

Wide Band and Wide Field Imaging - II



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Measurement Equation

The visibility measured by each baseline ij at one frequency and time

$$V_{ij}^{obs}(\nu, t) = M_{ij}(\nu, t) S_{ij}(\nu, t) \iiint M_{ij}^s(l, m, \nu, t) I(l, m, \nu, t) e^{2\pi i(ul + vm + w(n-1))} dl dm dn$$

Direction Independent Gains

- Eliminated during calibration

Primary Beams

- Power pattern varies with time, frequency and baseline

- **PBcor (post-deconvolution)**
- **A-Projection**
- **WB-A-Projection**
- **Mosaics**

Full Beam

Sky-brightness varies with frequency (time)

- All sources have spectral structure (some vary with time)

- **Cube Imaging**
- **Multi-Frequency Synthesis (MFS)**
- **Multi-Term-MFS (point source or multi-scale models)**

Wide-Band

W-Term

- Non-coplanar baselines

- Sky curvature

- **Faceting**
- **W-Projection**
- **3D FT**
- **W-Stacking**

Wide-Field

Wide Band + Full Beam/Wide-field

+ Mosaics

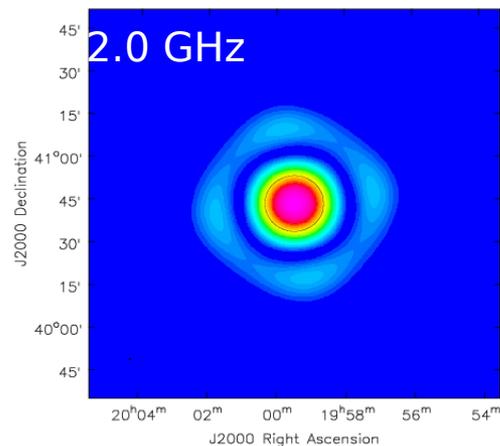
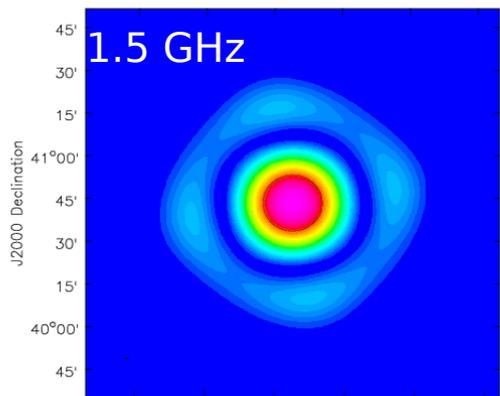
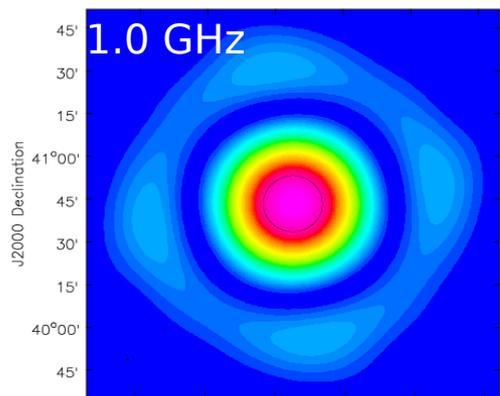
+ Single Dish

Example : Imaging the G55 supernova remnant

Imaging Framework

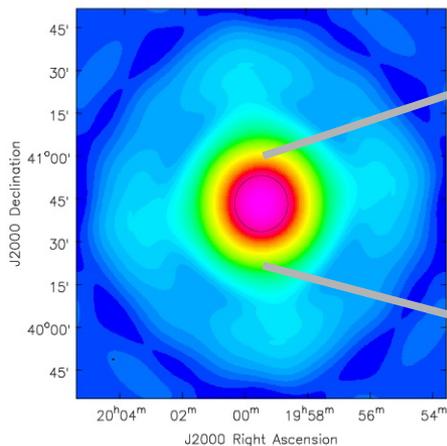
Wide-Band Wide-Field Imaging : Primary Beams

VLA PBs



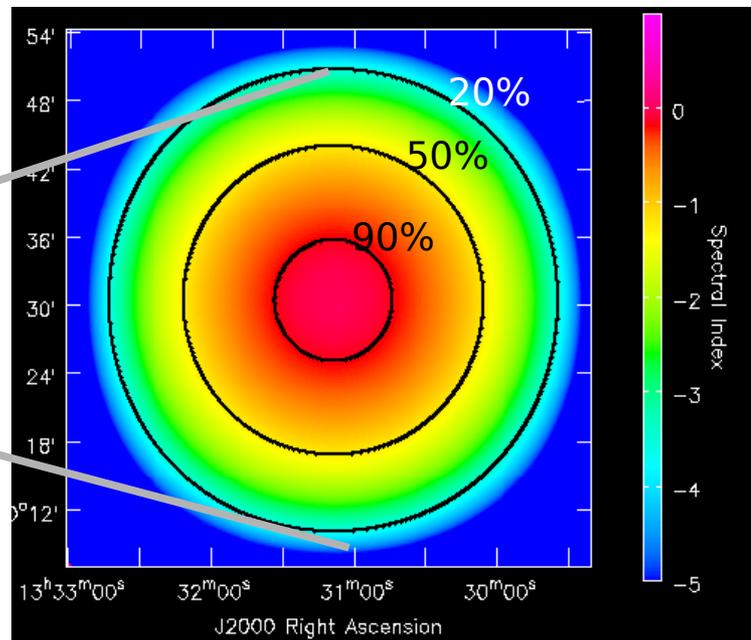
Primary beam scales (or changes) with frequency

Average Primary Beam



A very wide shelf of sensitivity outside the main lobe

Spectral Index of PB



For VLA L-Band (1-2 GHz)

- About -0.4 at the PB=0.8 (6 arcmin from the center)
- About -1.4 at the HPBW (15 arcmin from the center)

$$I_{wf,wb}^{obs} = \sum_{\nu} \left[\left(P_{\nu} \cdot I_{\nu}^{sky} \right) * PSF_{\nu} \right]$$

Wide-Band Primary Beam Correction

Cube Imaging

- Sky model represents $I(\nu)P(\nu)$
- Divide the output image at each frequency by $P(\nu)$

Multi-Term MFS + Wideband-PBcor

- Taylor coefficients represent $I(\nu)P(\nu)$

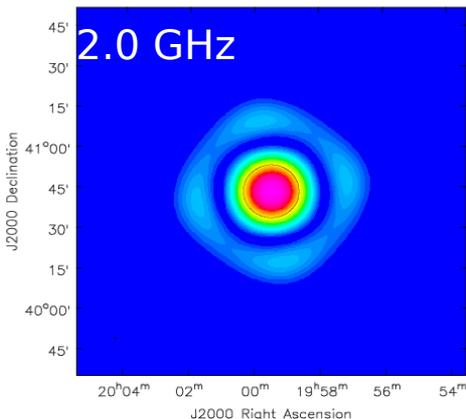
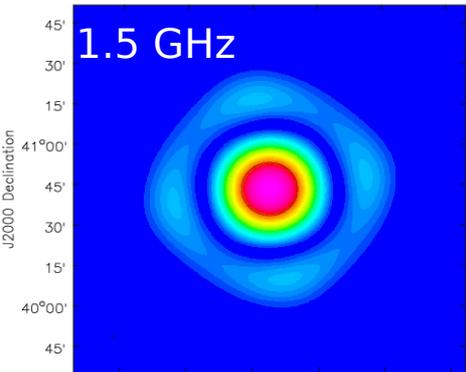
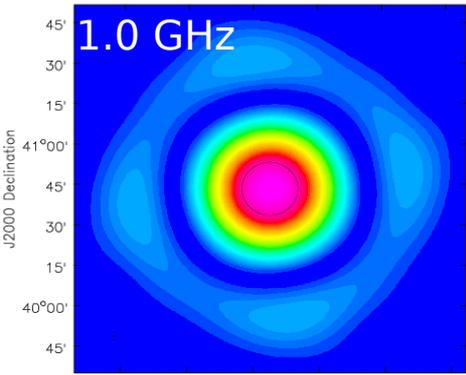
- Polynomial division by PB Taylor coefficients $\frac{(I_0^m, I_1^m, I_2^m, \dots)}{(P_0, P_1, P_2, \dots)} = (I_0^{sky}, I_1^{sky}, I_2^{sky}, \dots)$

Wideband A-Projection

- Remove $P(\nu)$ during gridding (before model fitting)

$$A_{\nu}^{-1} \approx \frac{A_{\nu_c}^T}{A_{\nu_c}^T * A_{\nu}} \quad \text{where} \quad P_{\nu} \cdot P_{\nu_c} \approx P_{\nu_{mid}}^2$$

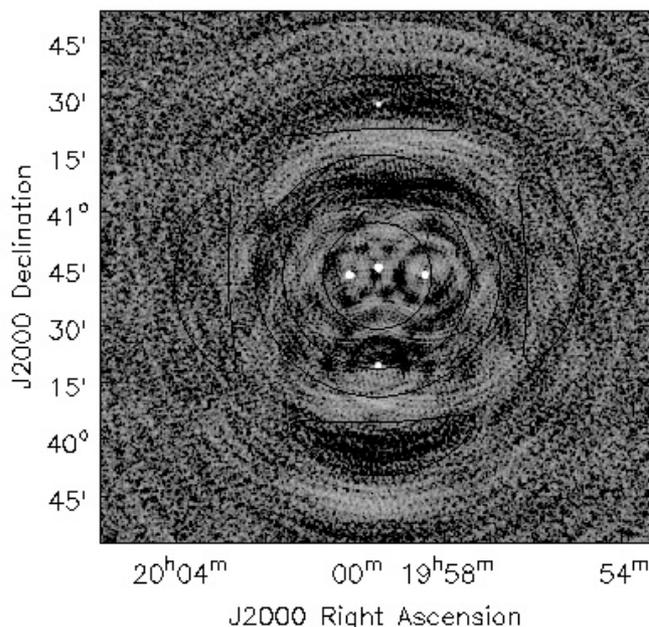
- Output spectral index image represents only the sky



Wide Band Full Beam imaging – Different algorithms

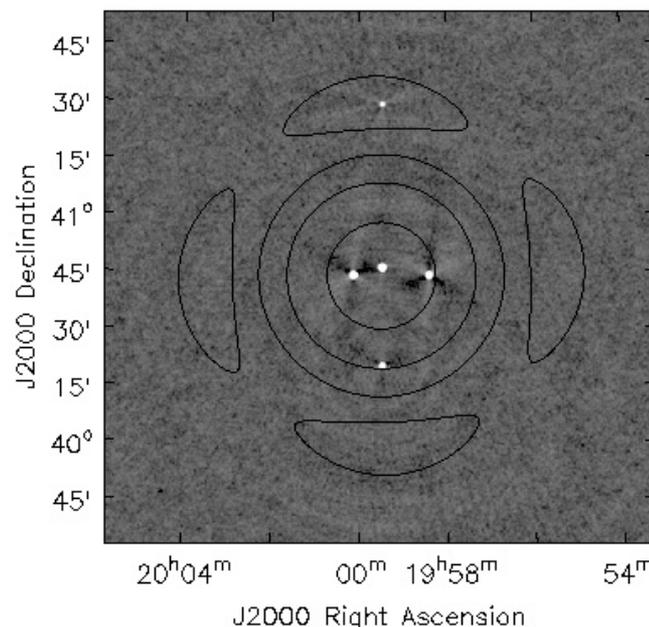
Basic
MFS
imaging

(no WB,WF
corrections)



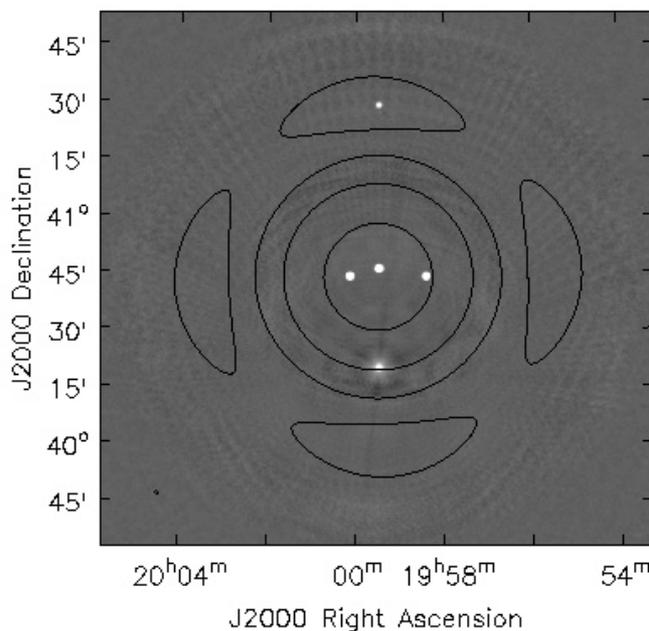
MT-MFS
wideband
imaging

(No WF
corrections,
PB freq
dependence
part of sky
model)



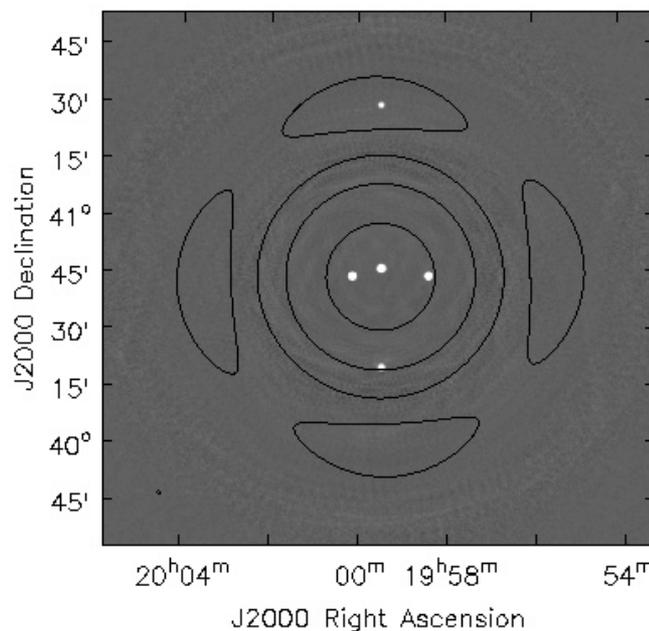
MT-MFS
wideband
imaging
+
A-Proj

(PB² freq
dependence
part of sky
model)



MT-MFS
wideband
imaging
+
WB-A-Proj

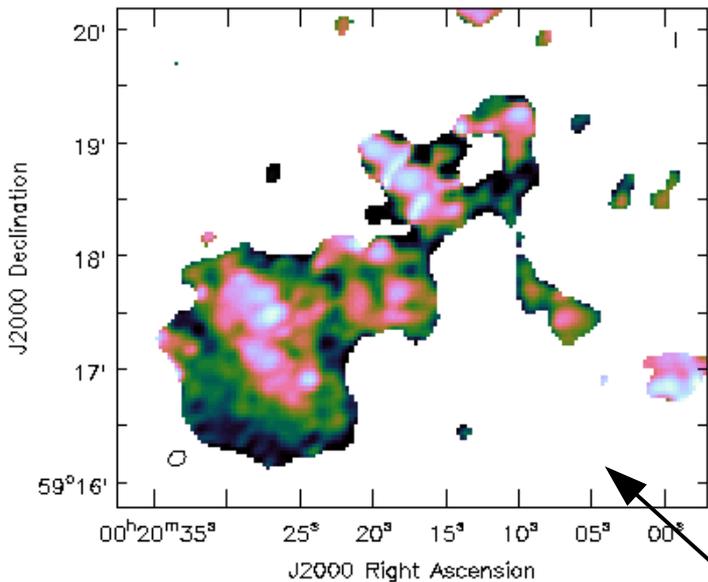
(PB freq
dependence
removed
during
gridding)



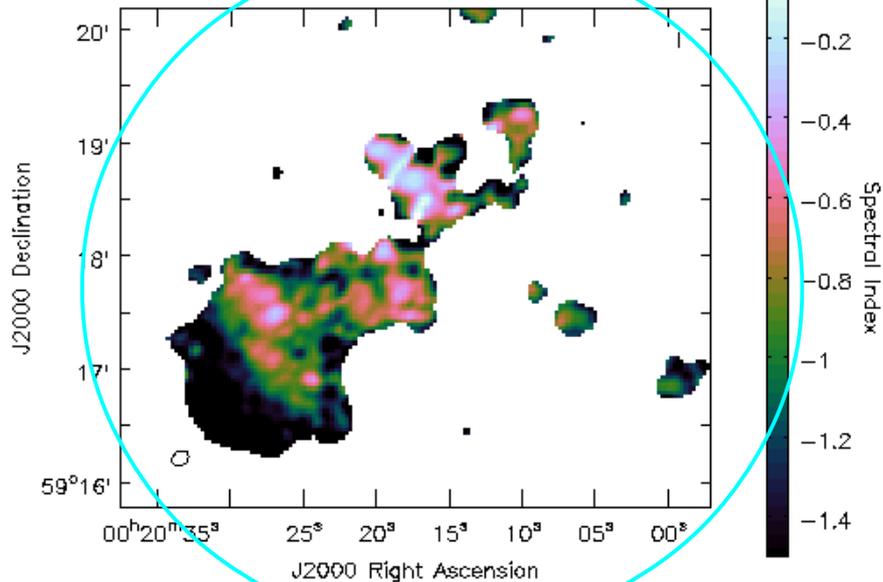
Wideband VLA imaging of IC10 Dwarf Galaxy

[Heesen et al, 2011]

After PB-correction



Before PB-correction



IC10 Dwarf Galaxy :

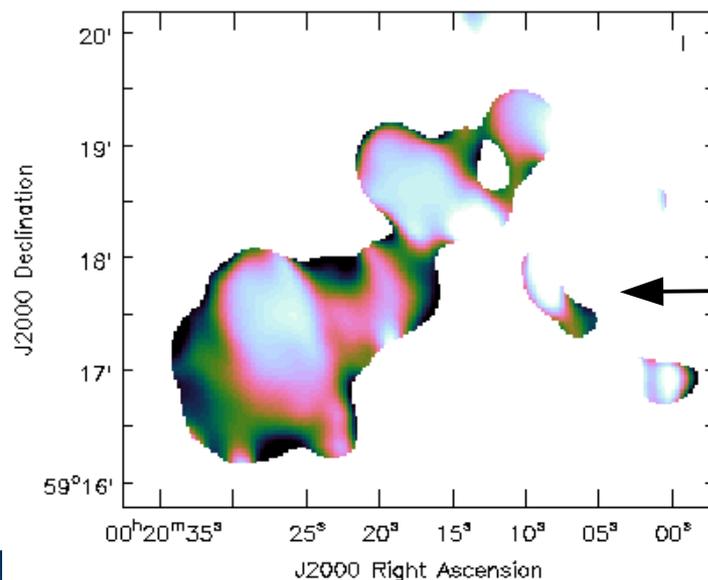
Spectral Index across C-Band.

Dynamic-range ~ 2000

50% of PB

MT-MFS : Wide-band PB-correction after multi-term multi-scale MFS.

Cube : Spectral-index map made by cube imaging, smoothing to lowest resolution, and spectral fitting.



Wide Band + Full Beam/Wide-field

+ Mosaics

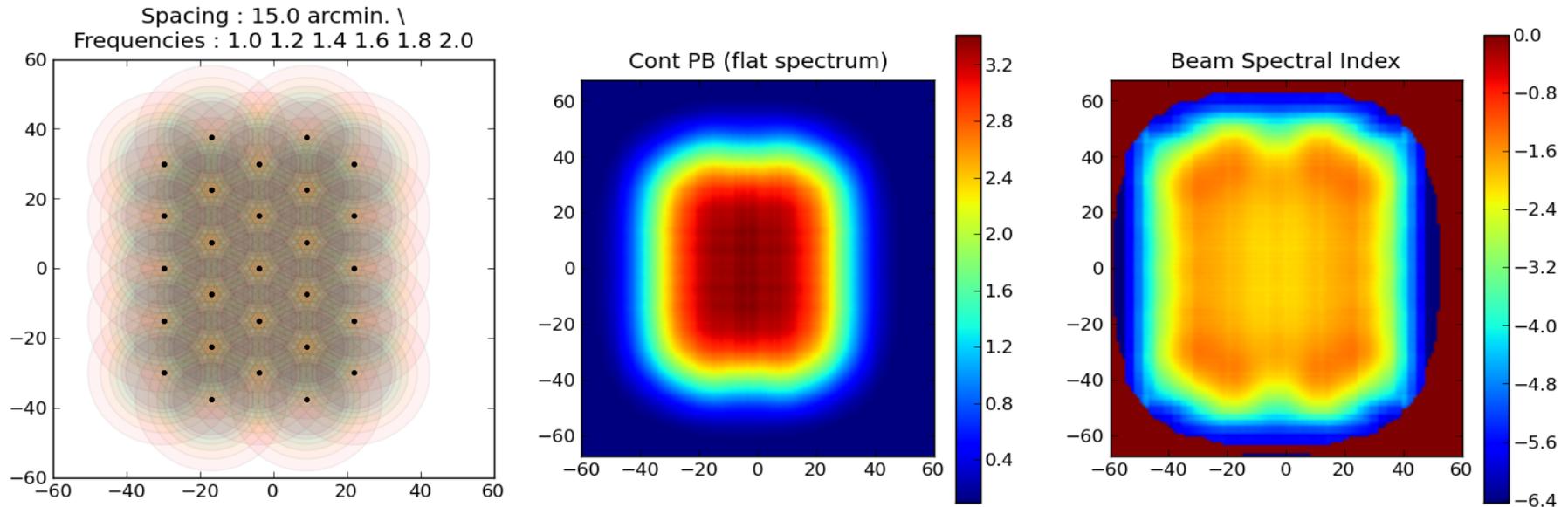
+ Single Dish

Example : Imaging the G55 supernova remnant

Imaging Framework

Wide-Band Mosaic Primary Beam

The mosaic primary beam has an artificial spectral index all over the FOV



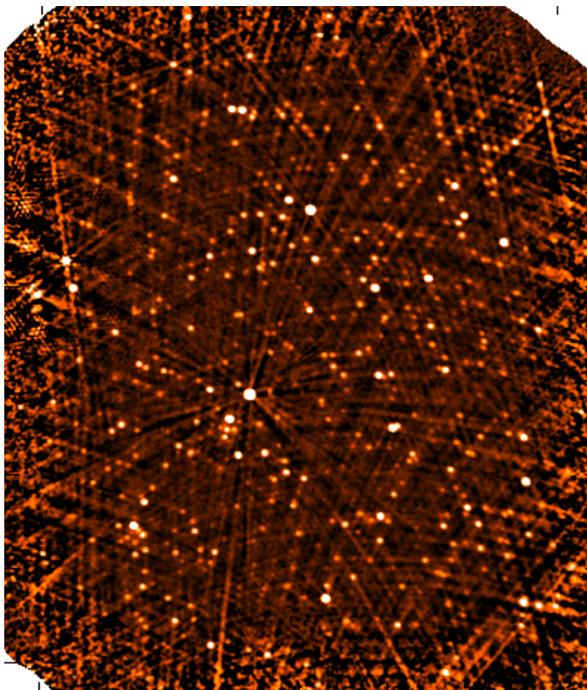
Algorithms :

- Deconvolve Pointings separately or together ([Stitched vs Joint Mosaic](#))
 - Impacts image fidelity, especially of common sources.
- Deconvolve Channels separately or together ([Cube vs MFS](#))
 - Impacts imaging fidelity and sensitivity, dynamic range
- Use A-Projection or not ([Accurate vs Approximate PB correction](#))
 - Impacts dynamic range and spectral index accuracy

Wideband Mosaic Imaging Accuracy [Rau et al, 2016]

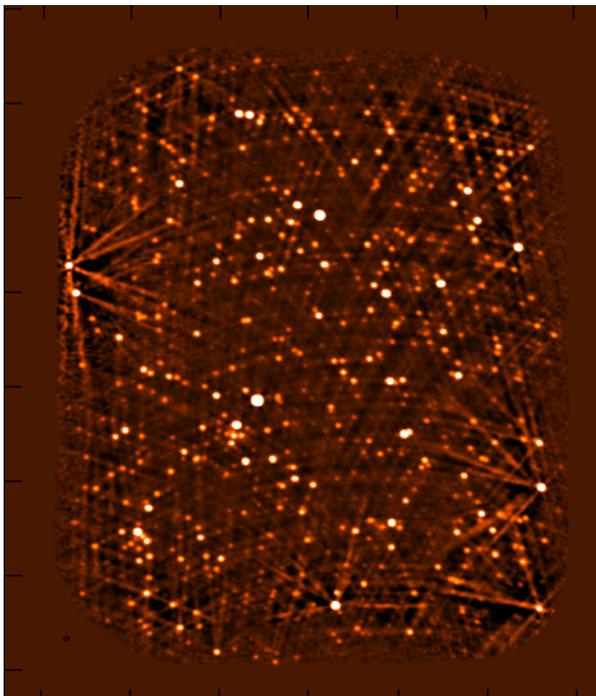
Cube + Joint Mosaic
(with static Primary Beams)

Dyn.Range = 5000:1



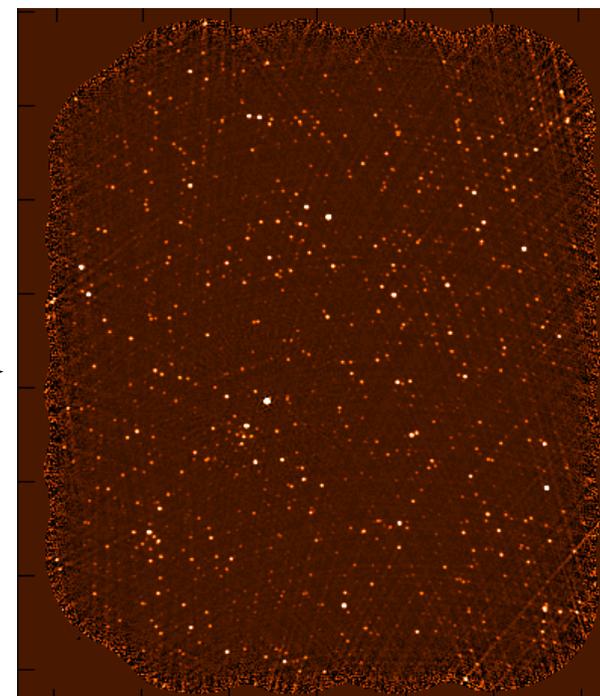
**Cube + A-Projection
+ Joint Mosaic**

Dyn.Range = 10000:1



**Wideband A-Proj +
Joint Mosaic + Multi-
term MFS**

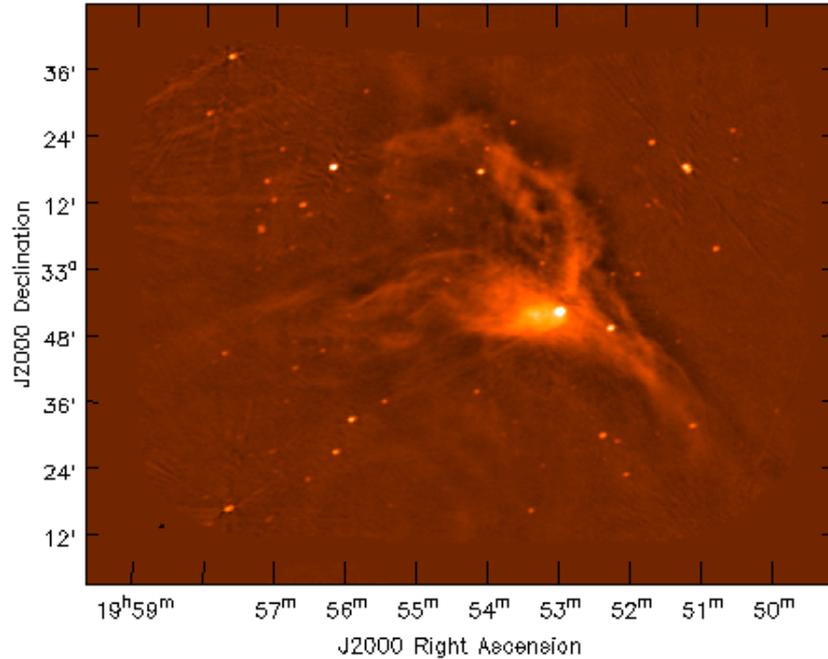
Dyn.Range = 40000:1



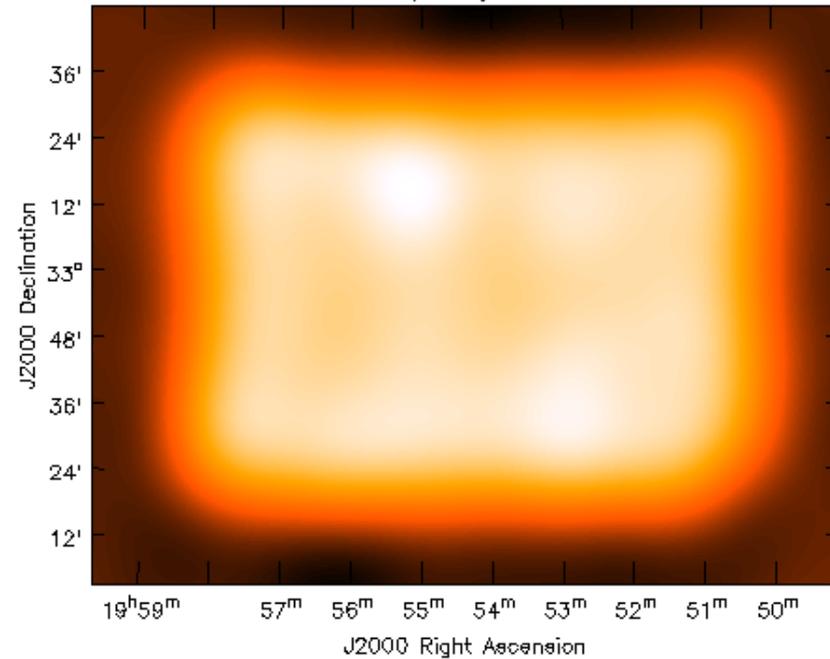
Method	I/I_{true}	I/I_{true}	I/I_{true}	$\alpha - \alpha_{true}$	$\alpha - \alpha_{true}$
Intensity Range	$> 20\mu Jy$	$5 - 20\mu Jy$	$< 5\mu Jy$	$> 50\mu Jy$	$10 - 50\mu Jy$
Cube	0.9 ± 0.1	0.9 ± 0.3	0.9 ± 0.5	-0.5 ± 0.2	-0.6 ± 0.5
Cube + AWP	1.0 ± 0.05	1.0 ± 0.2	1.0 ± 0.3	-0.15 ± 0.1	-0.1 ± 0.25
MTMFS + WB-AWP	1.0 ± 0.02	1.0 ± 0.04	1.0 ± 0.15	-0.05 ± 0.05	-0.1 ± 0.2

Wideband Mosaic of CTB80 (1-2 GHz, VLA-D config)

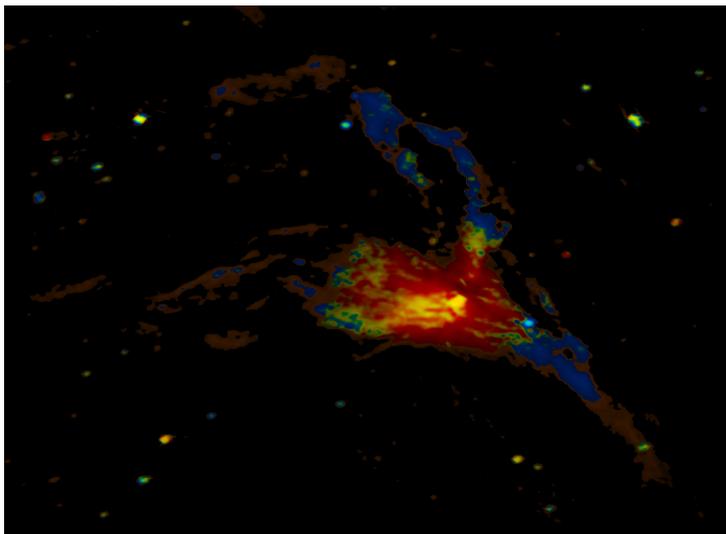
Intensity



Mosaic Primary Beam



Intensity-weighted Spectral Index



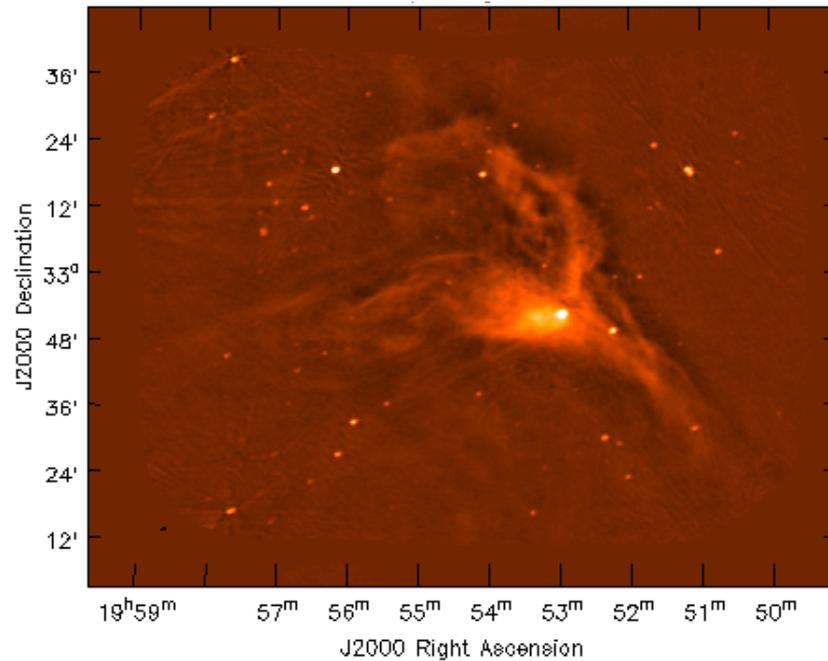
300GB calibrated dataset, 106 pointings over 1.5x2 deg, imaged with MS-MT-MFS (NT=2) + WB-A-Projection.

=> Mosaic primary beam spectral index of ~ -1.5 has been removed prior to the wideband sky model fitting.

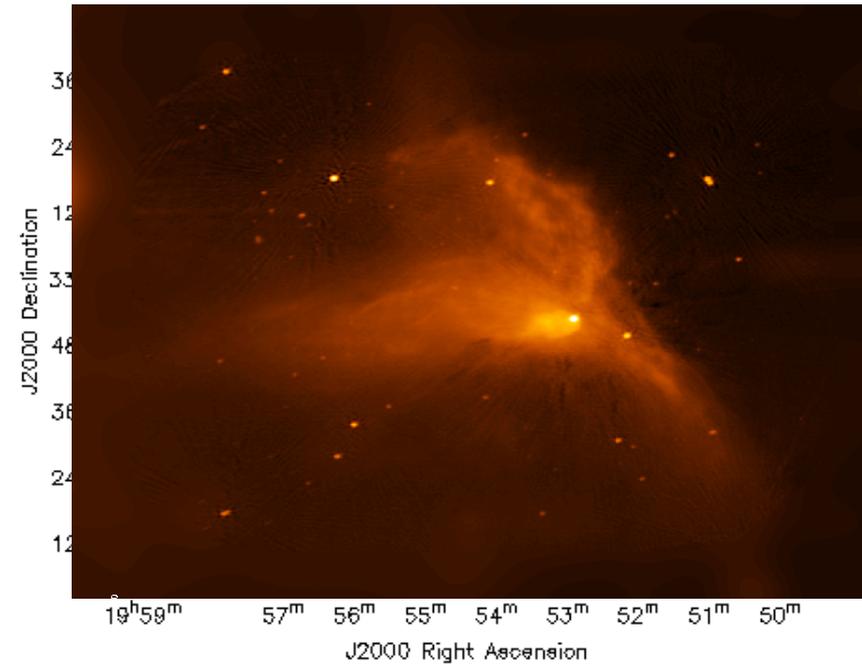
Wideband Mosaic + Single Dish data

Example : Combining Interferometer intensity image with Single dish data at reference frequency, using Feathering.

Int WB Mosaic



Int WB Mosaic + Single Dish



Joint SD+INT Spectral Index Map => Work in progress

Algorithms needed : Multiscale, Multi-term MFS, with A-Projection, W-Projection, form a Joint Mosaic, and Joint deconvolution with wideband single dish data.

(Must run in finite time → robust parallelization)

Wide Band + Full Beam/Wide-field

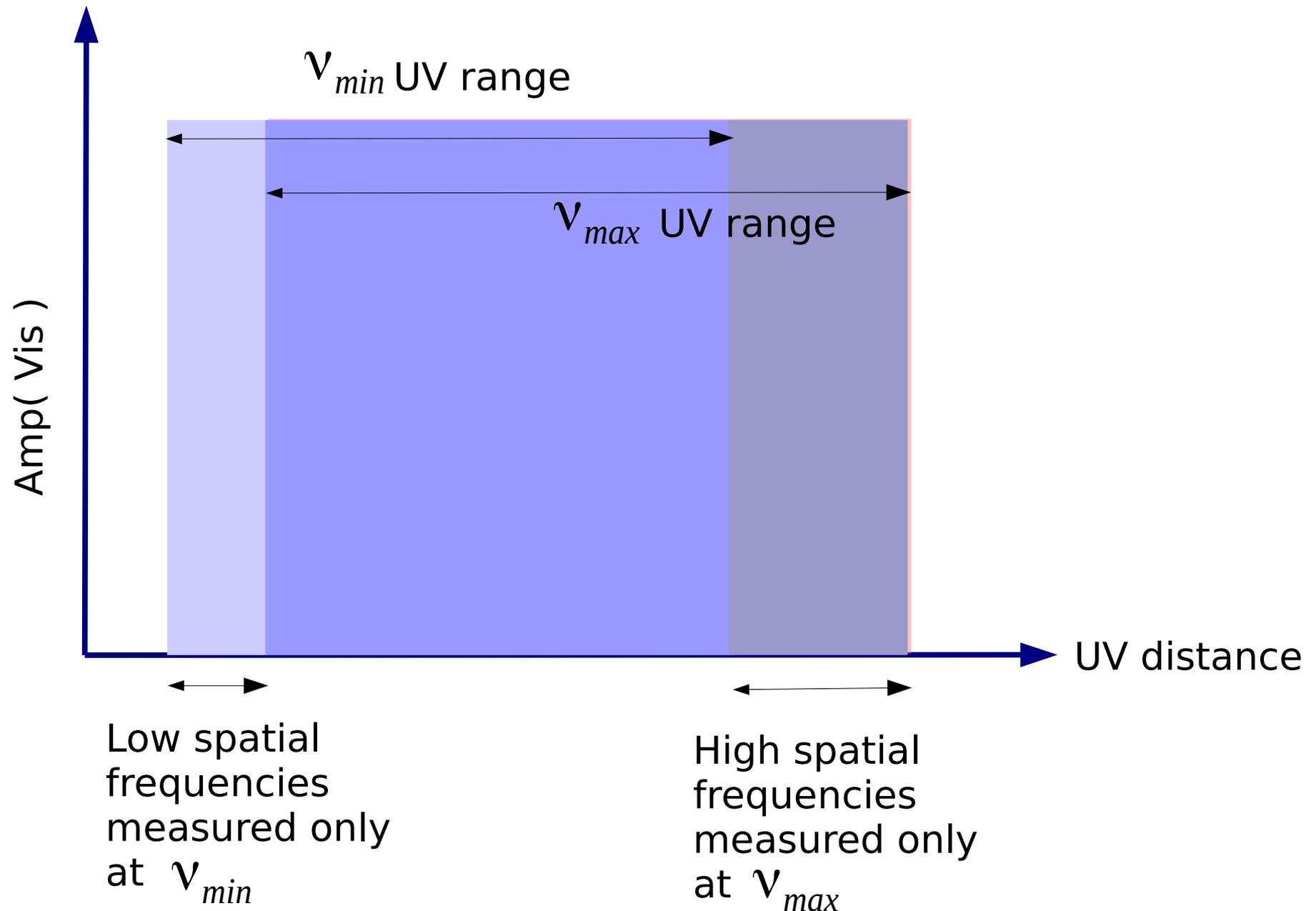
+ Mosaics

+ Single Dish

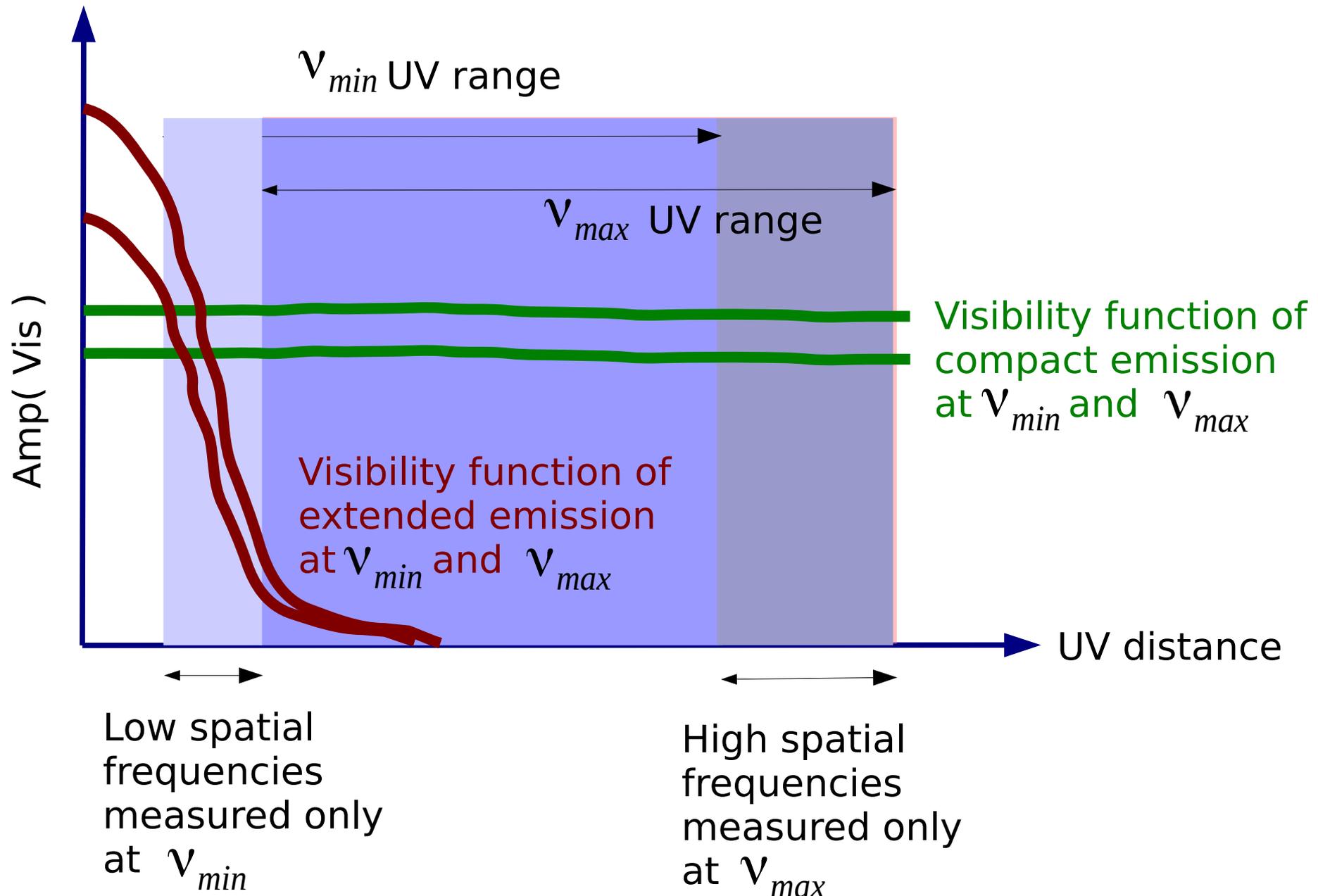
Example : Imaging the G55 supernova remnant

Imaging Framework

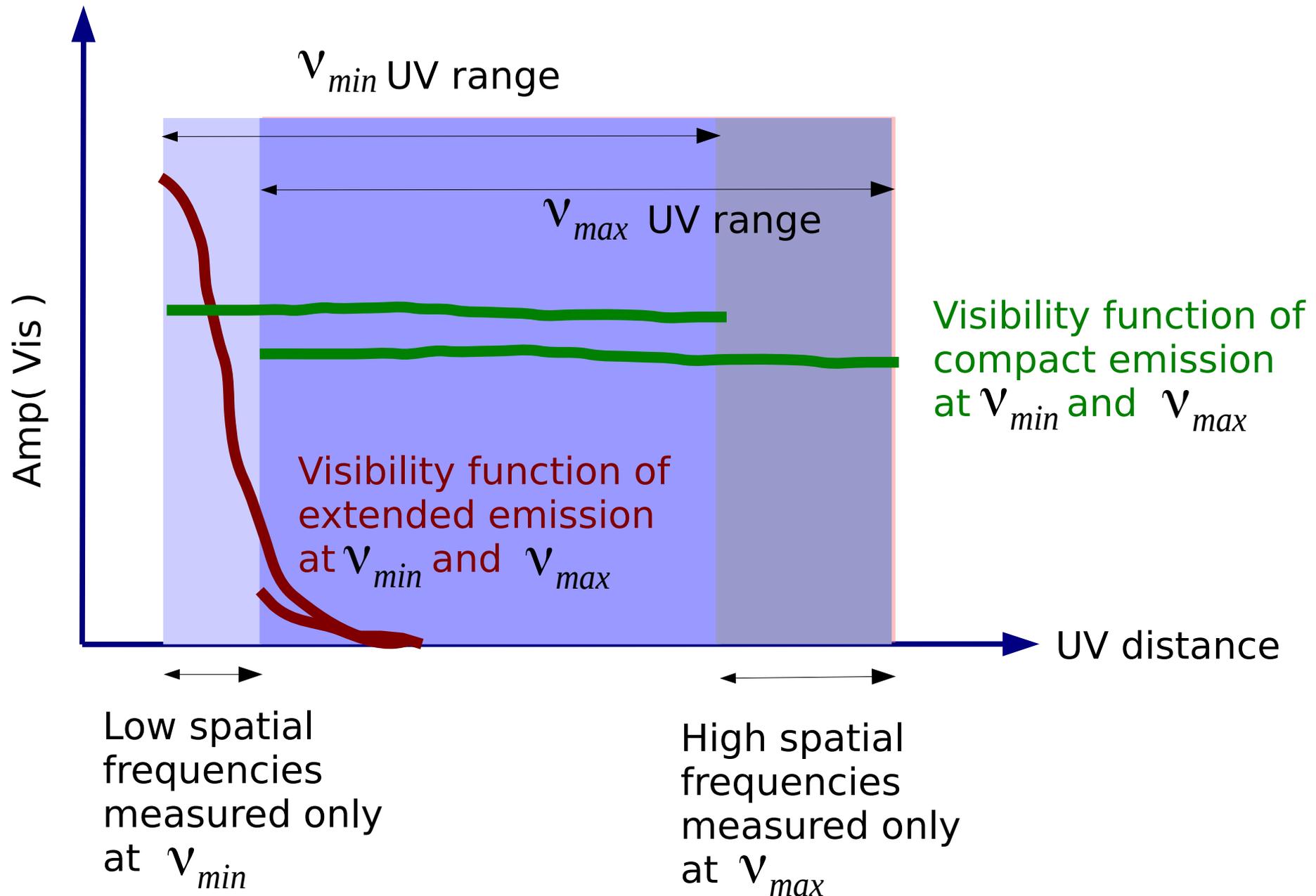
For which scales can we reconstruct the spectrum ?



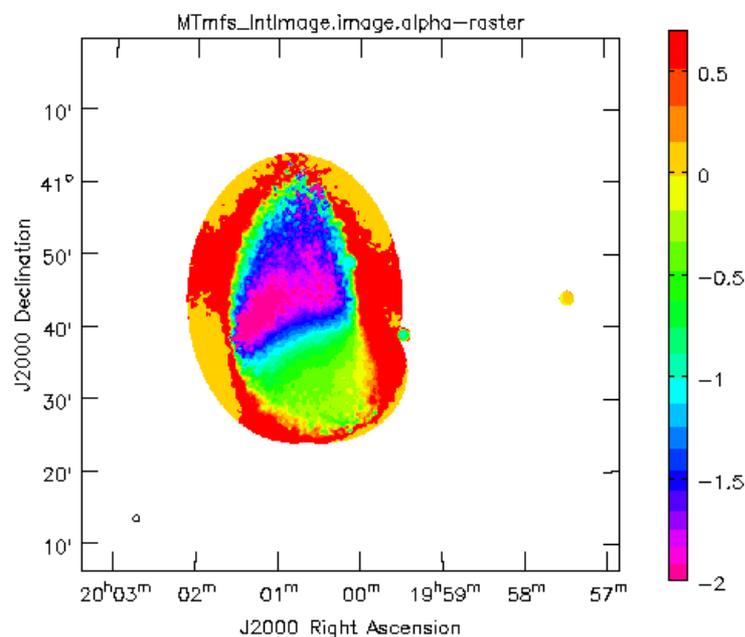
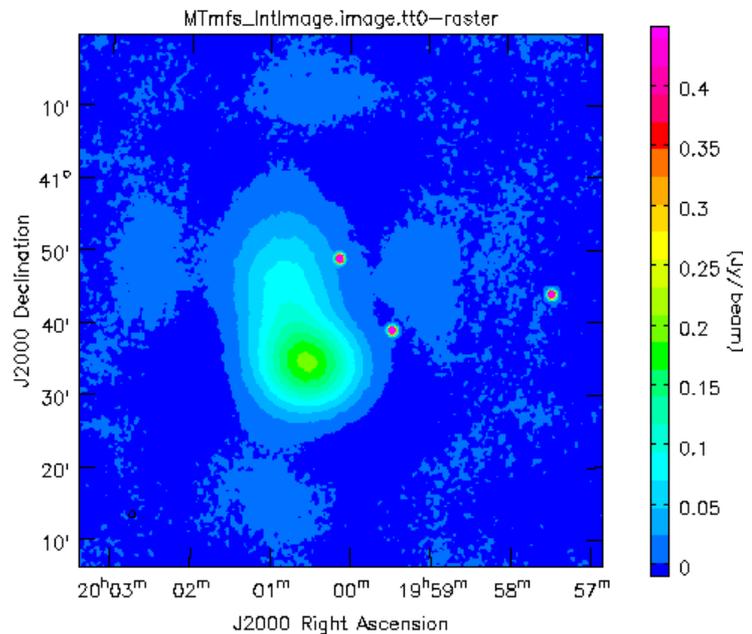
For which scales can we reconstruct the spectrum ?



For which scales can we reconstruct the spectrum ?

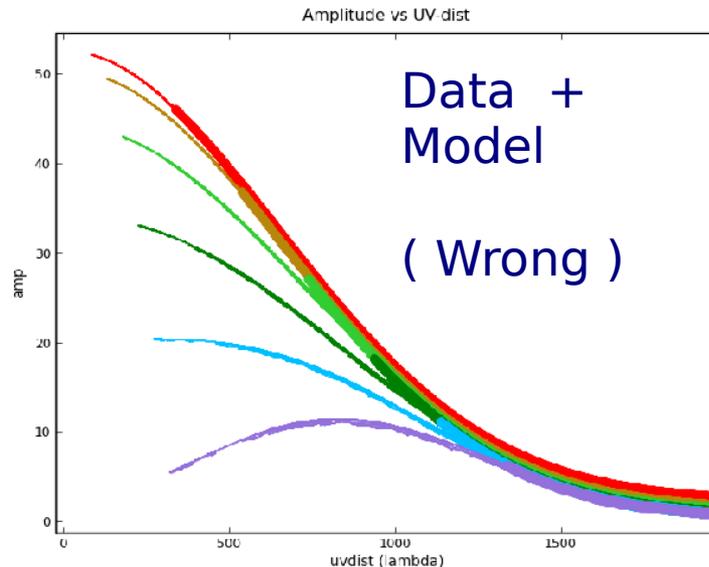
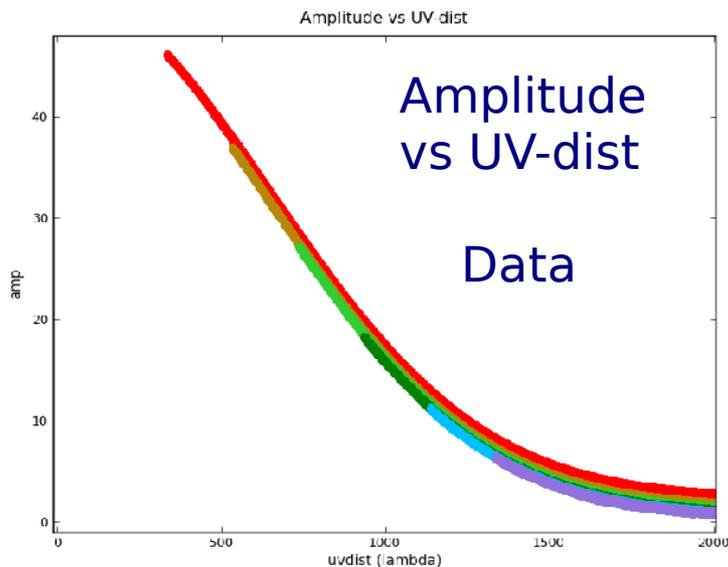


Very large spatial scales : wideband single dish data



Example : Flat spectrum emission at very large scales

Top : Only interferometer data
=> Negative bowl and artificial steep spectrum



No short spacings to constrain the spectra

=> False steep spectrum reconstruction

Wideband Single Dish + Interferometer Combination

Several Algorithms can be applied to wideband data.

(1) **Feathering** : Image SD and INT data separately (in wideband mode)
Combine outputs using a UV-domain weighted average
Perform feather per Taylor coefficient map.

=> Works best when noise levels match, weighting choice is obvious, and no mid-scale artifacts in the INT-only reconstruction.

(2) **Startmodel** : Use SD images as a starting model for the INT reconstruction

=> Works if there is clear overlap in UV-range between SD and INT data.

(3) **Artificial visibilities** : Simulate virtual SD visibilities, combine with INT data

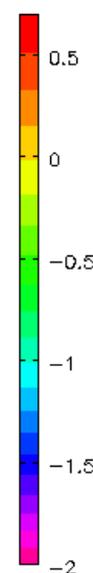
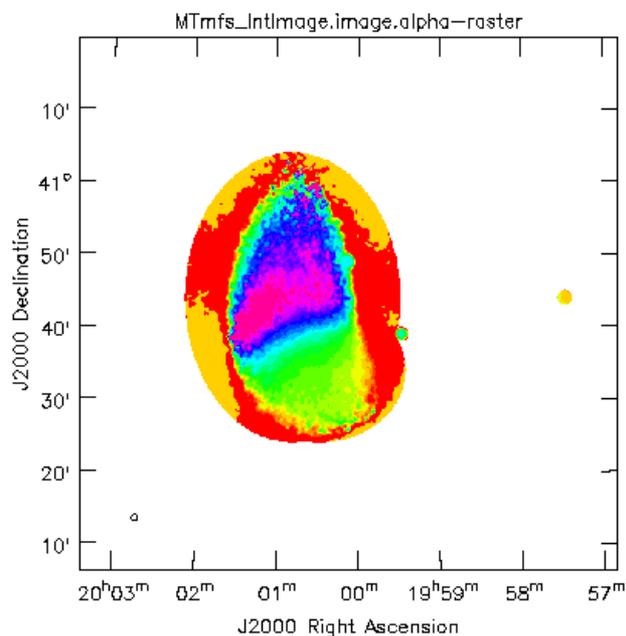
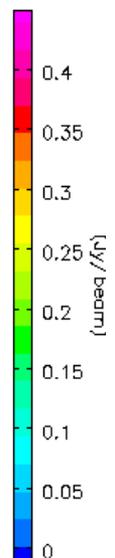
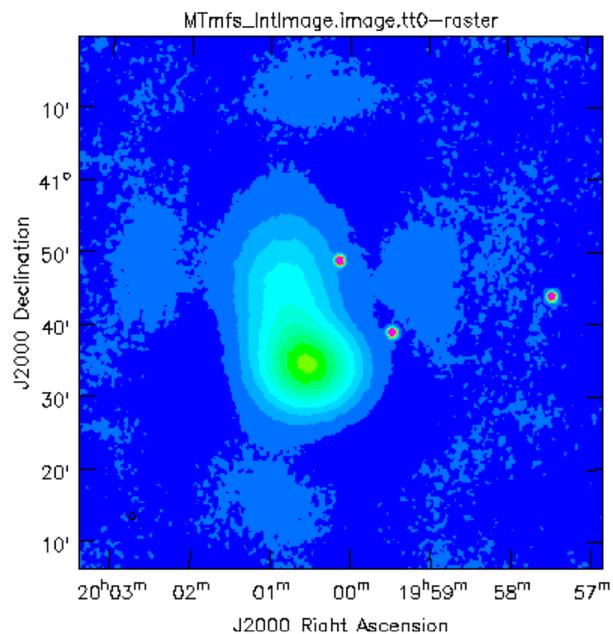
=> Flexible, a true joint reconstruction, relative weights handled externally.
[Koda et al, 2011]

(4) **Merge residual images and PSFs between major and minor cycle** :

=> Flexible, a true joint reconstruction, weight functions part of reconstruction framework, compatible with all wide-field, wide-band algorithms.

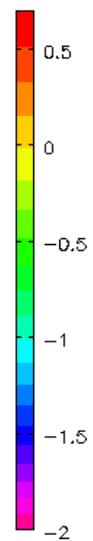
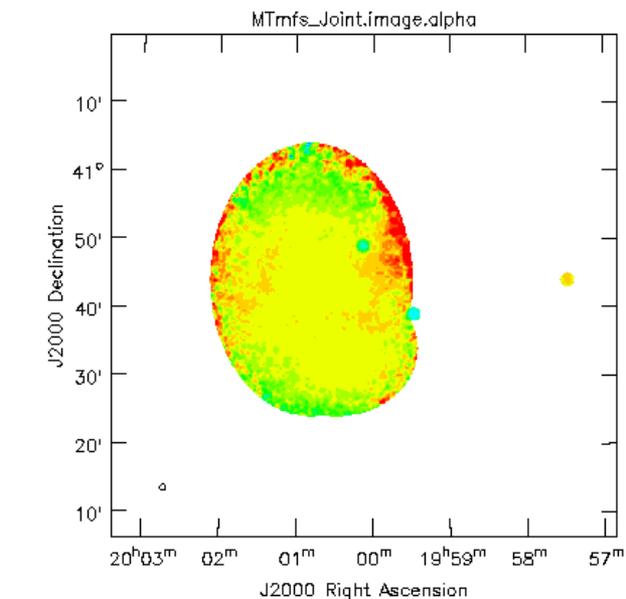
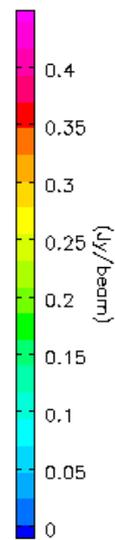
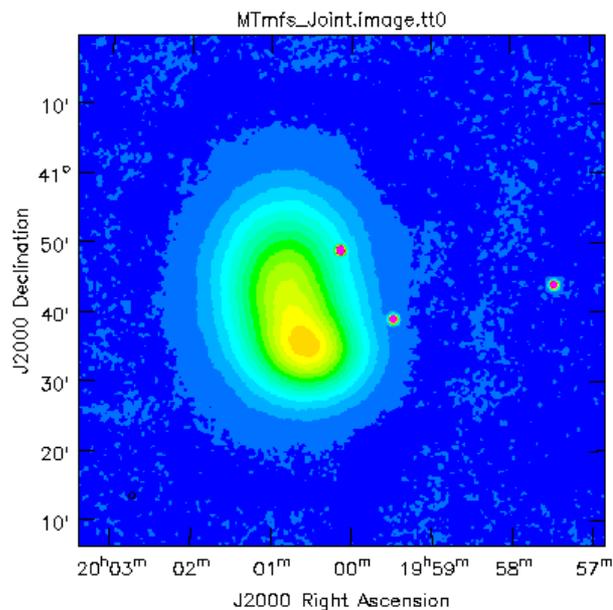
[Rau et al, 2019]

Very large spatial scales : wideband single dish data



Example : Flat spectrum emission at very large scales

Top : Only interferometer data
=> Negative bowl and artificial steep spectrum



Bottom : Joint wideband reconstruction (4)

=> Recovers more flux and gets accurate spectrum

=> Compatible with wide-field, wideband, mosaics

Wide Band + Full Beam/Wide-field

+ Mosaics

+ Single Dish

Example : Imaging the G55 supernova remnant

Imaging Framework

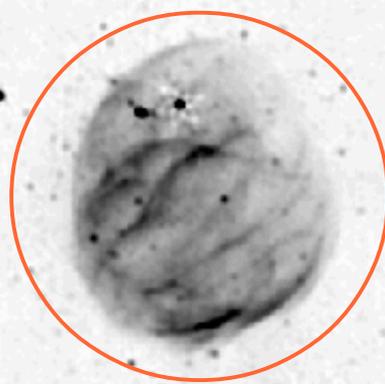
Example : SNR G55.7+3.4

7 hour synthesis, L-Band, 8 spws x 64 chans x 2 MHz, 1sec integrations

Due to RFI, only 4 SPWs were initially imaged (1256, 1384, 1648, 1776 MHz)

J2000 Declination

30'
15'
22°00'
45'
30'
15'
21°00'
45'



Imaging Algorithms applied : MS-MFS with AW-Projection

(nterms=2, multiscale=[0, 6, 10, 18, 26, 40, 60, 80])

Peak Brightness : 6.8 mJy

Extended Emission : ~ 500 micro Jy

Peak residual : 65 micro Jy

Off-source RMS : 10 micro Jy (theoretical = 6 micro Jy)

19^h26^m

24^m

23^m

22^m

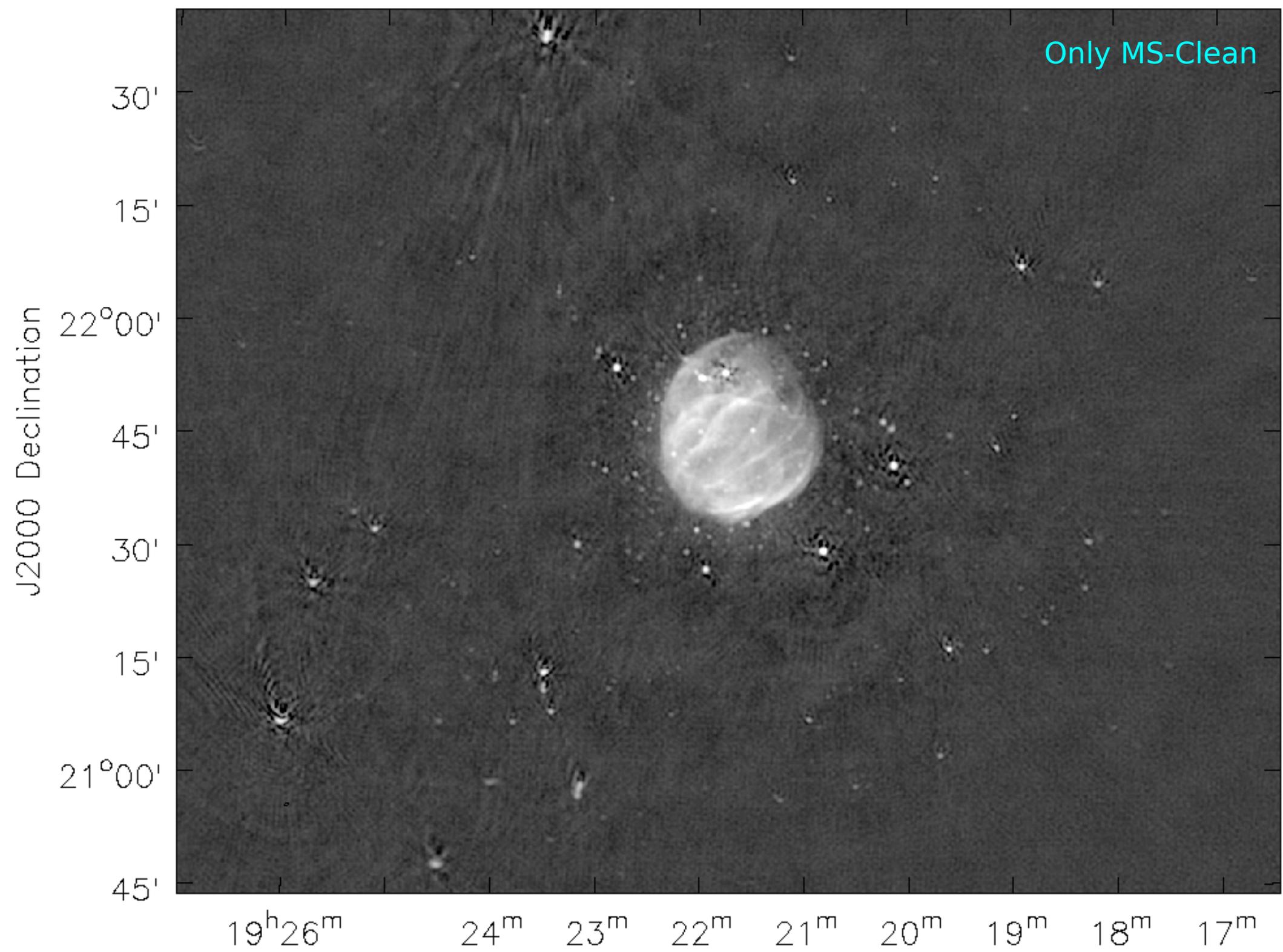
21^m

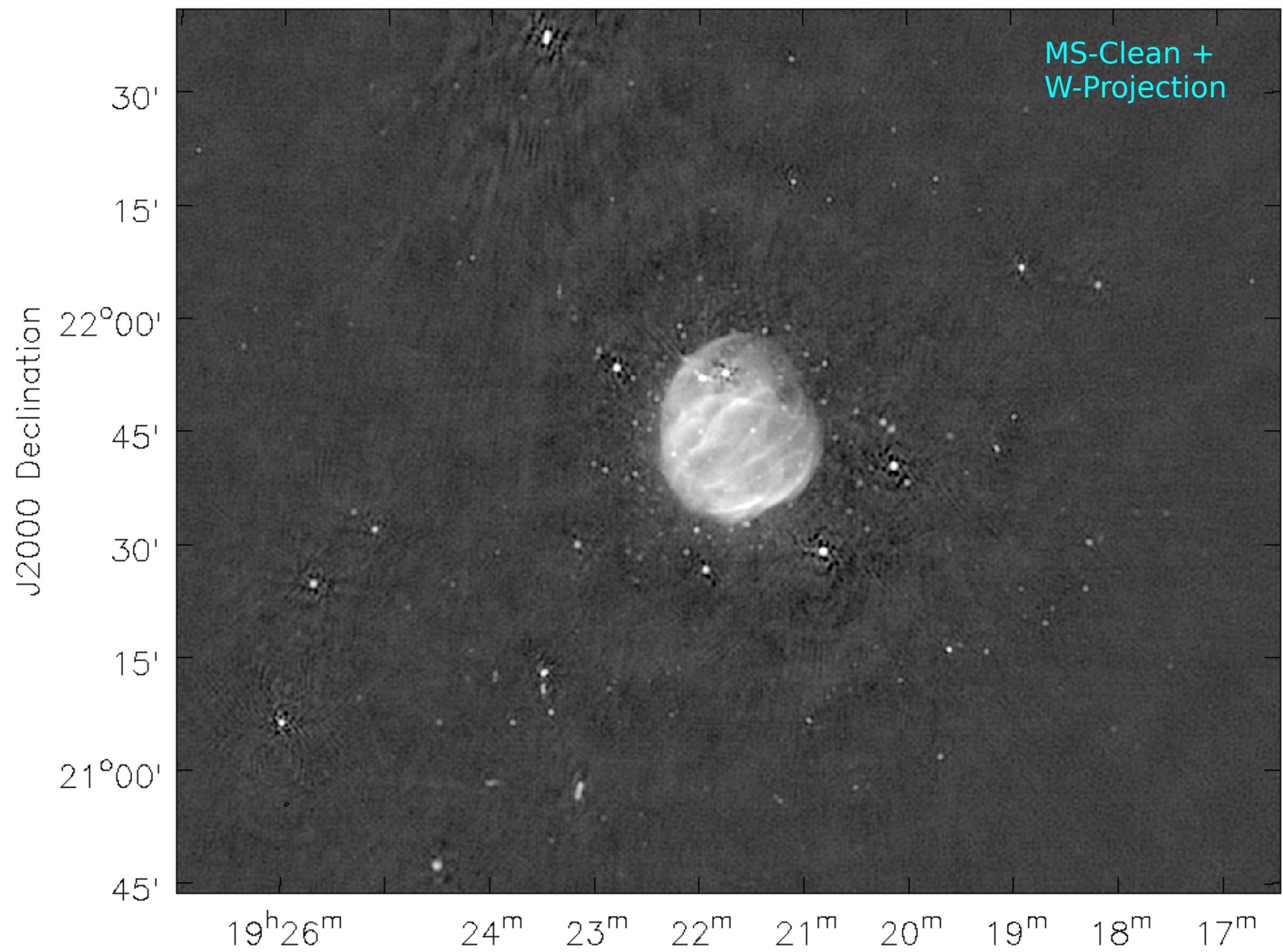
20^m

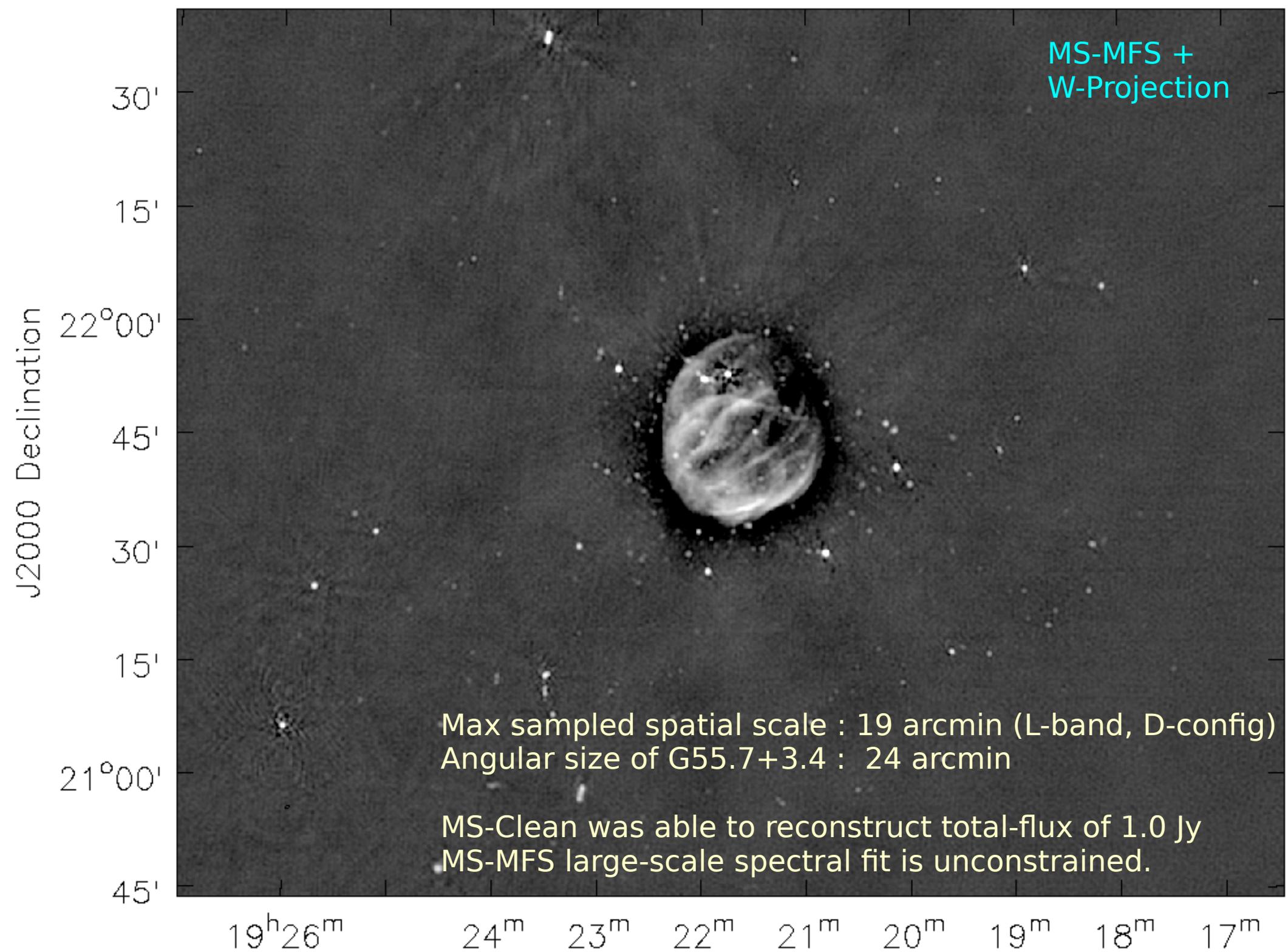
19^m

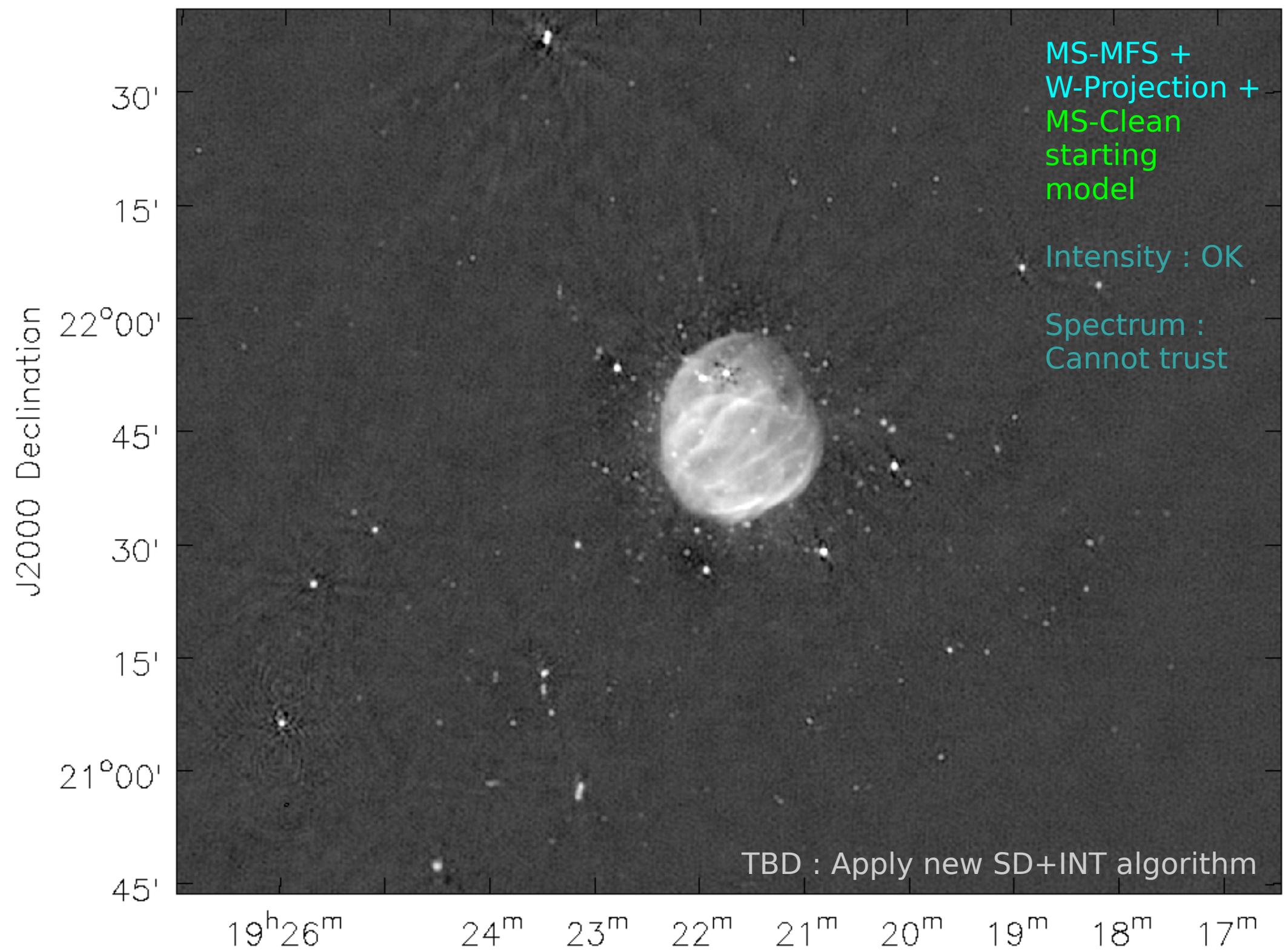
18^m

17^m





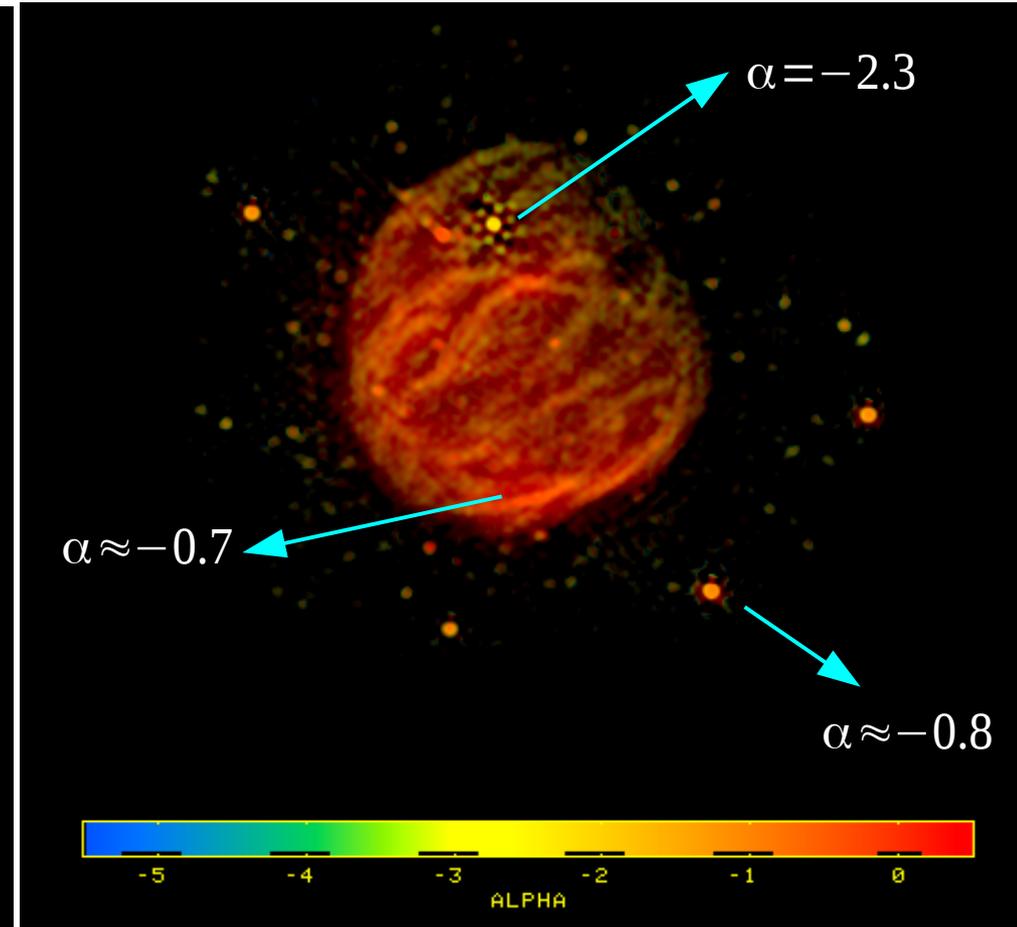
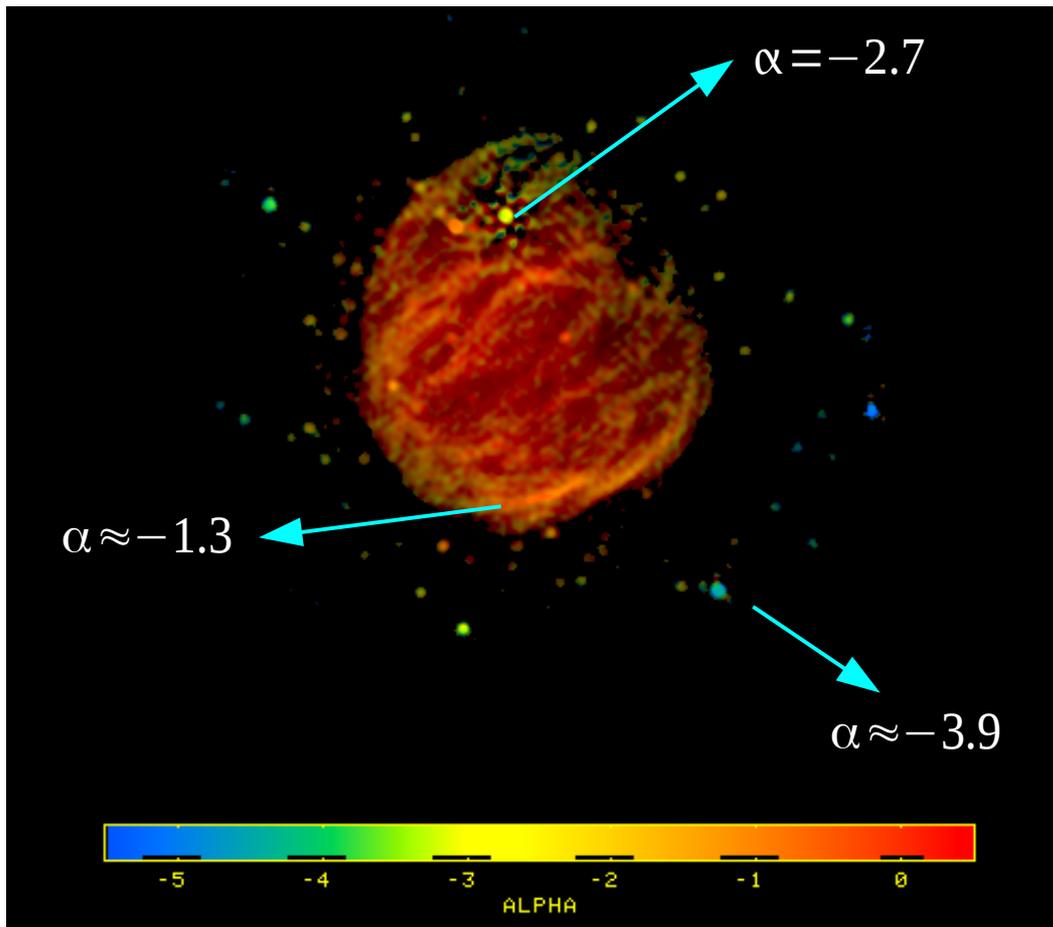




Spectral Indices before and after WB-A-Projection

Without PB correction
Outer sources are artificially steep

With PB correction (via WB-AWP)
Outer sources have correct spectra

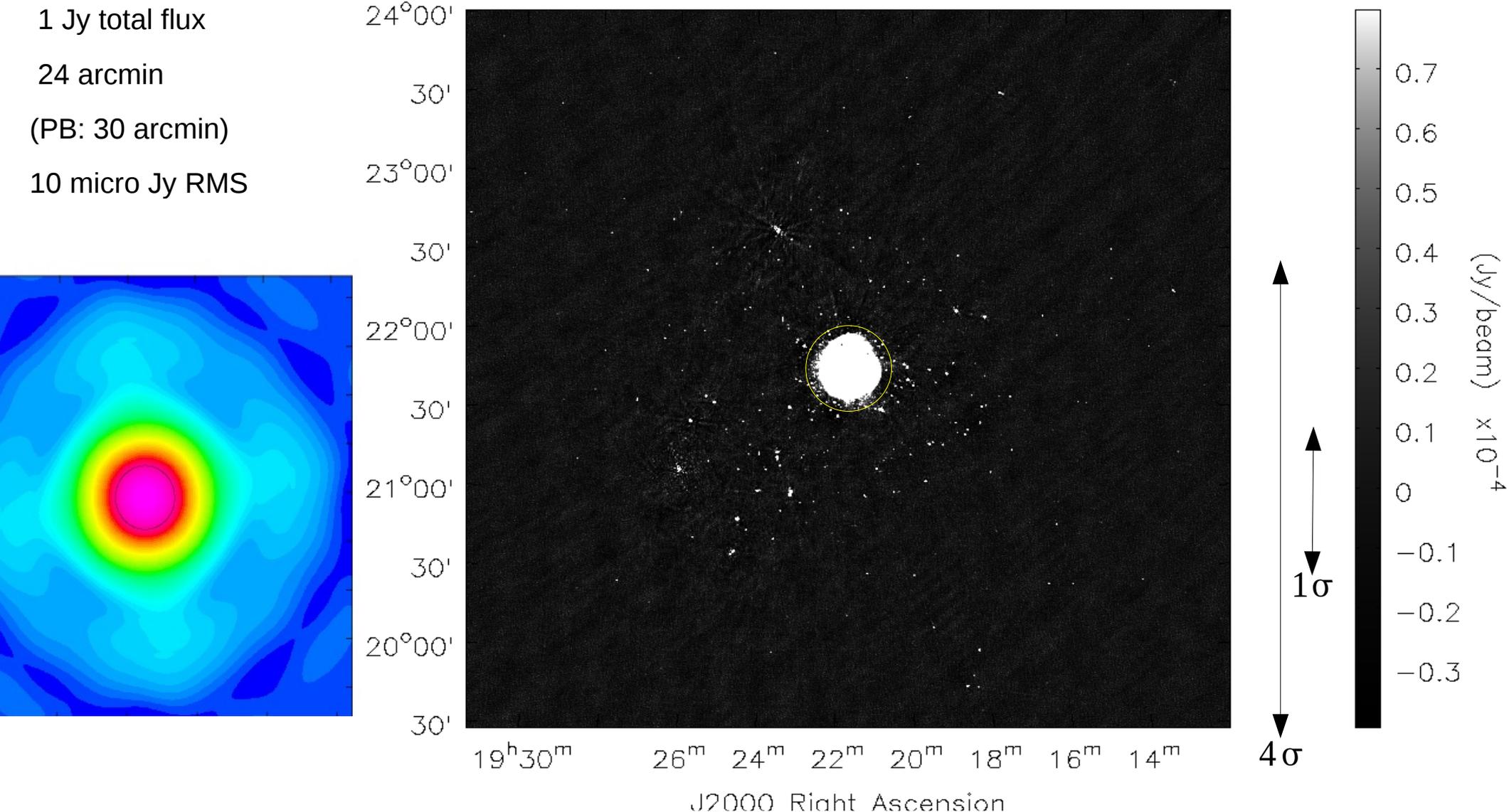


Intensity-weighted spectral index maps (color = spectral index from -5.0 to +0.2)

Wide-field sensitivity because of wide-bandwidths

G55.7+3.4 : Field-of-view of 4x4 degrees from one EVLA pointing at 1-2 GHz

1 Jy total flux
24 arcmin
(PB: 30 arcmin)
10 micro Jy RMS



=> Wideband Imaging implies wide-field imaging

Wide Band + Full Beam/Wide-field

+ Mosaics

+ Single Dish

Example : Imaging the G55 supernova remnant

Imaging Framework

Measurement Equation

The visibility measured by each baseline ij at one frequency and time

$$V_{ij}^{obs}(\nu, t) = M_{ij}(\nu, t) S_{ij}(\nu, t) \iiint M_{ij}^s(l, m, \nu, t) I(l, m, \nu, t) e^{2\pi i(ul + vm + w(n-1))} dl dm dn$$

Direction Independent Gains

- Eliminated during calibration

Primary Beams

- Power pattern varies with time, frequency and baseline

- **PBcor (post-deconvolution)**
 - **A-Projection**
 - **WB-A-Projection**
 - **Mosaics**

Full Beam

Sky-brightness varies with frequency (time)

- All sources have spectral structure (some vary with time)

- **Cube Imaging**
 - **Multi-Frequency Synthesis (MFS)**
 - **Multi-Term-MFS**
 (point source or multi-scale models)

Wide-Band

W-Term

- Non-coplanar baselines

- Sky curvature

- **Faceting**
 - **W-Projection**
 - **3D FT**
 - **W-Stacking**

Wide-Field

Imaging Framework - Major and Minor cycles

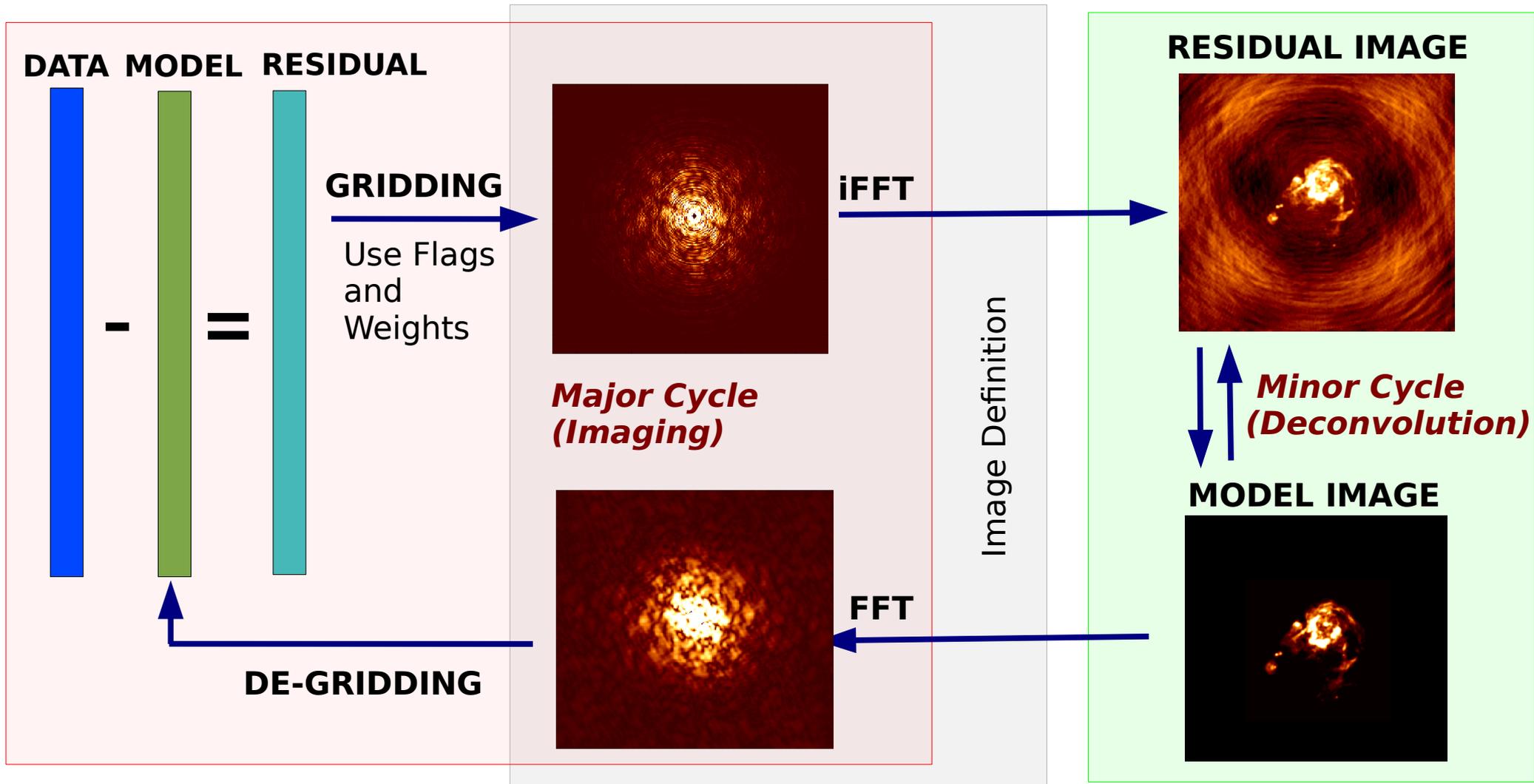
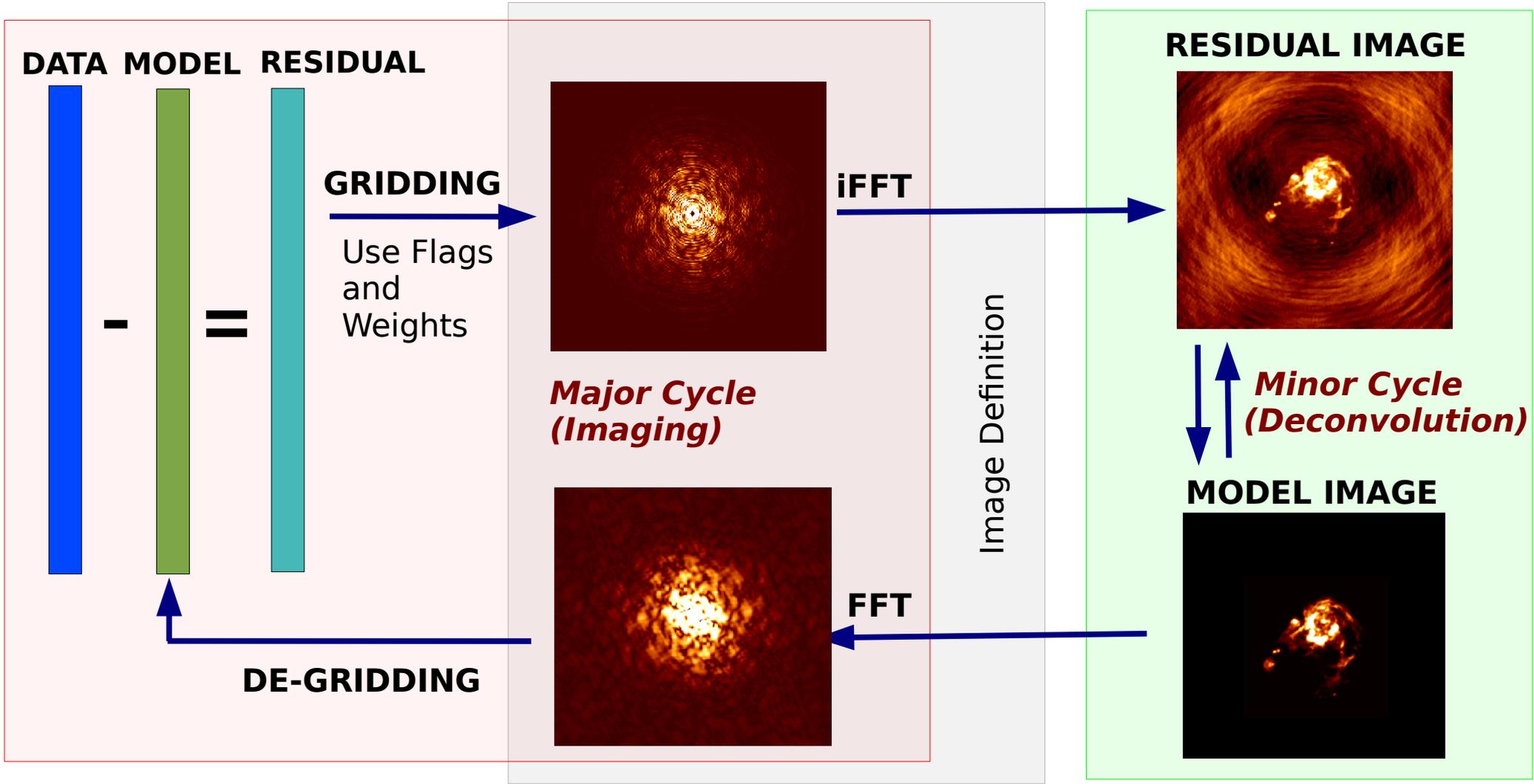


Image reconstruction is an iterative model-fitting / optimization problem

$$\text{Measurement Eqn : } [A] I^m = V^{obs}$$

$$\text{Iterative solution : } I_{i+1}^m = I_i^m + g [A^T W A]^+ (A^T W (V^{obs} - A I_i^m))$$

Imaging & Deconvolution

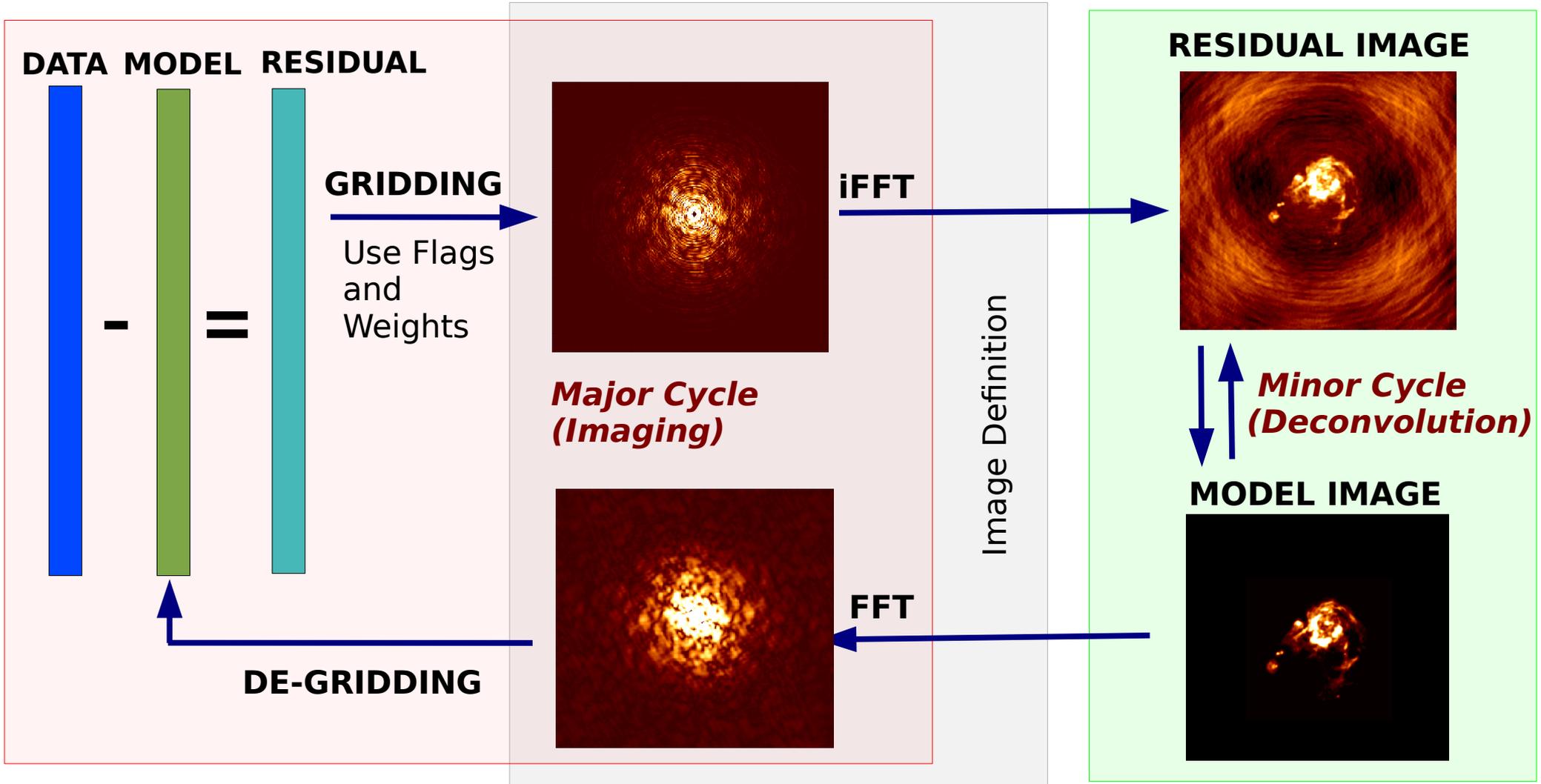


Instrumental Corrections (applied per visibility during gridding)

Mapping of data to Image Shape/Type

Solving for the sky model (non-linear optimization)

Algorithm Options

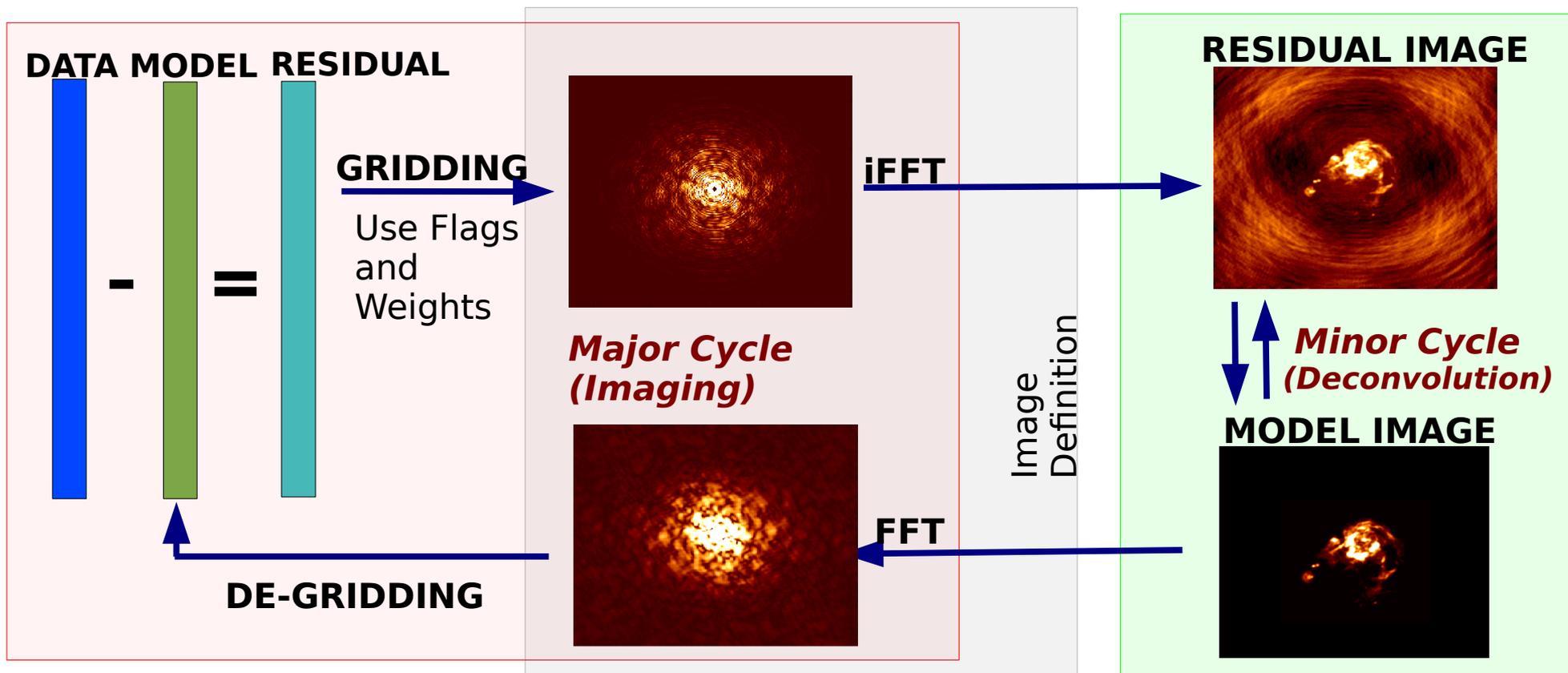


Standard gridding, W-Proj (WB)-A-Proj, Joint Mosaics, (Parallelization)

Cube, MFS, MT-MFS, Faceting, Stokes, Multi-Field, SD+INT Stitched Mosaic

Clean (Hogbom, Clark, MultiScale, MultiTerm, etc...)

Computational Cost



Runtime and computing resources depend on many factors.

=> Choose algorithms wisely...

- (a) Data Volume, (b) Gridding Algorithm, (c) Joint vs Separate reconstructions, (d) Deconvolution algorithm, (e) Sky brightness structure and convergence rate (f) Dynamic range, calibration accuracy (g) Iteration Control

Summary – Lectures 1 & II

Wide Band Imaging

Sky and instrument change with frequency
=> Cube vs MFS, wideband/multiscale model, spectral index

Wide Field Imaging

non-coplanar baselines and the W-term
=> W-Projection, W-Stacking, Faceting, 3D FFTs

Full Beam Imaging

antenna primary beams
=> pbcor, A-Projection, beam models

Wide-Band + Primary-Beams + Mosaics + W-term + Single-Dish
(+ Full-Pol + Clean/MS-Clean/etc...)

Major/Minor Cycle Imaging Framework

=> Flexible imaging framework that logically organizes all the pieces

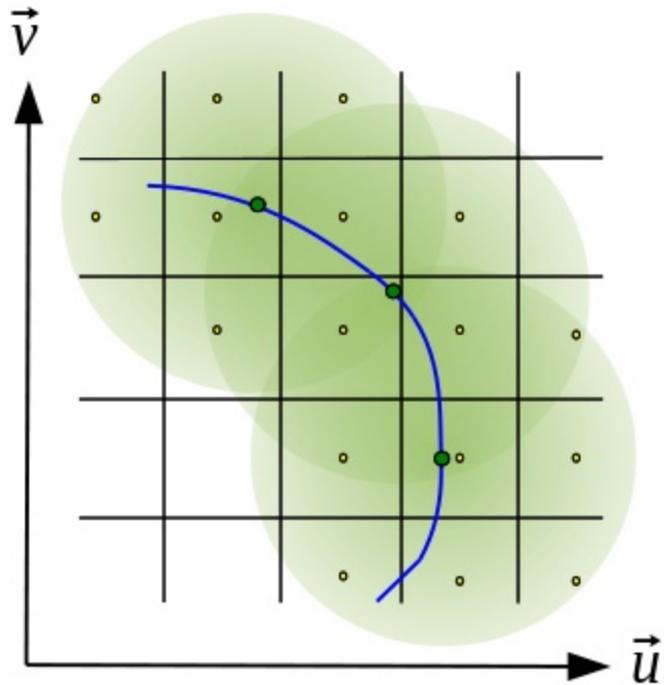
Need to choose algorithms carefully

[[Algorithm/software development is ongoing to refine all these ideas !]]

EXTRA SLIDES

Major Cycle : Data to Image, Model to Data

Gridding = Convolutional Resampling of visibilities to a regular grid

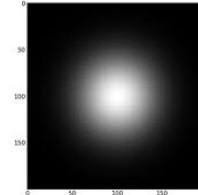


Convolution in UV-domain (per vis)
= Multiplication in Sky domain

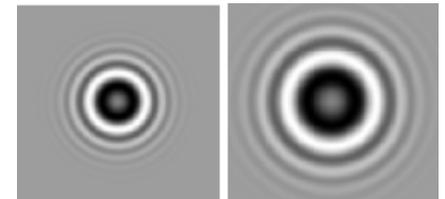
=> Handle wide-field imaging effects

Degridding : Model \rightarrow Data

Standard Imaging :
Prolate Spheroidal

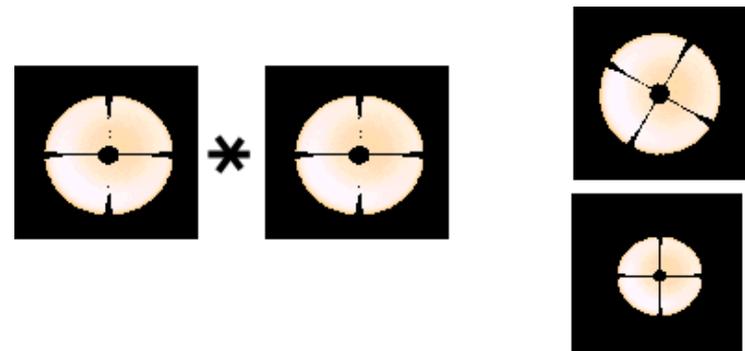


W-Projection :
FT of a Fresnel
kernel



A-Projection :

Baseline aperture illumination functions
+ phase gradients for joint mosaics



Combined algorithms :
Convolutions of different kernels

Minor Cycle : Solving for a sky model

For Point Sources :

- Hogbom Clean
- Clark Clean

For Point/Extended Sources :

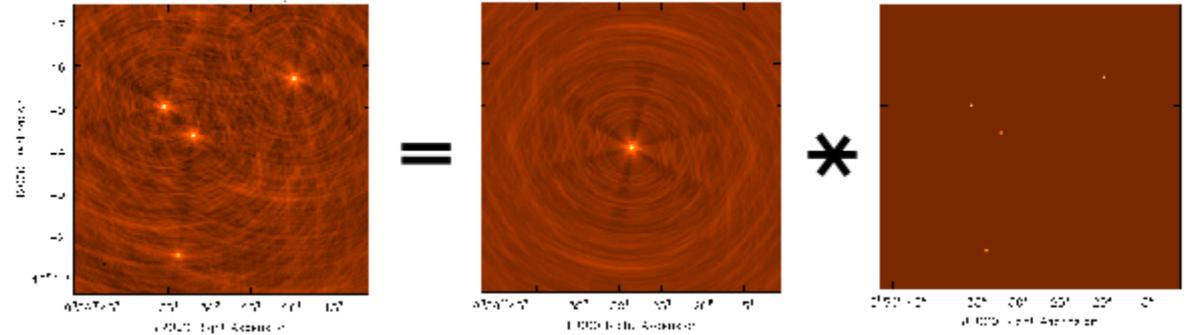
- Multi-Scale-Clean

For Wide-band Sky models

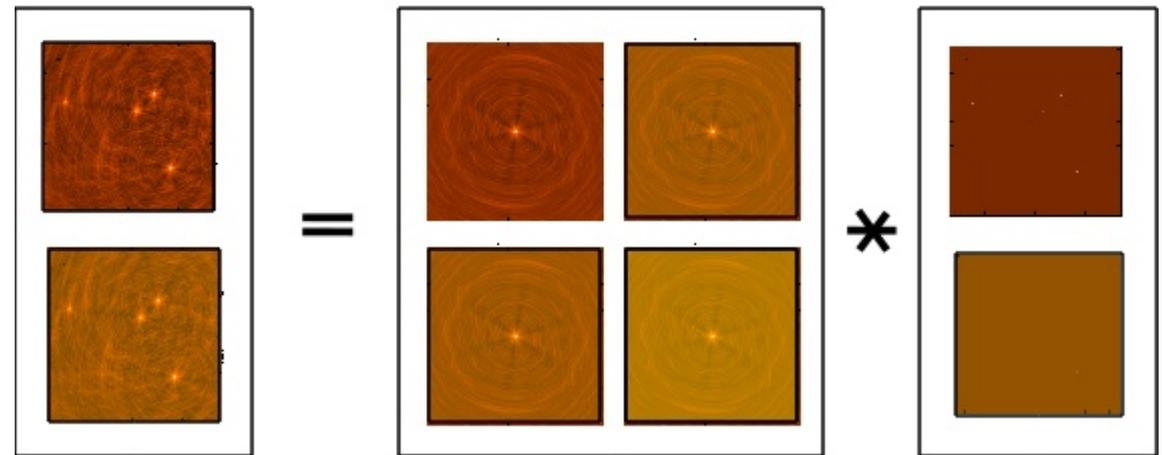
- Multi-Term MFS Clean
with or without Multi-Scale

(similar algo for time-variability)

Convolution Equation ==> Deconvolution



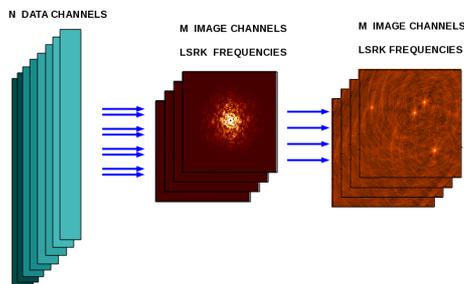
Multi-Term Convolution Equation
==> Joint Deconvolution



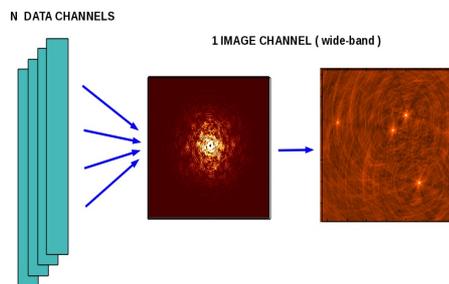
Other potential options : Any non-linear image-domain solver
E.x. Compressed sensing ideas : Gaussians (ASP), Wavelets (SARA/PURIFY),
Bayesian forms (MEM, RESOLVE, etc), wide-band non-parametric models, etc..

Mapping data to image coordinates/shapes

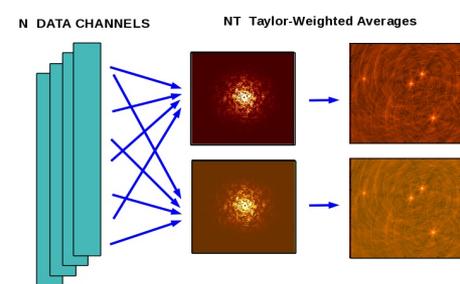
Spectral Cube



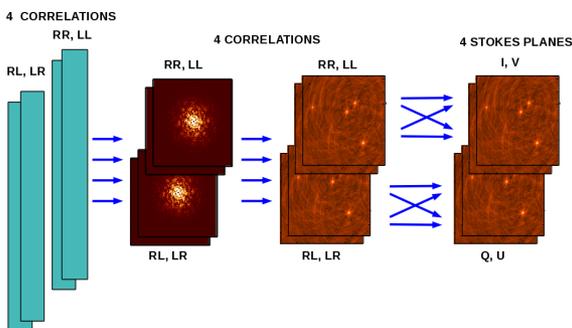
Continuum



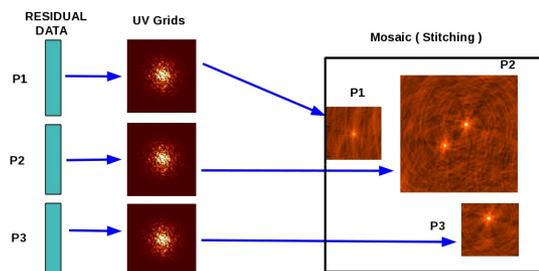
Wideband Continuum



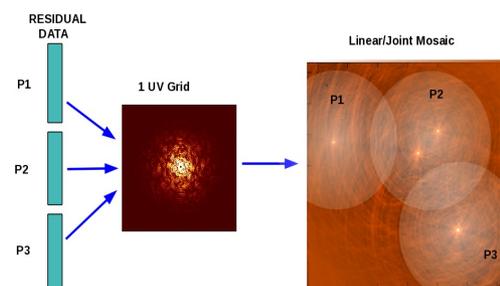
Stokes Planes



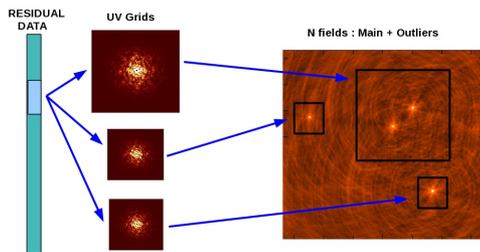
Stitched Mosaic



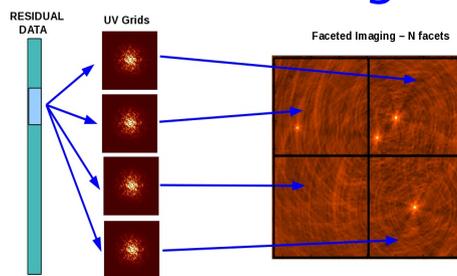
Joint Mosaic



Multi-Field



Faceting

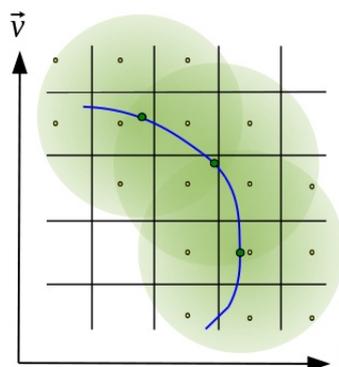


Different algorithms arise from different mappings of data to images

<https://casa.nrao.edu/casadocs/casa-5.1.2/synthesis-imaging/image-definition>

Computational Costs

Imaging runtime and compute resources depend on data size, sky signal, and algorithms chosen



Gridding : Convolutional resampling

$O(N_{\text{data}}) \times (n \times n)$ complex multiply/add ($n=5 - 100$)
 \Rightarrow Compute load : $O(N_{\text{data}}) * 10^{\{2-5\}}$ flops

Data parallelization, Multi-threading, GPUs, etc...

Example : Major cycle : 1hr \rightarrow 10 days (Diff Algorithms)

Data volume

$$N_{\text{data}} = N_{\text{ant}}^2 \times N_{\text{chan}} \times N_{\text{pol}} \times N_{\text{time}}$$

Complex numbers

Lustre I/O

Example :
 8hr data
 300 GB

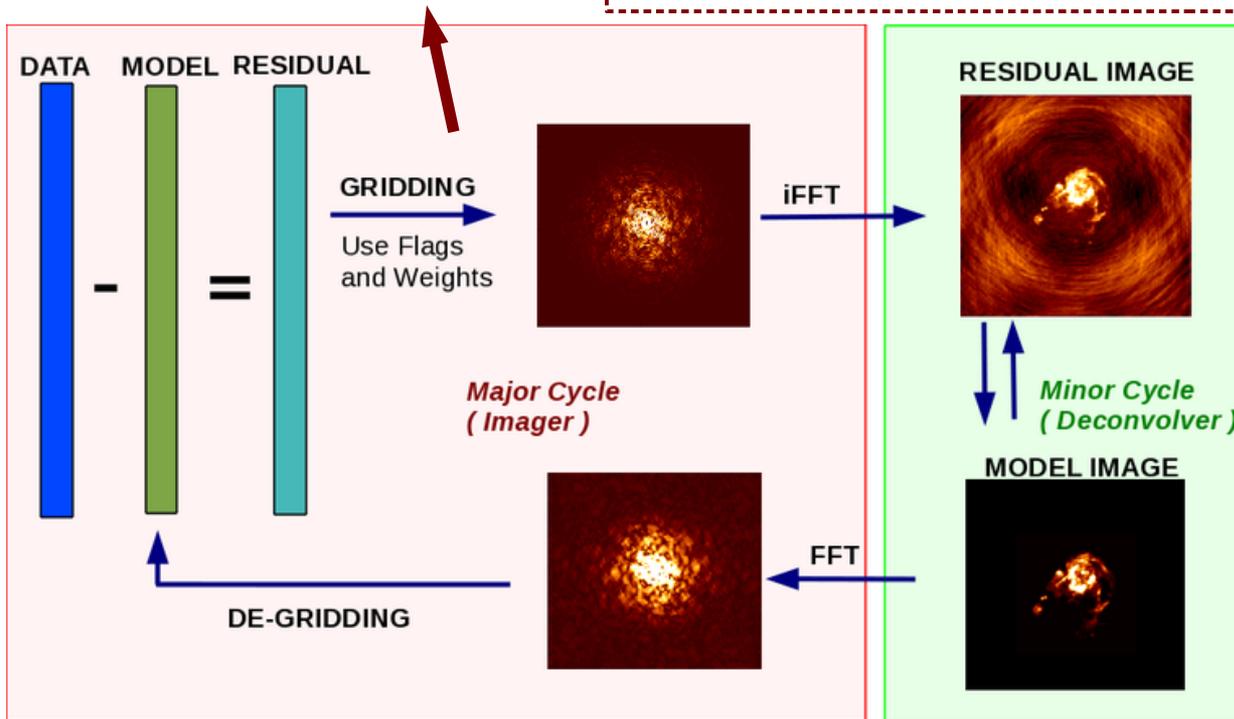


Image sizes

$$N_{\text{pix}} = N_x \times N_y \times N_{\text{chan}} \times N_{\text{pol}}$$

Real / Complex
 FFTs : $O(N \log N)$
 Pixel math: $O(N^2)$
 Mem : ~ 8 copies

Multi-threading
 Chan parallelization

N_x : 1k \rightarrow 40k
 N_{chan} : 200 - 16K

Example :
 1K x 1K x 256
 ~ 1 GB per image

Number of iterations : 5 - 10 major cycle loops
 10^2 to 10^4 minor cycle steps

Runtime varies by 1-2 orders of magnitude. Depends on data.

Wide Band + Full Beam Imaging – Some guidelines

- MFS has better imaging fidelity, resolution and sensitivity than Cube
 - For 2:1 bandwidth, the dynamic range limit with standard MFS (no spectral model) is few 100 to 1000 for a spectral index of -1.0
- MT-MFS gives HDR images when the spectral model is appropriate and there is sufficient SNR.
 - For point sources, spectral index errors < 0.1 for $\text{SNR} > 50$ (2:1 bwr)
for $\text{SNR} > 10$ (4:1 bwr)
 - For extended emission, spectral index errors < 0.2 for $\text{SNR} > 100$
- W-Projection is more accurate and faster than Faceting
 - For D-config,L-Band, uncorrected W errors are visible outside 1 deg
- PBcor assumes invariant beams, (WB)-A-Projection handles variability
 - Uncorrected VLA beam squint and rotation causes $\text{DR} < \text{few} \times 10^4$
 - For 2:1 bwr, the PB's artificial spectral index at the HPBW is -1.4