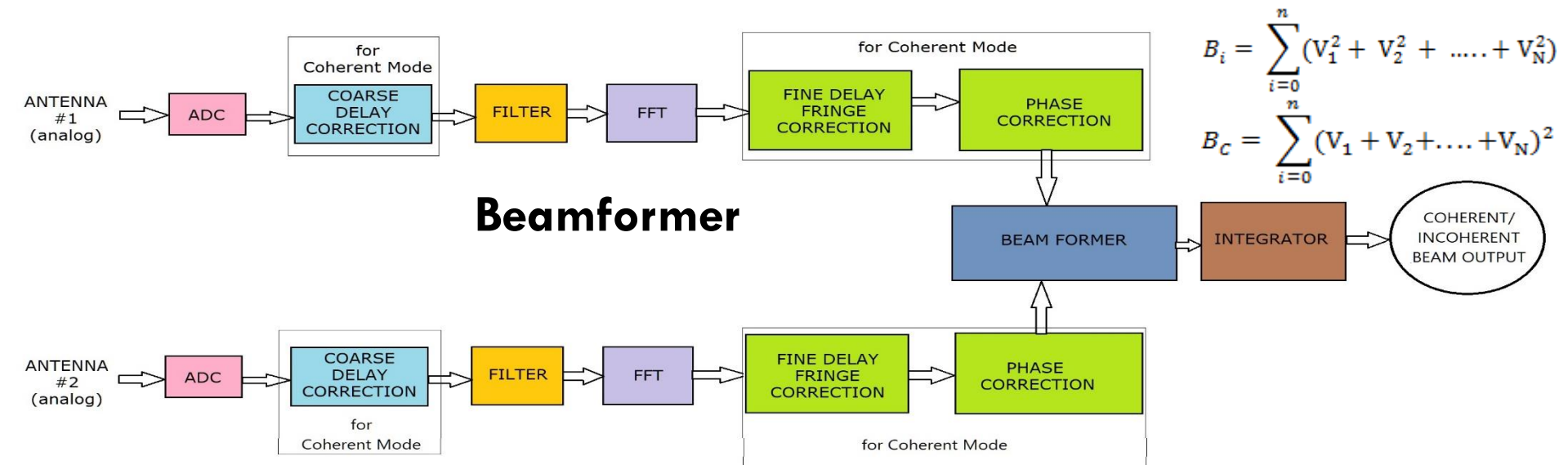
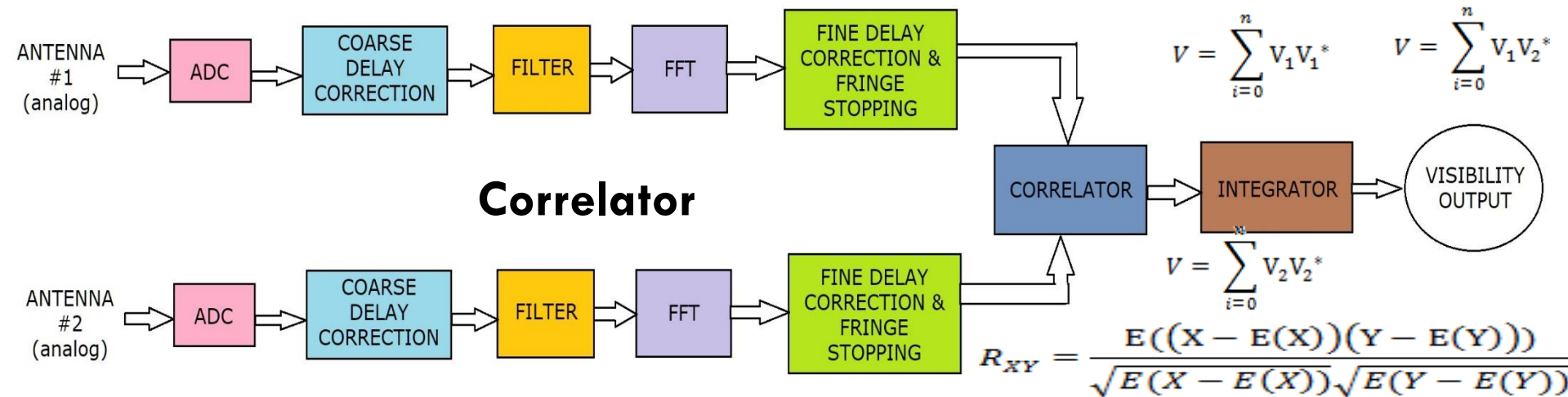
- Voltages from individual antennas are added to form the coherent beam.

$$B_c = \sum_{i=0}^N (V_1 + V_2 + \dots + V_N)^2$$

Phase is important !

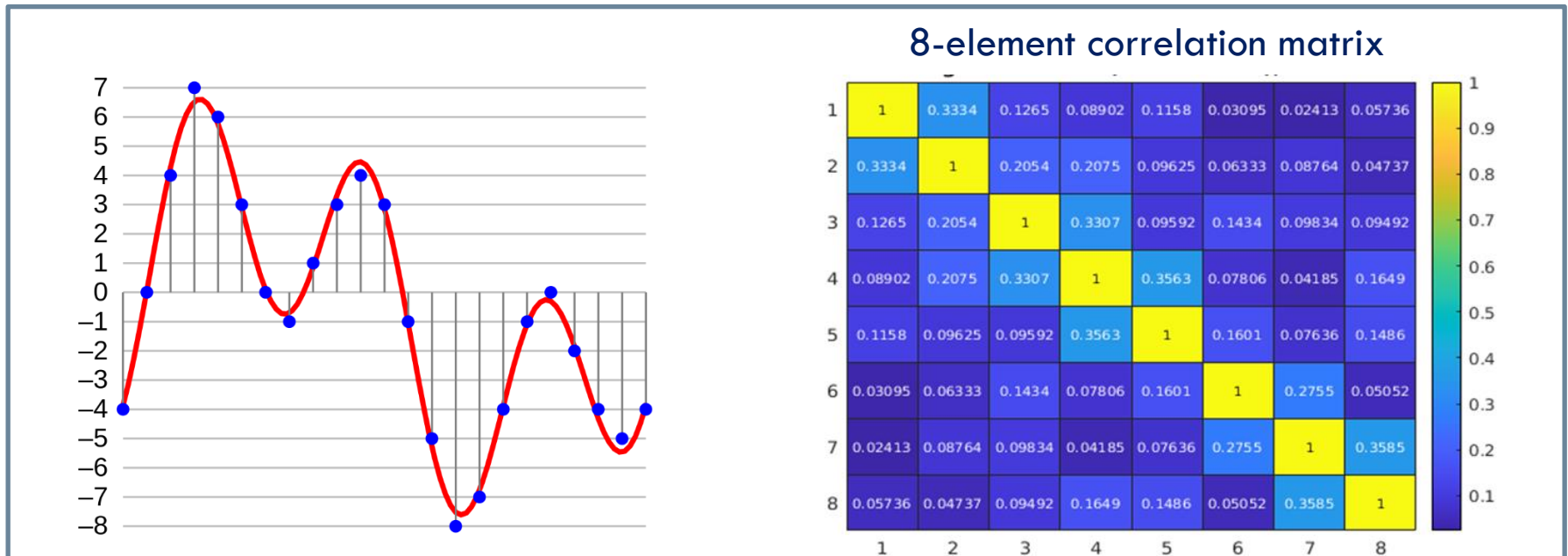


Digital Processing: Block Diagram



Major Challenges for Real-time Processing

- Sampling frequency: 2x the signal bandwidth
 - ▣ Faster processing
- Algorithmic complexity grows as N^2
 - ▣ Parallel Computing



Modern Correlators: Example

Modern correlators consist of signal processing component and networking component

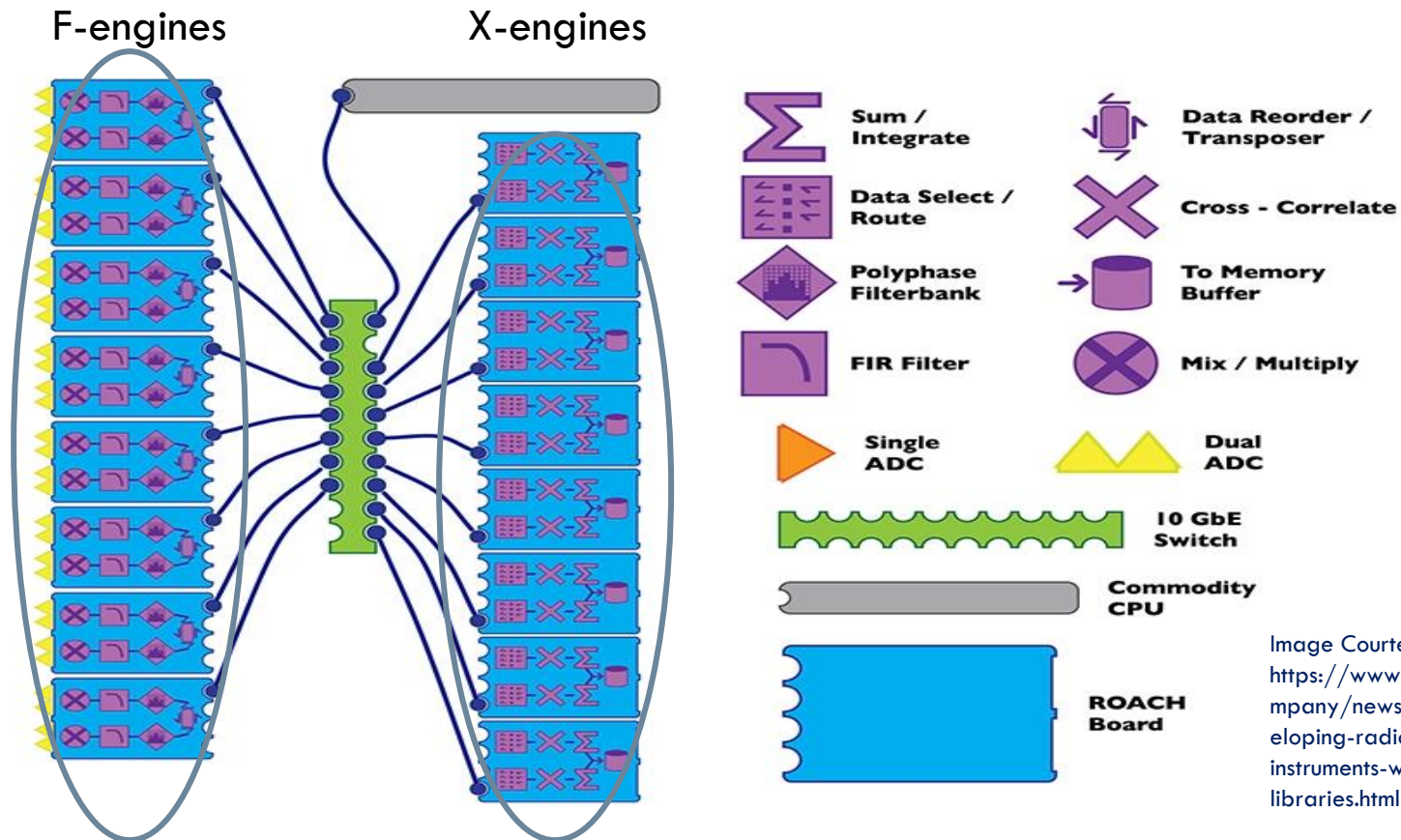


Image Courtesy:
<https://www.mathworks.com/company/newsletters/articles/developing-radio-astronomy-instruments-with-simulink-libraries.html>

Commonly used method is to carry out digitization, delay correction, FFT in F-engine and multiplication and accumulation in X-engine. High speed data connectivity is required between the F & X engines

uGMRT Correlators: Installation

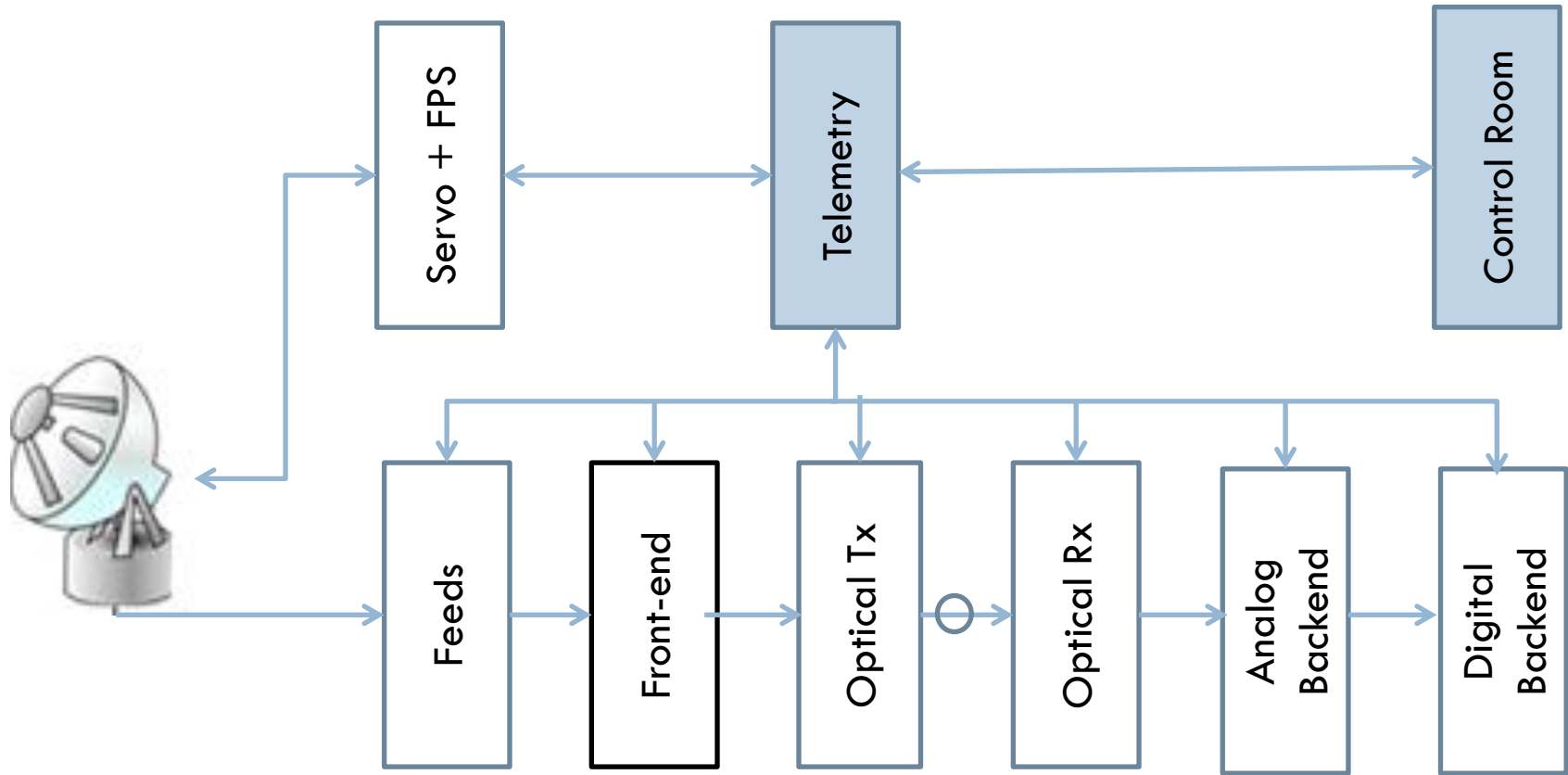


Image Courtesy: Digital Backend Group

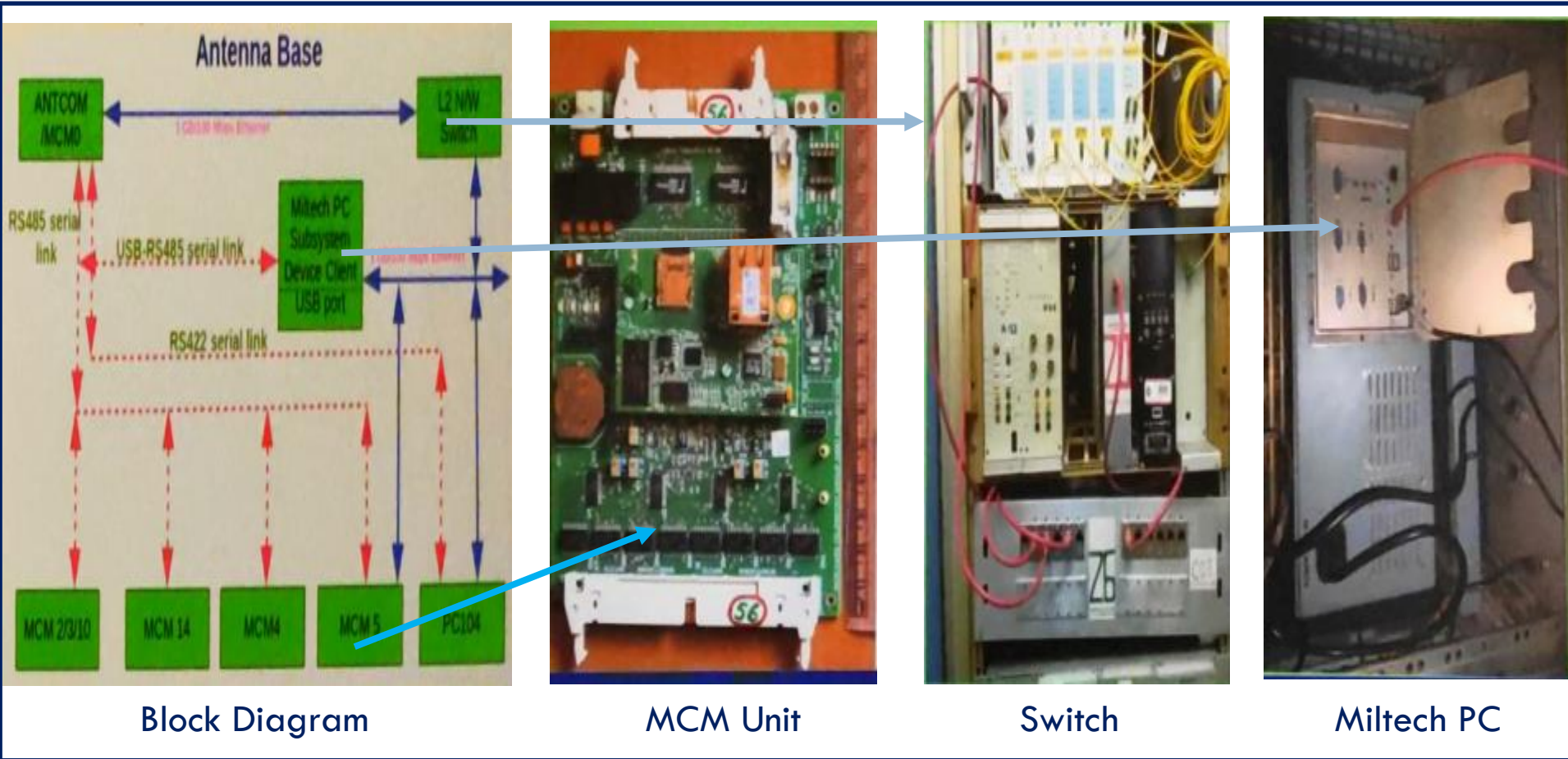


uGMRT correlator and beamformer : a combination of Field Programmable Gate Array (FPGA) and Graphics Processing Unit (GPU).
16-node cluster, computation of the order of ~ 10 TFlops. Power consumption: ~ 20 kW

GMRT Systems

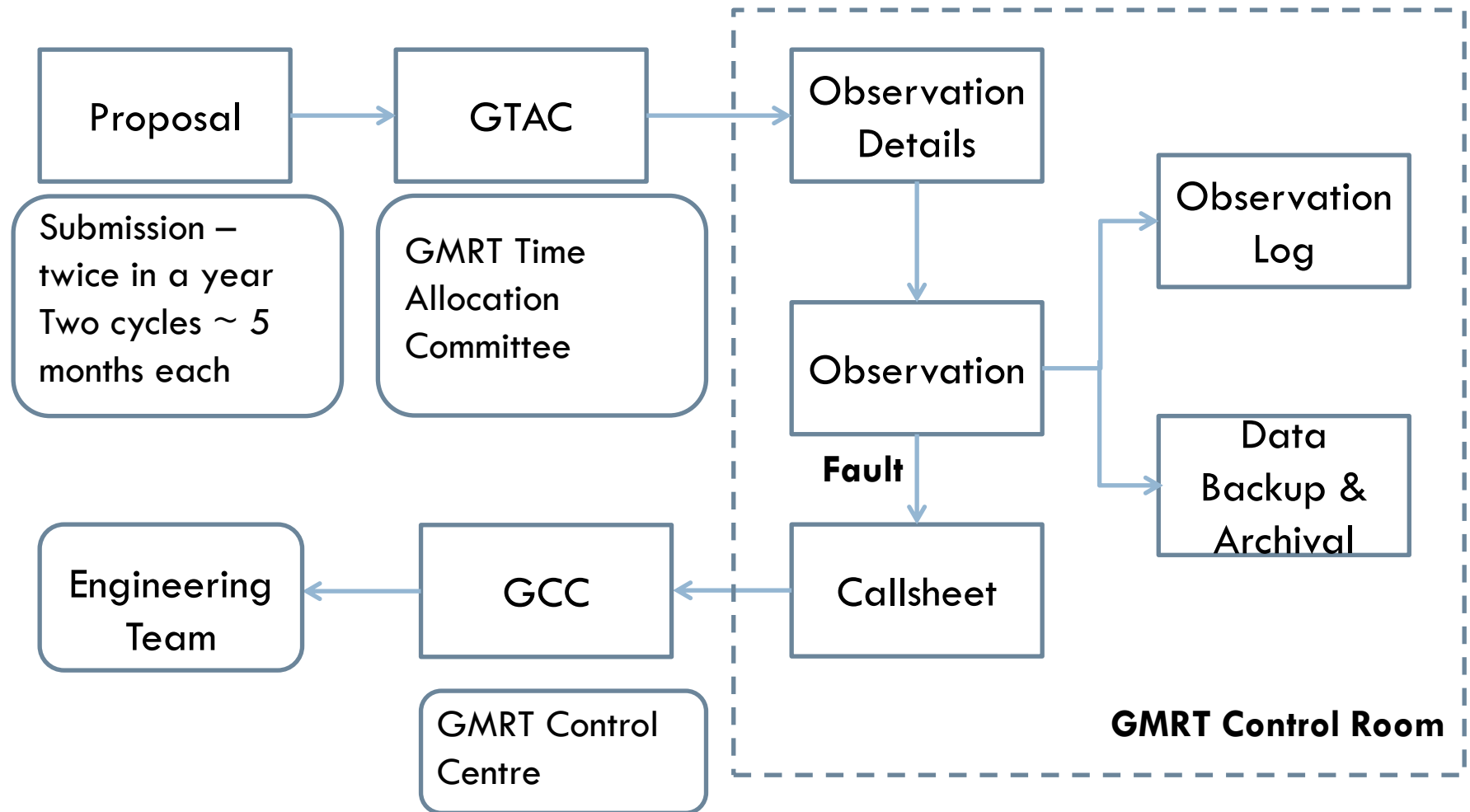


Telemetry

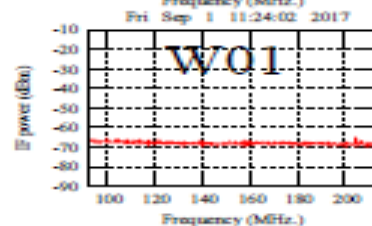
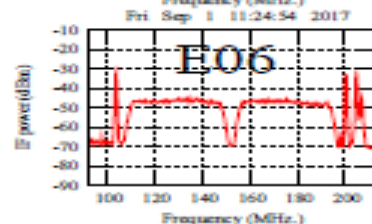
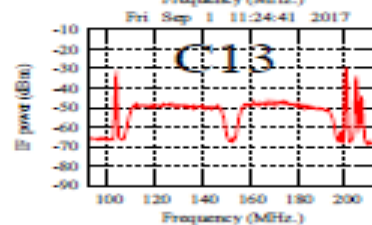
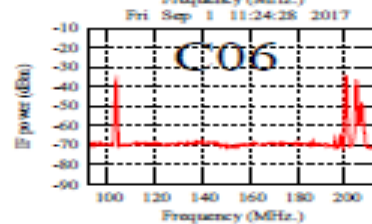
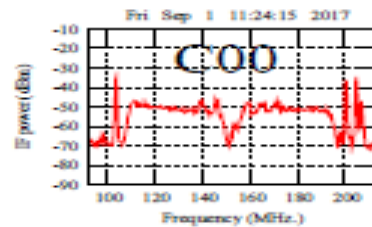


Control & monitoring between the control room and other subsystems of the antenna and receiver

Control Room



Diagnostic Tools



User Documents <http://gmrt.ncra.tifr.res.in/~astrosupp/>

GMRT Observer's Manual
 System Parameters and Current Status
 Polarisation observations with GMRT (V2)
 Dual band multi-pointing with GMRT (V2)
 GMRT Software Backend Documents
 uGMRT upgrade status

Before Observations

GTAC Schedule [NCRA] [GMRT]
 White Slot Request[NCRA] [GMRT]
 Command file Creator and Observations Setup
 Line Observations Frequency Setup (tune)
 Source(s) Rise and Set Time
 Observing Time Calculator
 VLA Calibrator Search
 Dual band multi-pointing coordinates
 Online Archive (GOA)

During Observations

Antenna Tracking Status
 Corr band shapes and Project State *
 Gain-amplitude and Phase (rantsol)
 Visibility - amplitude and phase (xtract)
 Antenna Wind Status
 Satellite passes

After Observations

LTA to FITS conversion:
 AIPS help:
 RFI Plots:
 GDDP summary:

Antenna Systems

Ondisplay Antenna Tracking Status
 Ondisplay History
 Feed position status
 Pointing Offsets
 Wind Monitoring Station
 Antenna Wind Status
 Temperature Status
 Servo data
 Electrical Power Status

Analog Backend

GAB Status
 IF Band Shapes and Deflection data
 Gray Plots

Digital Backend

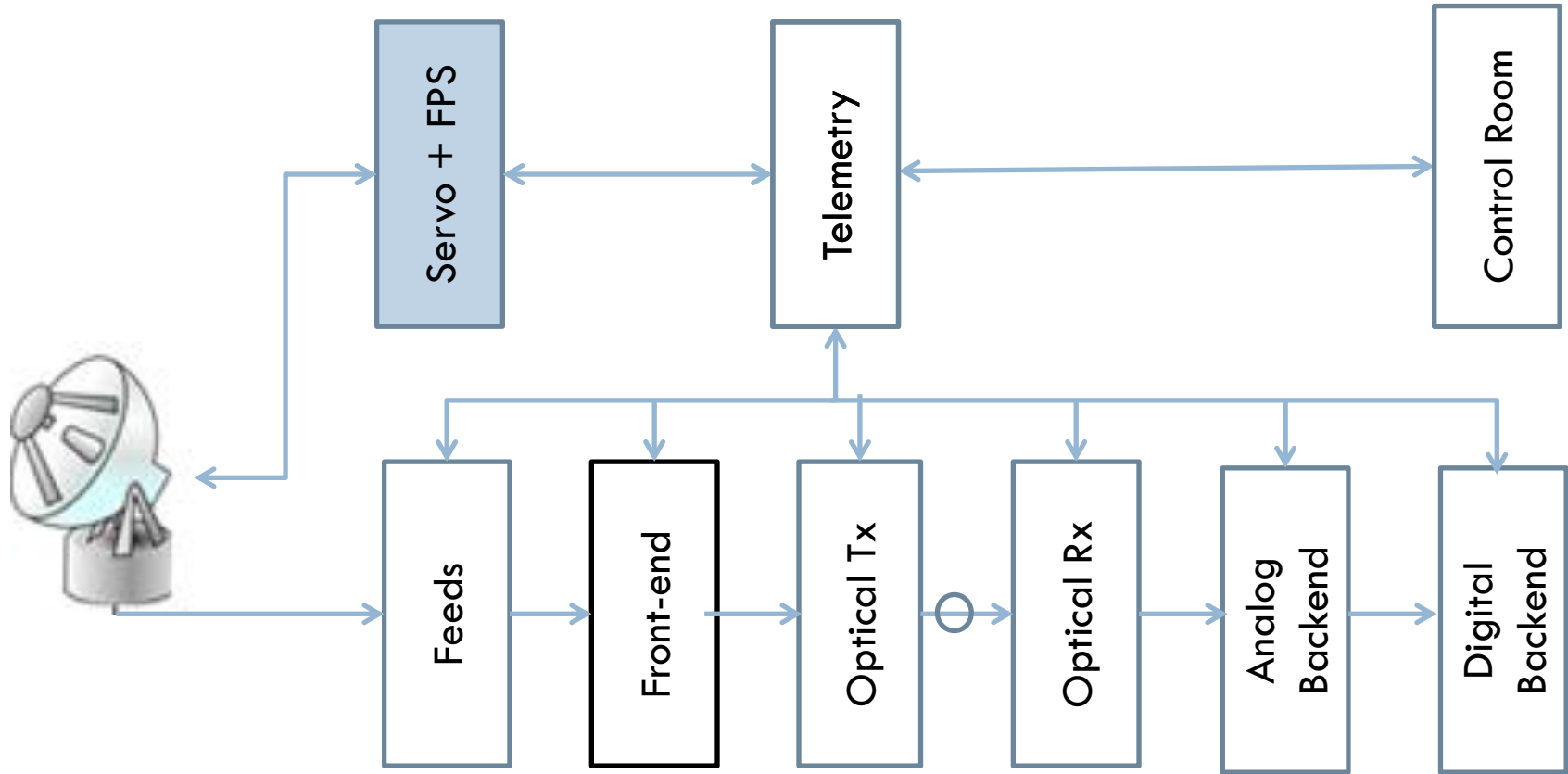
Corr band shapes and Project State
 Fringe Status (rantsol amp-gain)
 Gain-amplitude and Phase (rantsol)
 Visibility - amplitude and phase (xtract)
 Correlator Room Temperature

Gmon Tools, Logs

Test Results, Callsheets and Schedules

Useful scripts
 Recent Callsheets
 GMRT Upgrade Status
 Results of Weekly PMQC tests
 GDDP, RFI status gray plots
 Antenna Beam Width Plots
 Schedules and white slot request

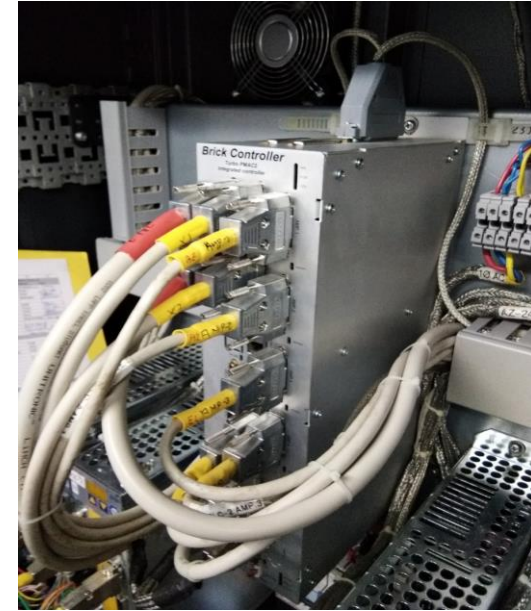
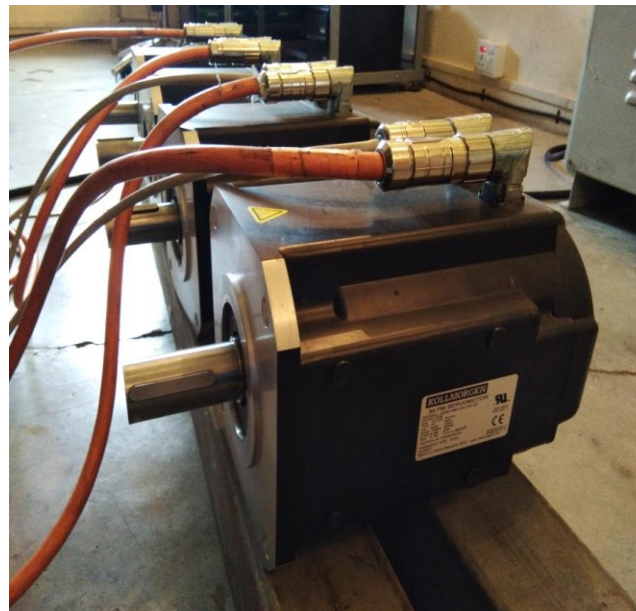
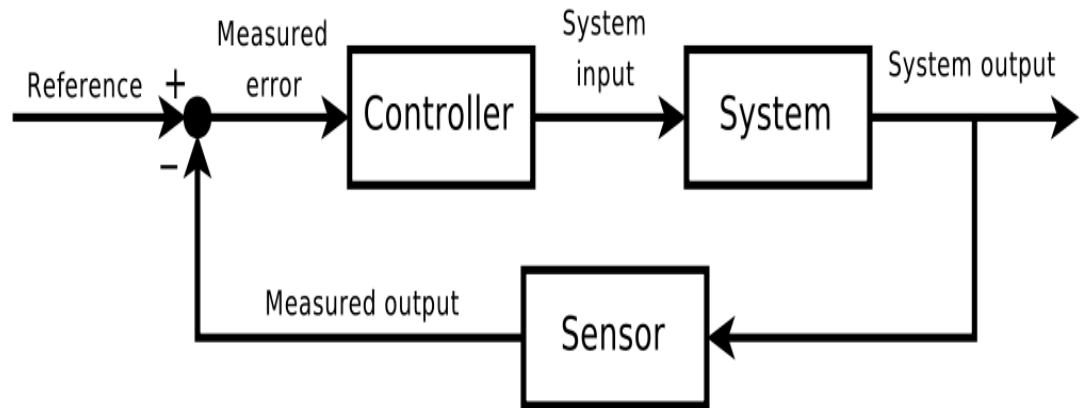
GMRT Systems



Servo System

- Points the antennas to any part of the sky and tracks a source
- $\pm 270^\circ$ movement around azimuth axis and 17 to 110° above horizon about elevation axis
- Slew speed of $30^\circ / \text{min}$ in Az axis and $20^\circ / \text{min}$ in El axis
- RMS tracking and Pointing accuracy: 1 arcmin at 20 kmph wind speed
- Feed rotation and positioning system

Closed-loop control system



Maintaining and Upkeeping



Image Courtesy: GMRT Archives

High Lift Platform for servicing front-end amplifiers, electronics and structural maintenance

Need a minimum number of antennas (26) for a fruitful scientific observation

Day to day problem solving and long-term maintenance!

Painting: Very important for maintaining the health of the mechanical structure
Takes ~3 months to paint one GMRT dish !



Image Courtesy: David Green

Challenge: Radio Frequency Interference

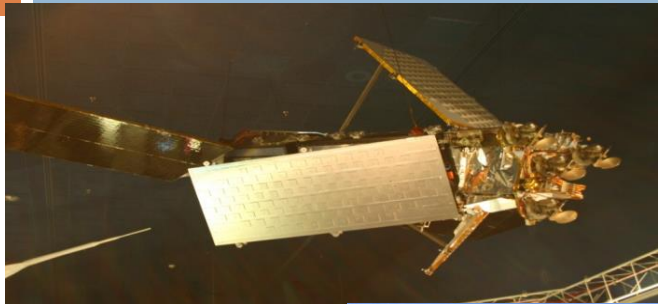
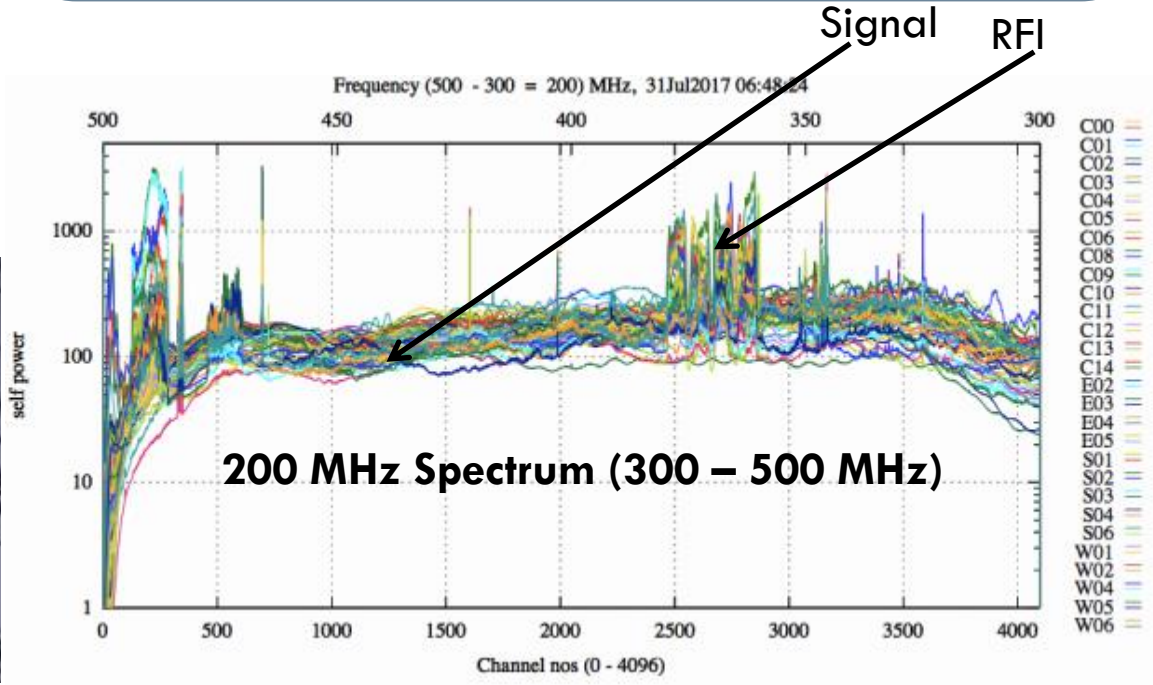
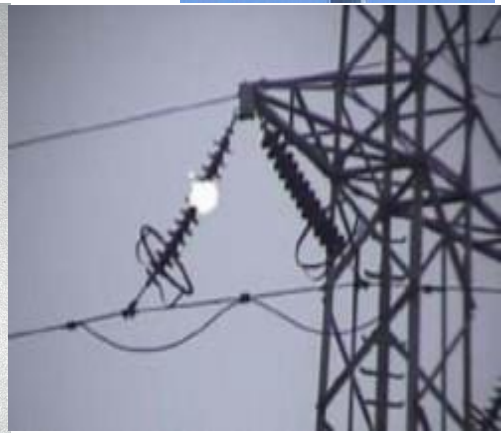


Image Courtesy: Wikipedia



- GMRT is a passive service receiver
- Due to large bandwidth and sensitive receiver systems, it is vulnerable to interference generated by various terrestrial and extra-terrestrial sources
- Radio Quiet zone around the array
- Located in a valley – mountains provide RFI shielding from Pune and Mumbai



RFI at GMRT: Coexistence

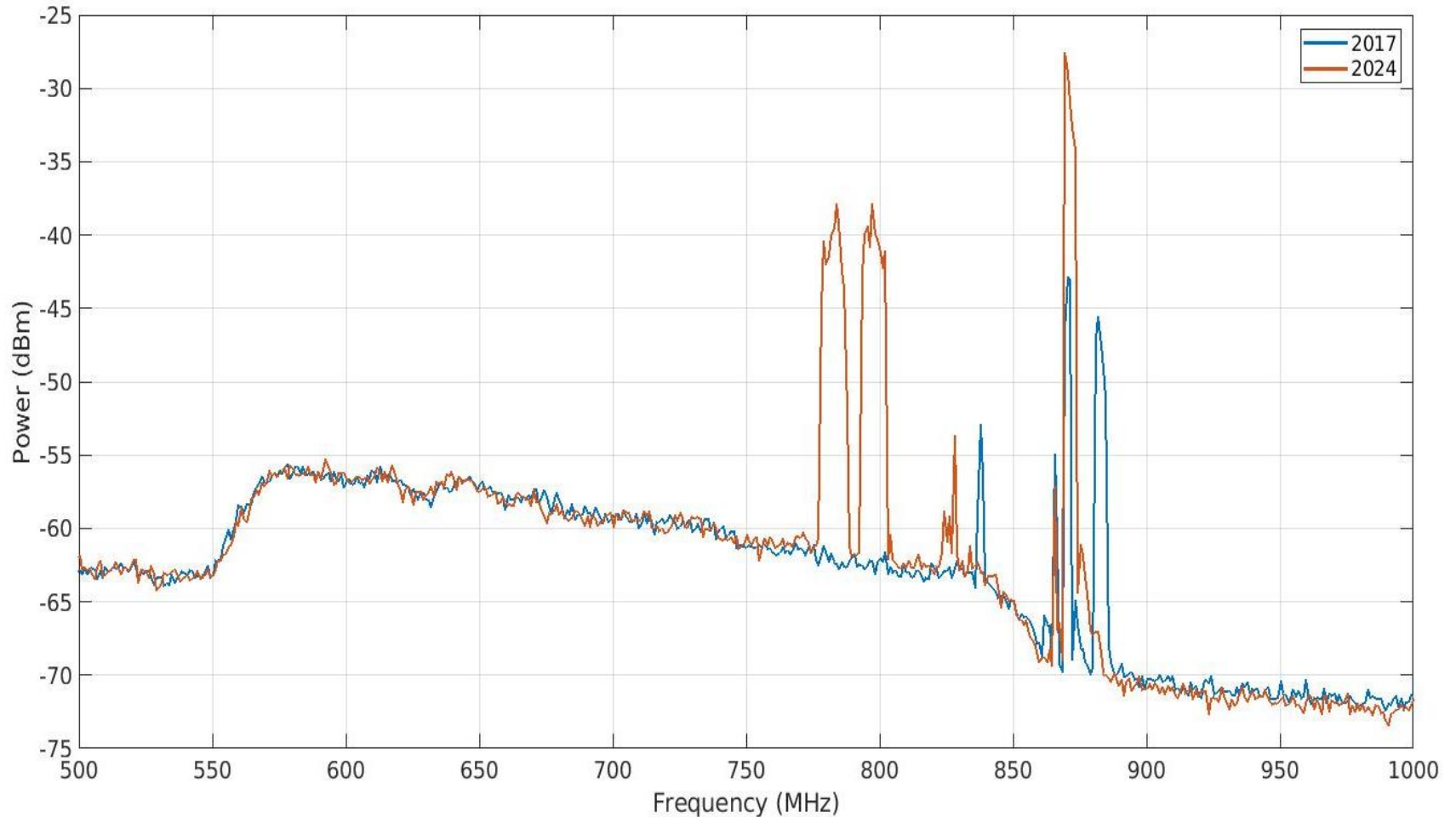


Coexisting with surrounding villages, farmlands and other industries – the potential sources of RFI

Image Courtesy: NCRA Archives

Increasing levels of RFI

Comparison between Band-4 in 2017 and 2024



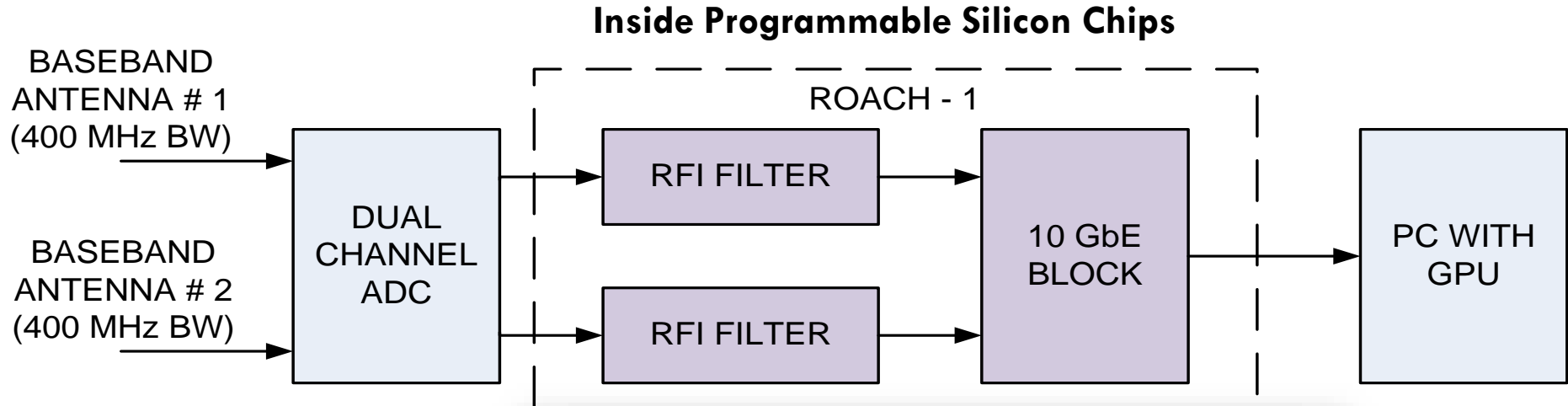
Mitigating Internal & External RFI



Image Courtesy: RFI + Electrical group

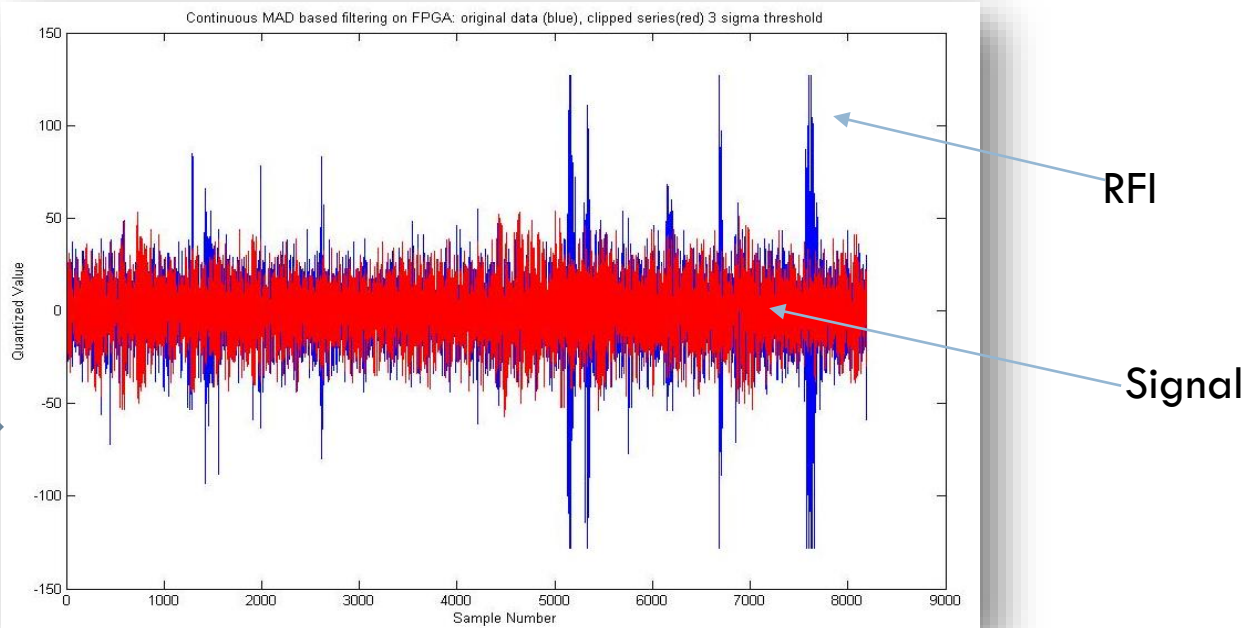


RFI Mitigation in digital system



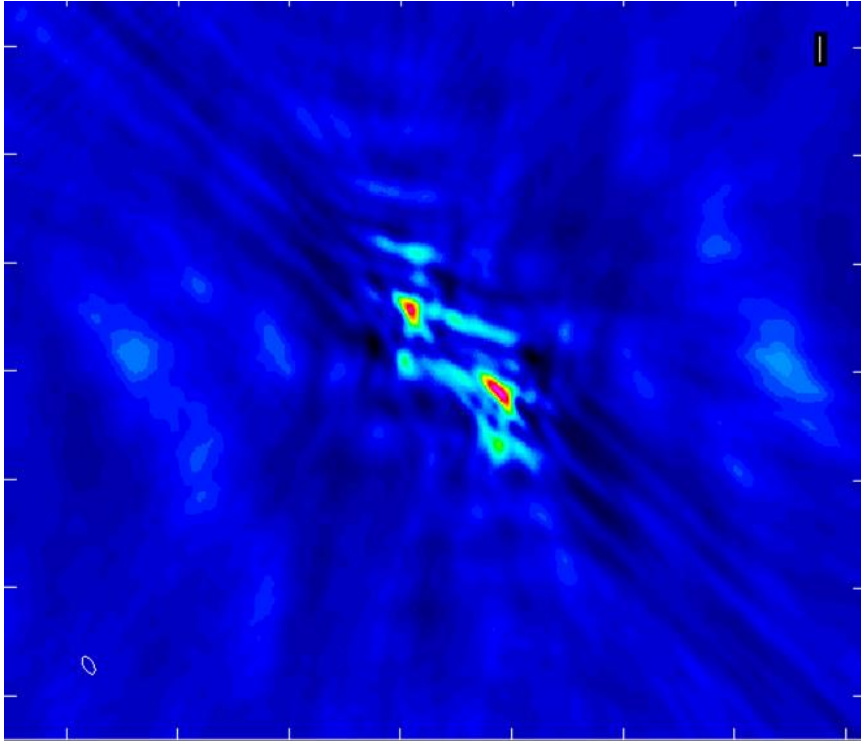
Strong power-line RFI detected through statistical techniques and filtered right after digitization (before processing)

GMRT 150 MHz time-series: blue (unfiltered), red (filtered)

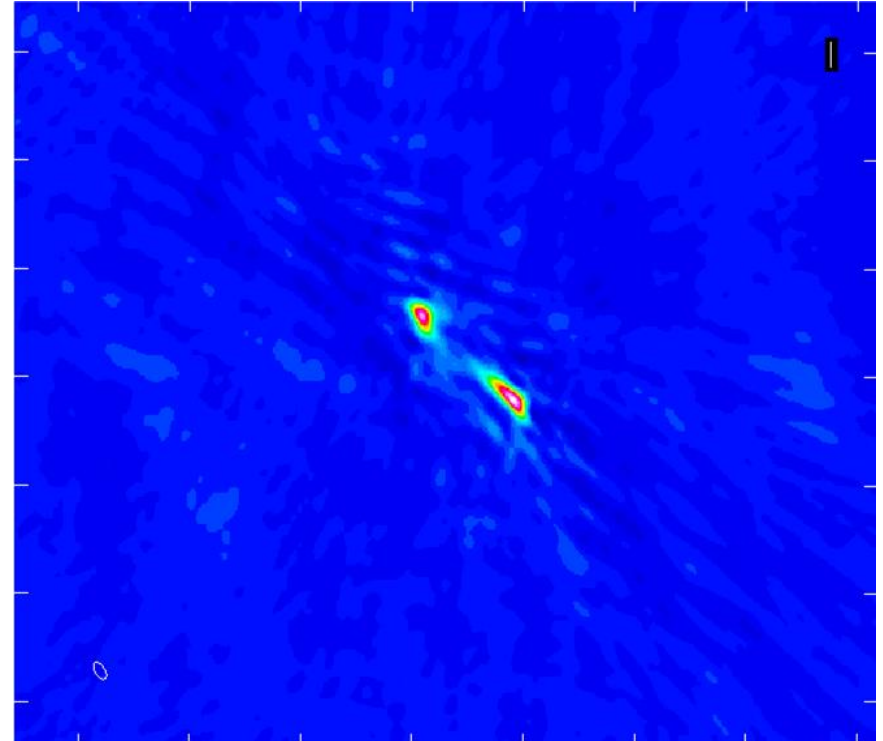


Imaging: Extended Source

Unfiltered



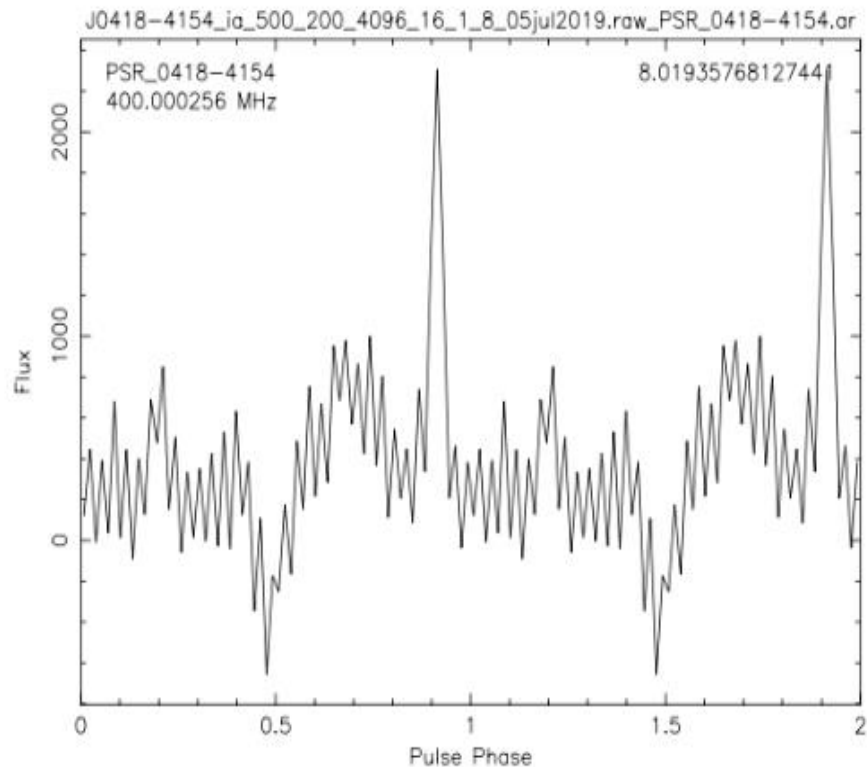
Filtered



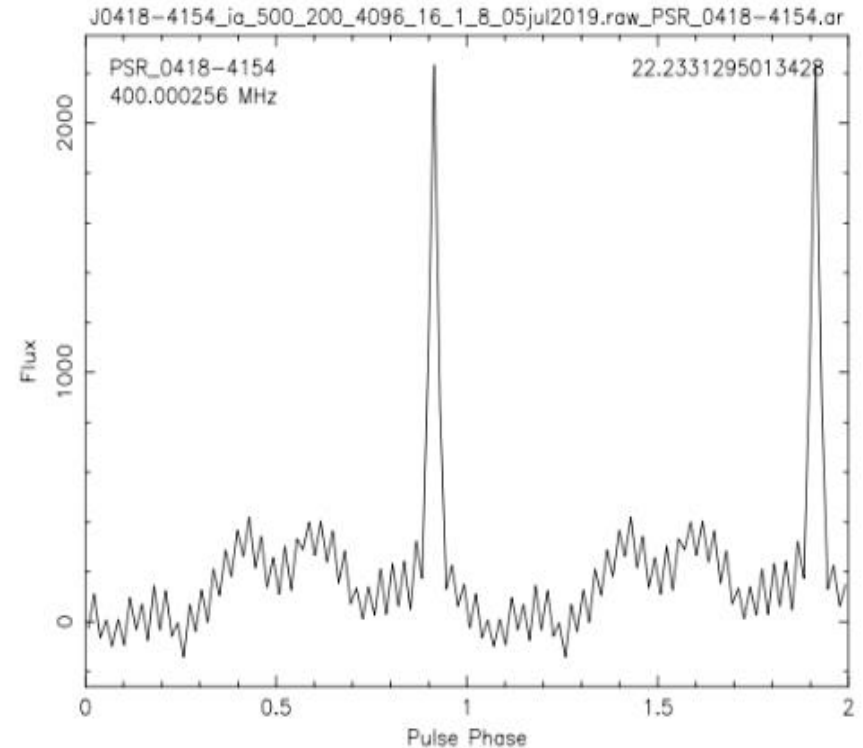
- uGMRT Band-4, 550-850 MHz , 200 MHz RF bandwidth, 2048 spectral channels
- Imaging for baselines < 1 kilolambda (~ 0.5 km)
- Noise RMS - 1.6 mJy/beam (Unfiltered) 0.52 mJy/beam (Filtered)
- Average Flagging: ~ 2.5 -3%

Time-domain Astronomy

Unfiltered



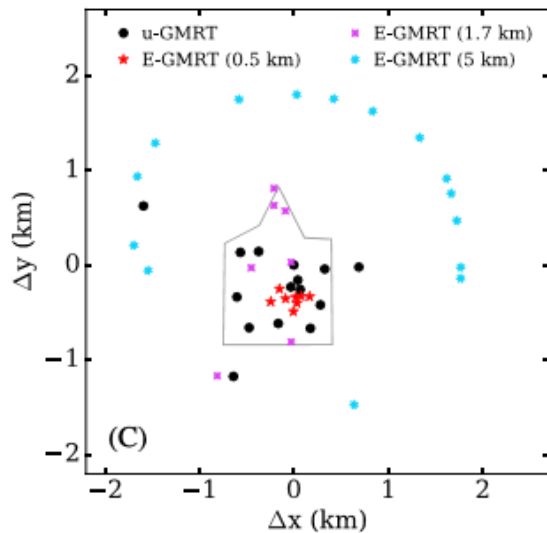
Filtered



- Pulsar (J0418-4154) profile comparison: Incoherent Array beam - 4096 spectral channels
327.68 μ s integration time.
- SNR improvement by factor of 3; Average Flagging \sim 3%

Expansions to the existing uGMRT: eGMRT

Adding more antennas for
baselines < 5 km



Improved sensitivity

Increase in Field-of-View
(degrees²) depends on
number of independent
beams

The Expanded GMRT (eGMRT)

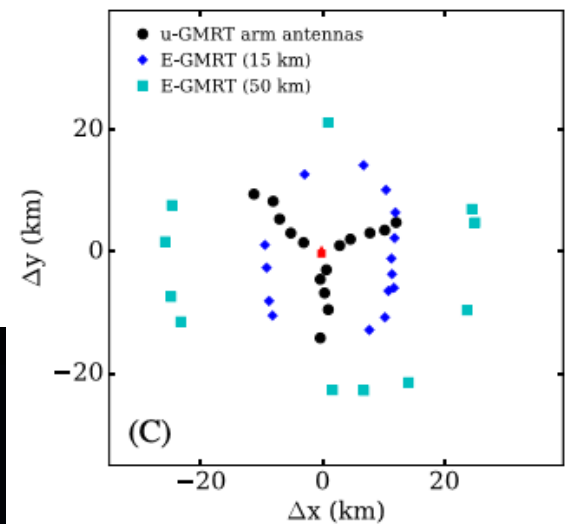
Adding focal plane array on
the GMRT antennas



Image Courtesy: K. Hariharan

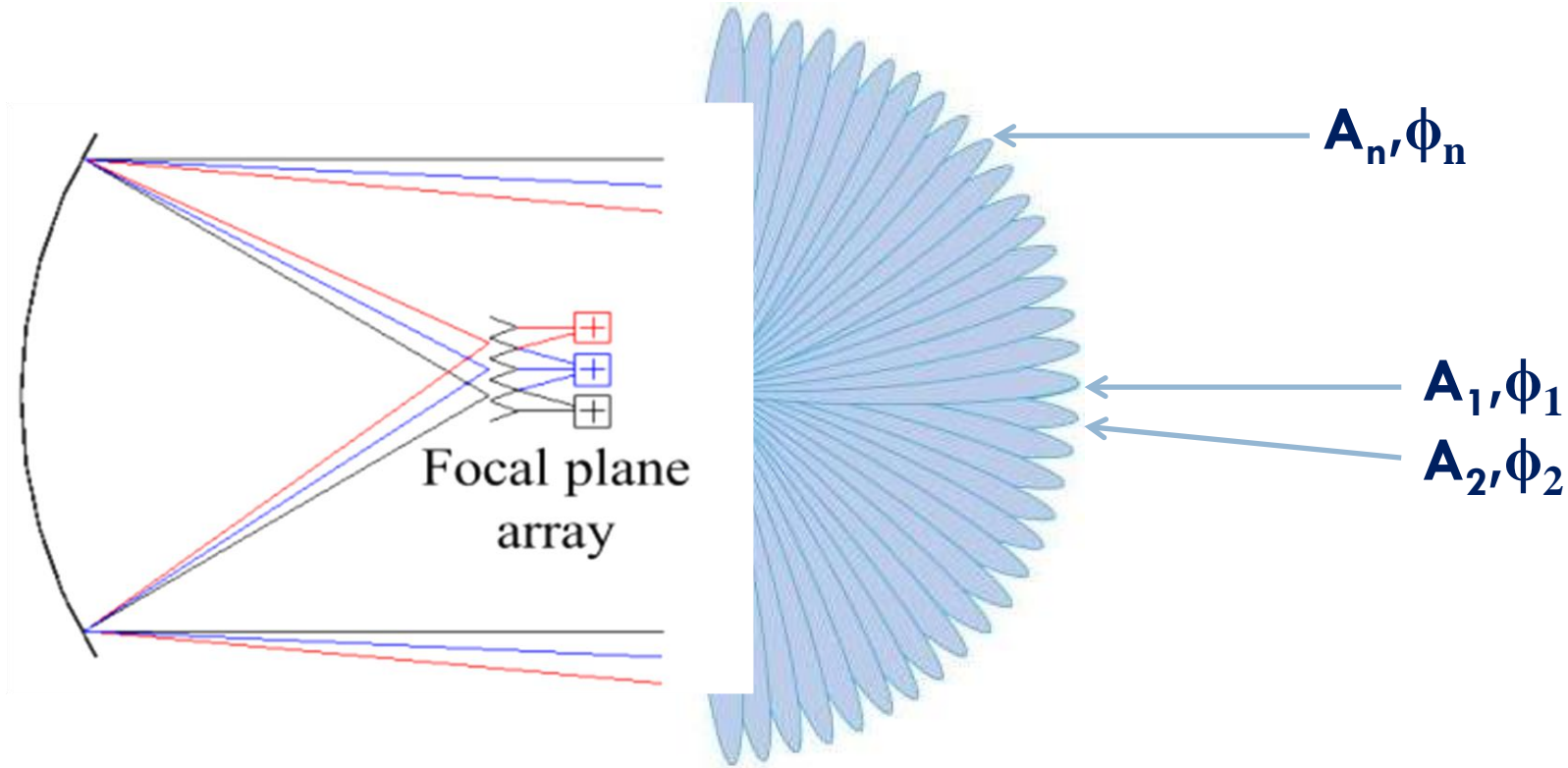
Increased Field-of-View

Adding more antennas for
baselines > 5 km and up to 50 km



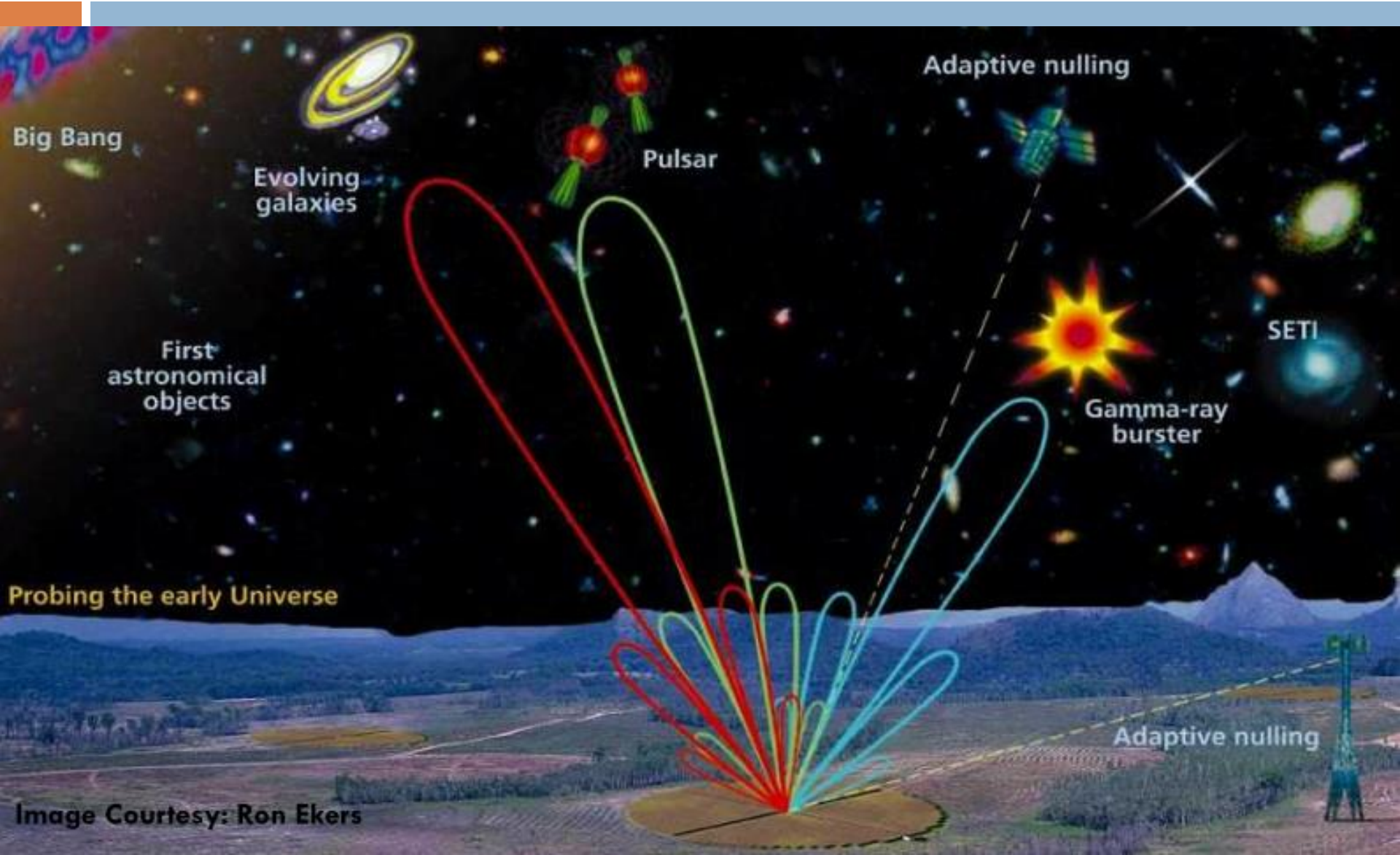
Improved angular resolution,
lower confusion limit

Focal Plane Array Beamforming

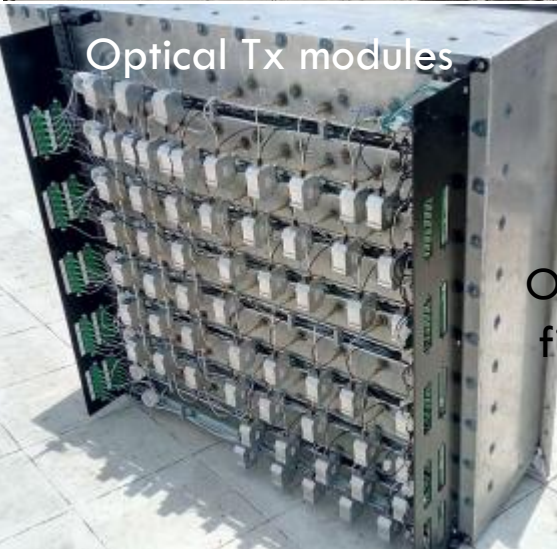


- N independent beams; increases the Field-of-View
- Changing the amplitude and phase of each element
- Combine signals from different elements

Forming multiple beams: Advantages



Experimental eGMRT beamformer



Optical fiber

Optical Rx and Analog signal processing modules



144-element L-band Beamformer (1.1 – 1.7 GHz)

32-element, 5-beam, FPGA-based digital beamformer



Acquisition and Control Computer

References

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3. http://gmrtscienceday.ncra.tifr.res.in/gsd2021/engineering_posters.php