

# Giant Metrewave Radio Telescope (GMRT): A System Overview

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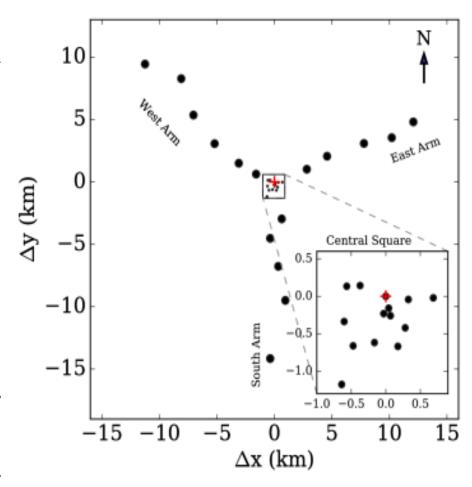
Radio Astronomy School - 2023

March 18 2023

GMRT

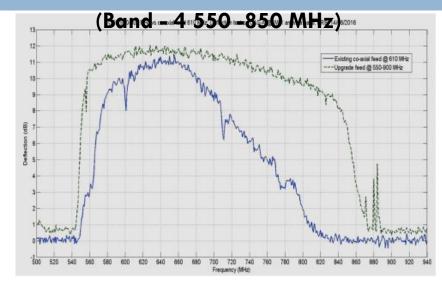
#### Giant Metrewave Radio Telescope

- Sensitive telescope operating between 150 to 1450 MHz. A national project of the Govt. of India
- Located 80 km north of Pune, 160 km east of Mumbai
- Array telescope: 30 antennas, each \$\frac{1}{2}\$ of 45 m diameter 14 antennas in 1 sq. km. region, other spread in a Y-shaped array
- Central square (C00 C14, except C07), E-arm (E02-E06), W-arm (W01-W06), S-arm (S01-S06, except S05)



#### The Upgraded GMRT

- Near seamless observing (120 – 1450 MHz)
- Four observing bands:
  - Band -2 (120 240 MHz)
  - Band -3 (250-500 MHz)
  - Band -4 (550-850 MHz)
  - Band -5 (1050-1450 MHz)
- 400 MHz instantaneous bandwidth
- Improved sensitivity (P=kTB watts, for noise-like signals)



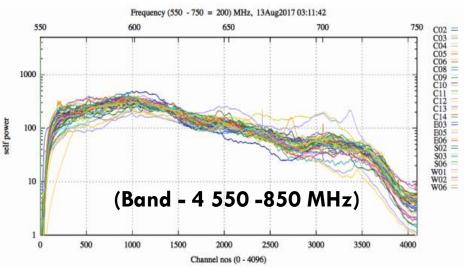


Image Courtesy: FE group + Control room

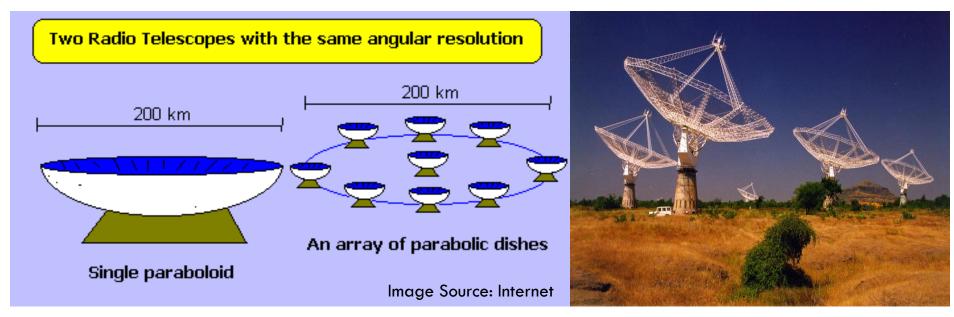
#### Angular Resolution: resolving distant objects

Resolve two distant objects in the sky

$$\Theta \sim \lambda/D$$

For a given wavelength, depends on the diameter of the telescope or maximum separation between two antennas

GMRT best resolution (L-band Synthesized beam):  $\sim 2"$ 

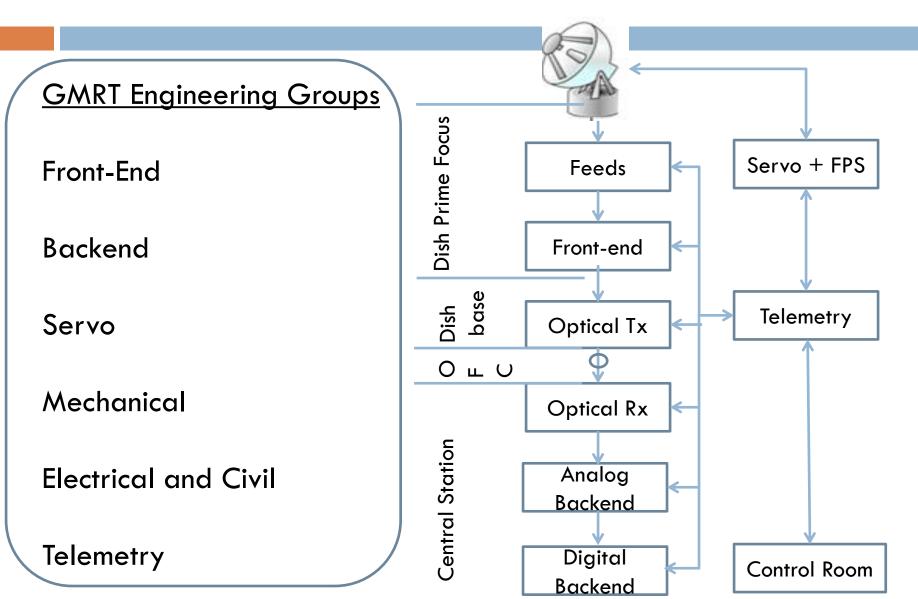


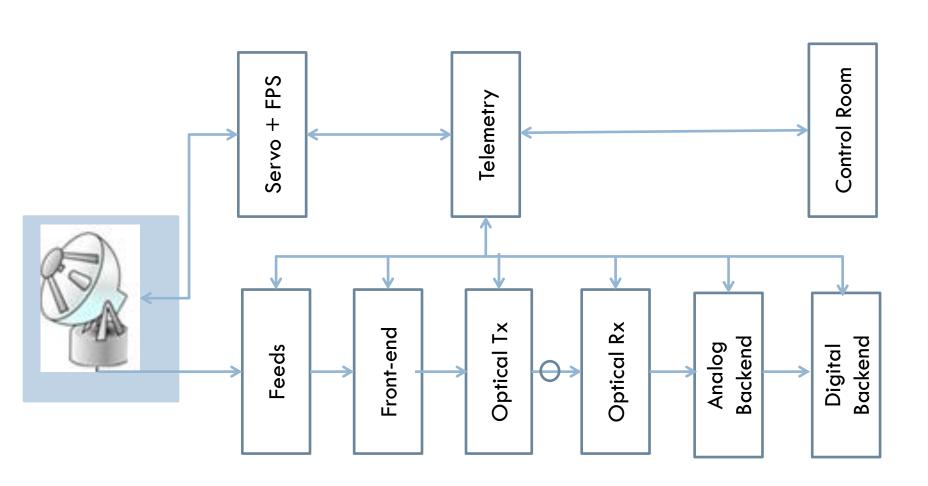
Sampling the source signal through different apertures

#### Short Spacing Antennas of GMRT

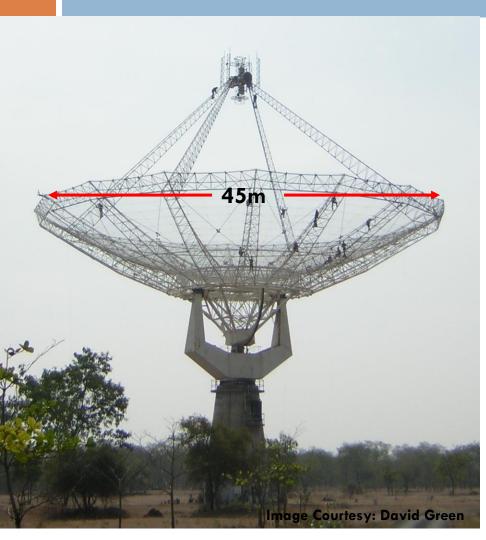


Shortest spacing  $\sim 100$ m; largest spacing  $\sim 25$ km





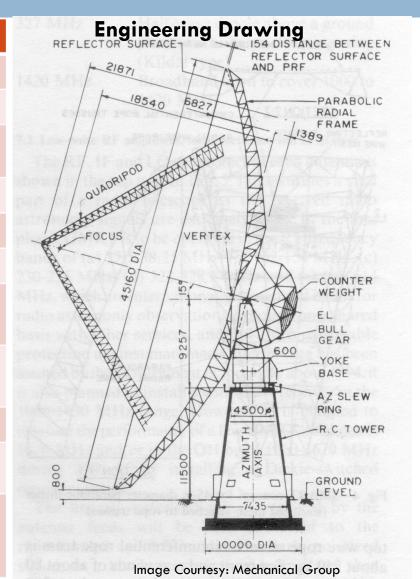
#### **GMRT** Antenna



- ☐ Prime-focus parabolic reflector dish antenna of 45m diameter
- Physical aperture depends on the dish area illuminated by the feed  $-\sim60\%$  up to L-band;  $\sim40\%$  in L-band
- ☐ Wire mesh as reflecting surface
- Three sectors with different mesh sizes: 10x10 mm (innermost), 15x15 mm and 20x20 mm (outermost)
- ☐ Effective collecting area (GMRT) 30,000 sq m at lower frequencies 20,000 sq m at highest frequencies
- ☐ Four feeds mounted on a turret

#### **GMRT Antenna Parameters**

Parameter	Value
Focal Length	18.54 m
Physical Aperture	$1590 \text{ m}^2$
f/D ratio	0.412
Mounting	Altitude – Azimuth
<b>Elevation Limits</b>	17 to 110 degrees
Azimuth Range	± 270 degrees
Slew Rates	Alt – 20 degree / min Az - 30 degree / min
Weight of moving structure	82 tons + counter weight of 34 tons
Survival wind speed	133 km/hour
RMS surface error	10 mm (typical)
Tracking and Pointing Error	< 1'arc (up to 20 kmph) Few arc min(> 20 kmph)

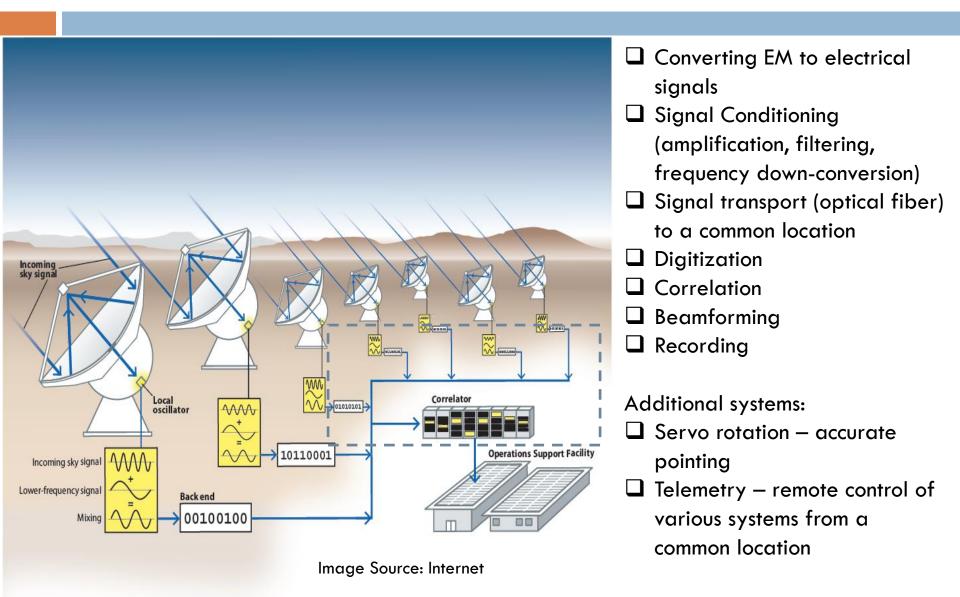


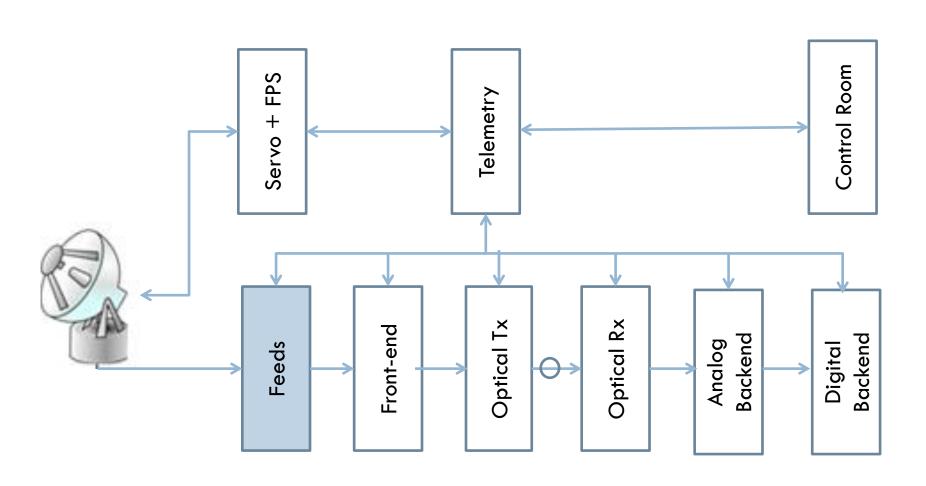
#### Dish and Reflecting Surface



- •7% solidity with 0.55 mm diameter Stainless Steel (SS) wires spot-welded at junction point to form a surface with 10x10 / 15x15 / 20x20 mm wire-grid.
- •Mesh panel supported by SS rope trusses attached to tubular parabolic frame: SMART (Stretched Mesh Attached to Rope Trusses) concept to form the parabola.

#### Radio Telescope: Overall Picture





#### Feeds and Front-end Electronics

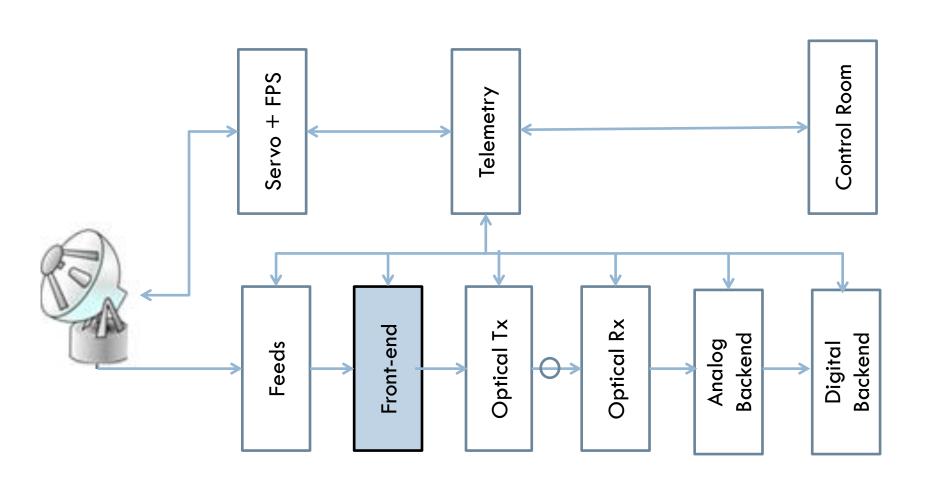




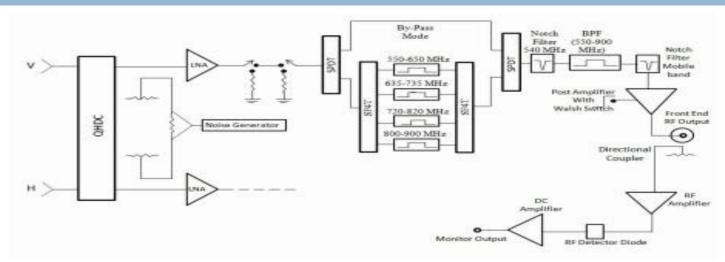


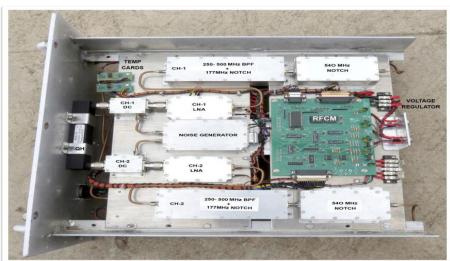


**Image Courtesy: FE Group** 



#### Front-end Electronics

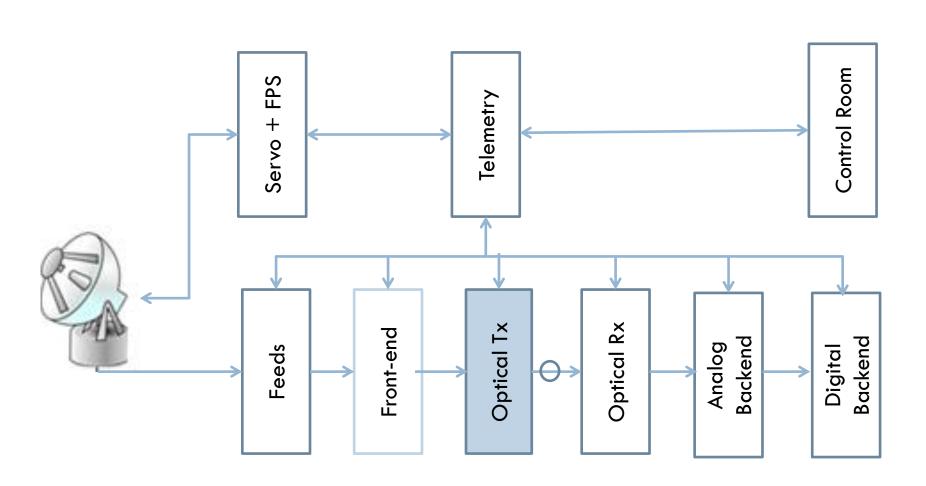






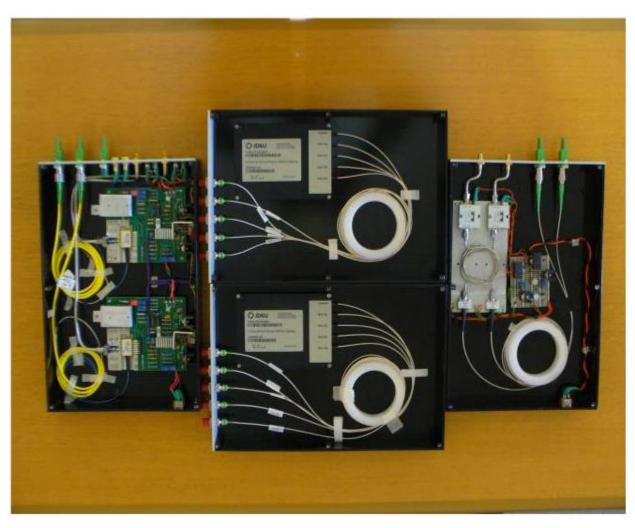
**Front End Box** 

LNA chassis Image Courtesy: FE Group



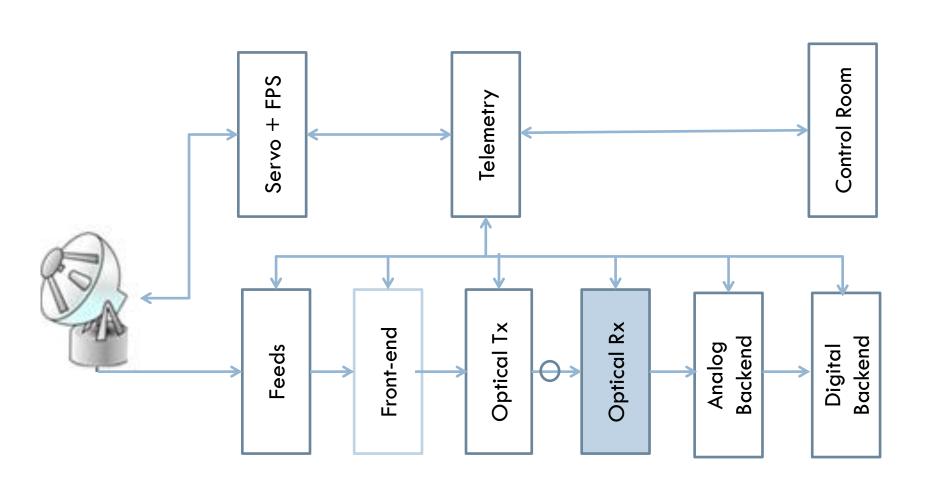
#### Fiber Optics System

- •First radio telescope to use analog fiber optic link for signal transport.
- •Fiber buried at a depth of 1.5m below the ground to reduce the effect of temperature on phase stability of the link.
- •Link distances vary from 200 m to 22 km.
- •Dense wavelength division multiplexing (DWDM) to accommodate multiple data and control channels on a single fiber.

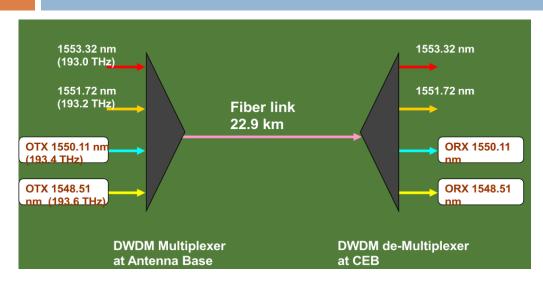


**Image Courtesy: OFC Group** 



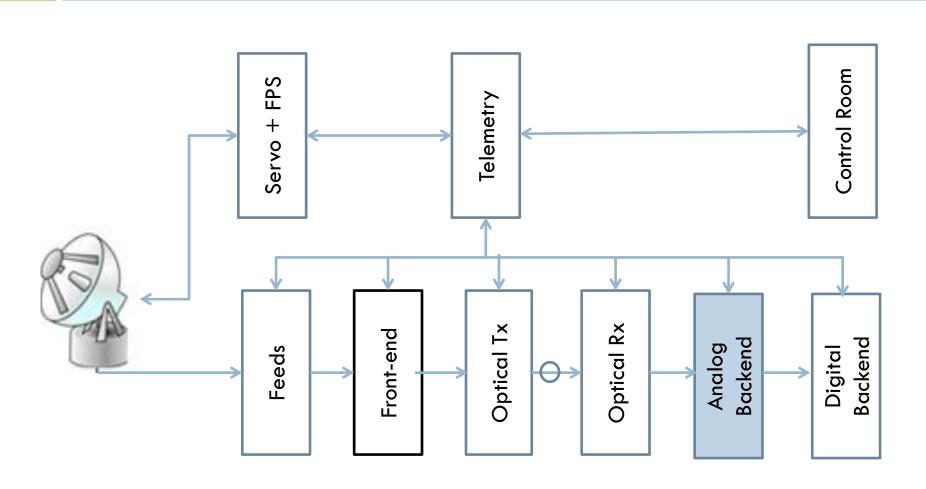


#### **Optical Receiver System**

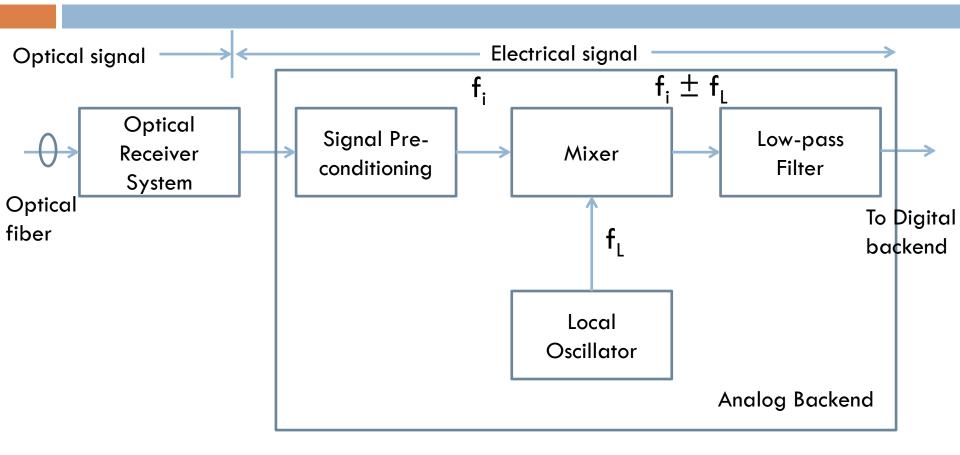








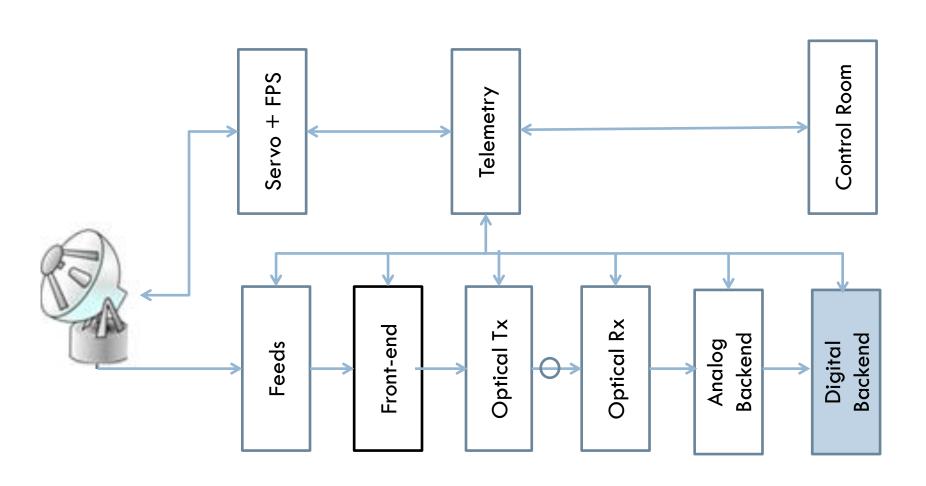
#### Signal Processing in Receiver Room



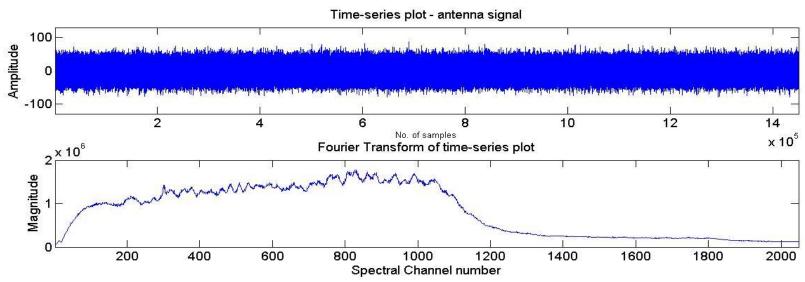
Analog backend amplifies the signal, converts from radio frequency (120 -1450 MHz) to baseband (0-400 MHz) through frequency heterodyning and provides desired bandwidth signal to the digital system

#### Baseband System - Installation





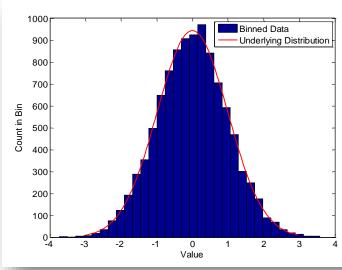
#### **Astronomical Signal**



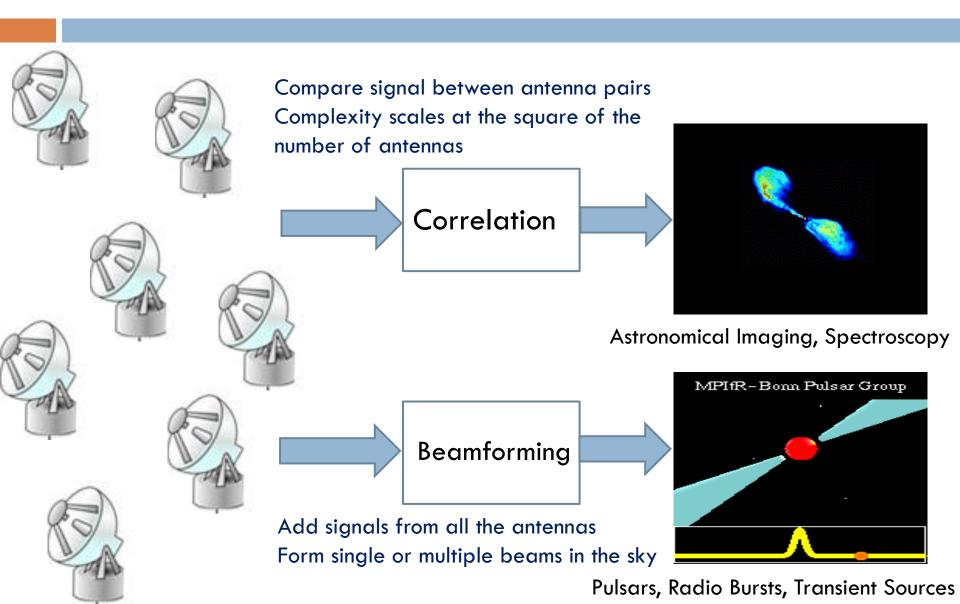
- •Zero mean Gaussian distributed random signal
- •Stationary random process mean and autocorrelation do not change with time (under ideal conditions)
- Noise power measured over bandwidth

$$P = kTB$$
 Watts

K = Boltzmann constant, T = Temperature, B = Bandwidth



#### Correlation & Beamforming



#### Signal Correlation

Radio Source



$$R_{xy}(\tau) = \sum_{n=0}^{T} x[n]y[n+\tau]$$



Digitized signal from Antenna#1



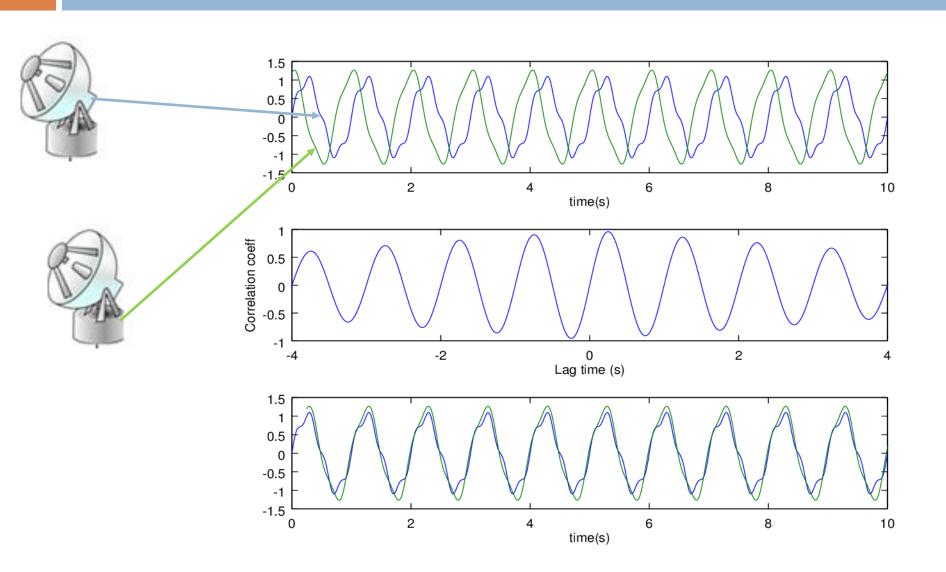
Digitized signal from Antenna#2

Correlation gives information about the similarity between two signals - the common component contributed by the source Cross Correlate signals from antennas after correcting for the delay between them  $(\tau)$ .

For N antennas, n(n-1)/2 cross-correlation operations are required. That makes it really complicated!

A computationally efficient method is to transform signals to frequency domain and multiply

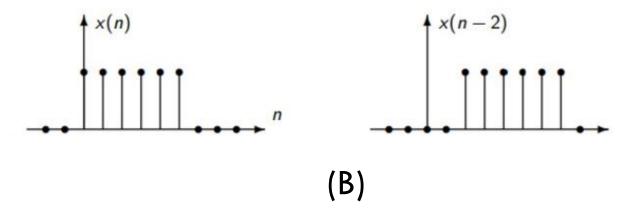
### Correlation as a function of lag



#### **Delay Correction**

(A)

Time delay can be corrected by appropriately sliding the sequences in time domain Useful when the delay is integer multiple of the clock period

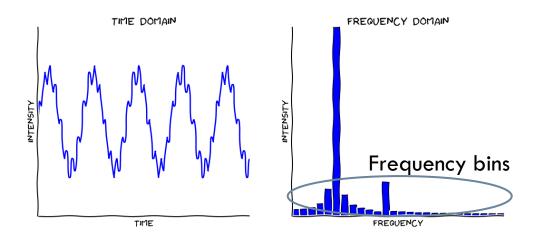


Can also be corrected by phase multiplication in the frequency domain Useful for correcting delays that are sub-multiple of the clock period

$$x(t-t_0) \stackrel{FT}{\longleftrightarrow} e^{-j\omega t_0} X(j\omega)$$

#### Correlation in the Fourier Domain

- ☐ Perform Discrete Fourier Transform (DFT) on the antenna signals
- □ Fast Fourier Transform computationally efficient algorithm for computing DFT ( $N^2$  vs  $Nlog_2N$ )
- $\square$  N-point transform provides a frequency resolution of (sampling freq. / N) Hz.



- Implementation resources and complexity increases with the number of points
- ☐ Frequency resolution depends on the type of observation. Usually the no. of points is of the range of 2048 to 32768 for wideband receivers

Signals in the Fourier domain are multiplied  $X(\omega)Y(\omega)$  for getting the cross-correlation – this is done for each bin of antenna#1 with antenna#2 and so on.

#### Correlation of Complex Signals

- ☐ The output of FFT is complex number
- ☐ Complex multiplication is required for this each operation needs 4 multiplications and 2 additions

$$z_1 z_2 = (x_1 + iy_1)(x_2 + iy_2)$$

$$= x_1 x_2 + ix_1 y_2 + ix_2 y_1 + i^2 y_1 y_2$$

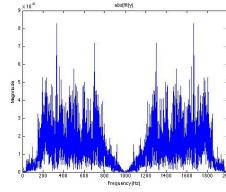
$$= (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)$$

 $Image\ courtesy: http://www.thefouriertransform.com/math/complexmath.php$ 

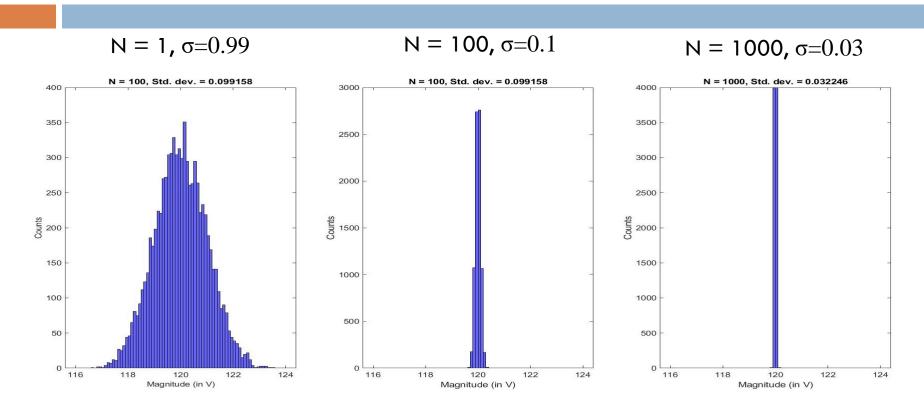
Since the input signal is real, the number of frequency bins contain redundant information are not used for further processing or correlation (conjugate symmetry property of DFT)

$$X(j\omega) = X^*(-j\omega)$$

■ Note: The above property does not hold if the input is a complex signal



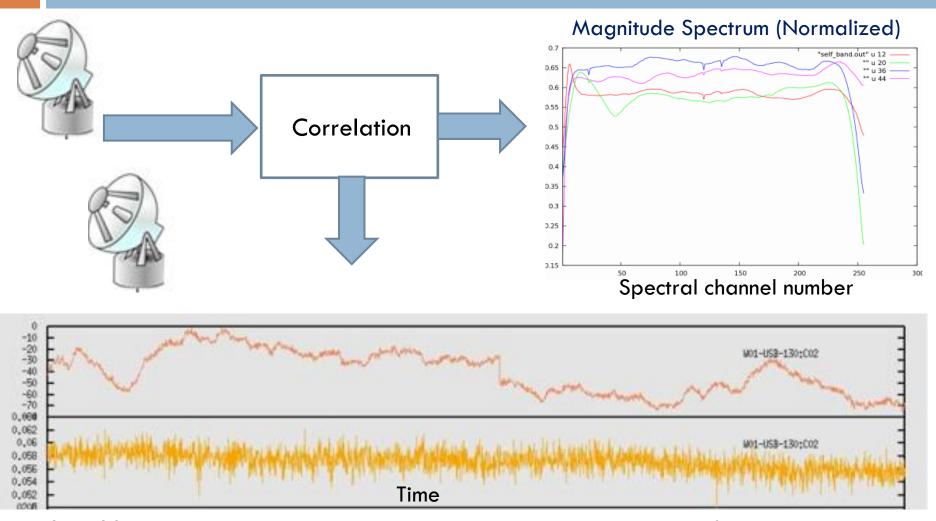
#### Integration



- Averaging leads to reduction in noise variance.
- Signal-to-Noise ratio improves by a factor of N<sup>0.5</sup>
- Deterministic signal adds coherently while noise adds incoherently
- Increases the ability to detect a weak signal buried in noise!

#### Reduces uncertainty in the measurement parameter

#### Correlation: Typical Output



W01-C02 baseline cross-correlation amplitude (normalized) and phase for a single spectral channel (frequency) as a function of time

#### Beamformer

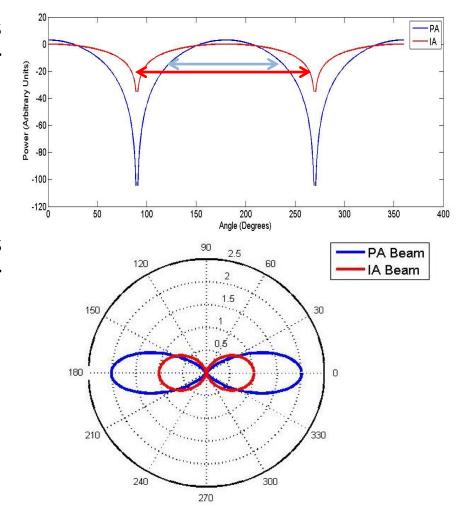
 Power from individual antennas is added to form the incoherent beam (scalar addition)

$$B_i = \sum_{i=0}^{n} (V_1^2 + V_2^2 + \dots + V_N^2)$$

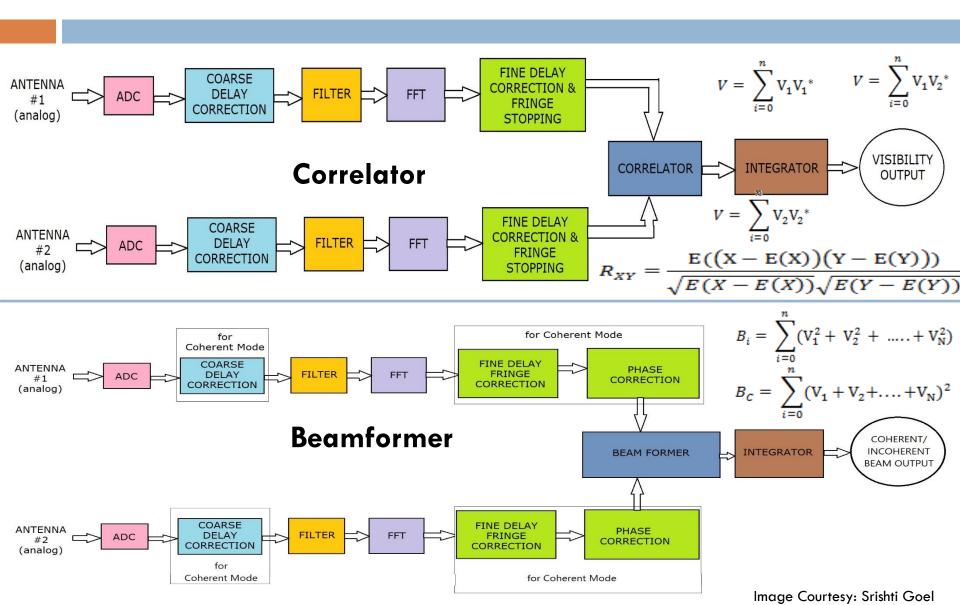
 Voltages from individual antennas are added to form the coherent beam.

$$B_C = \sum_{i=0}^{n} (V_1 + V_2 + \dots + V_N)^2$$

Phase is important!

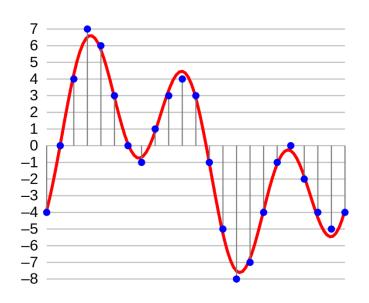


#### Digital Processing: Block Diagram



# Major Challenges for Real-time Processing

- Sampling frequency: 2x the signal bandwidth
  - Faster processing
- Algorithmic complexity grows as N<sup>2</sup>
  - Parallel Computing

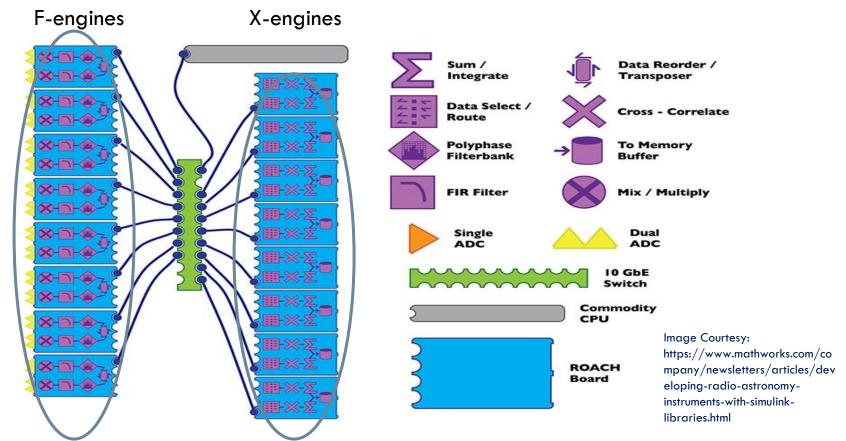


#### 8-element correlation matrix



# Modern Correlators: Example

Correlators consist of signal processing component and networking component



Commonly used method is to carry out digitization, delay correction, FFT in F-engine and multiplication and accumulation in X-engine. High speed data connectivity is required between the F & X engines

### uGMRT Correlators: Installation



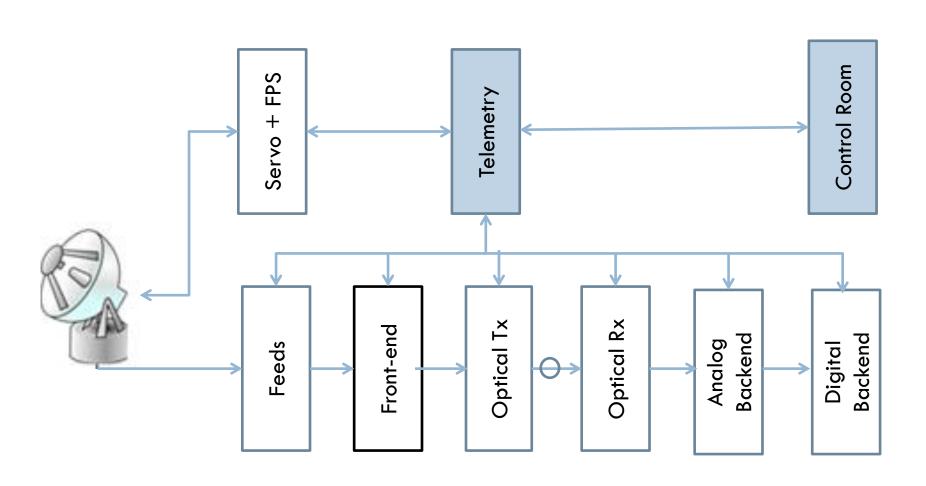
uGMRT correlator and beamformer: a combination of Field Programmable Gate Array (FPGA) and Graphics Processing Unit (GPU).

16-node cluster, computation of the order of  $\sim$ 10TFlops. Power consumption:  $\sim$ 20 kW

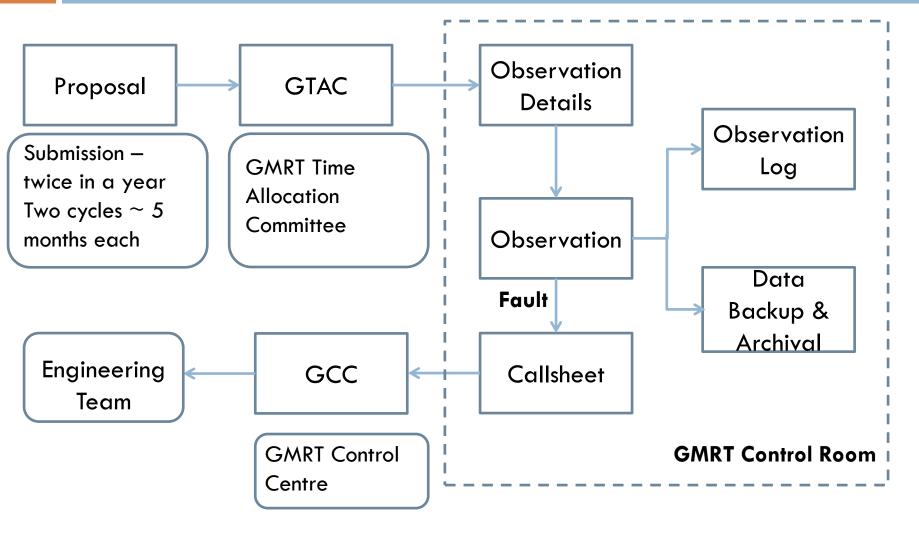




# **GMRT Systems**

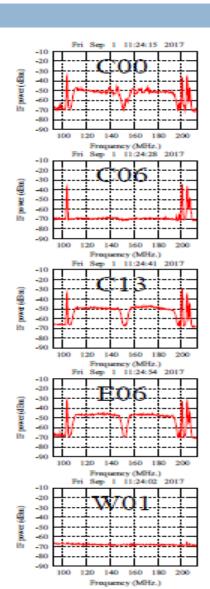


### **Control Room**



NCRA Archival and Proposal System (NAPS) https://naps.ncra.tifr.res.in/naps/login

# Diagnostic Tools



### User Documents http://gmrt.ncra.tifr.res.in/~astrosupp/ Antenna Systems

GMRT Observer's Manual
System Parameters and Current Status
Polarisation observations with GMRT (V2)
Dual band multi-pointing with GMRT (V2)
GMRT Software Backend Documents
uGMRT upgrade status

#### Before Observations

GTAC Schedule [NCRA] [GMRT]
White Slot Request[NCRA] [GMRT]
Command file Creater and Observations Setup
Line Observations Frequency Setup (tune)
Source(s) Rise and Set Time
Observing Time Calculator
VLA Calibrator Search
Dual band multi-pointing coordinates
Online Archive (GOA)

#### **During Observations**

Antenna Tracking Status
Corr band shapes and Project State \*
Gain-amplitude and Phase (rantsol)
Visibility - amplitude and phase (xtract)
Antenna Wind Status
Satellite passes

#### After Observations

LTA to FITS conversion: AIPS help: RFI Plots: GDDP summary: Ondisplay Antenna Tracking Status
Ondisplay History
Feed position status
Pointing Offsets
Wind Monitoring Station
Antenna Wind Status
Temperature Status
Servo data
Electrical Power Status

#### Analog Backend GAB Status IF Band Shapes and Deflection data Gray Plots

#### Digital Backend

Corr band shapes and Project State Fringe Status (rantsol amp-gain) Gain-amplitude and Phase (rantsol) Visibility - amplitude and phase (xtract) Correlator Room Temperature

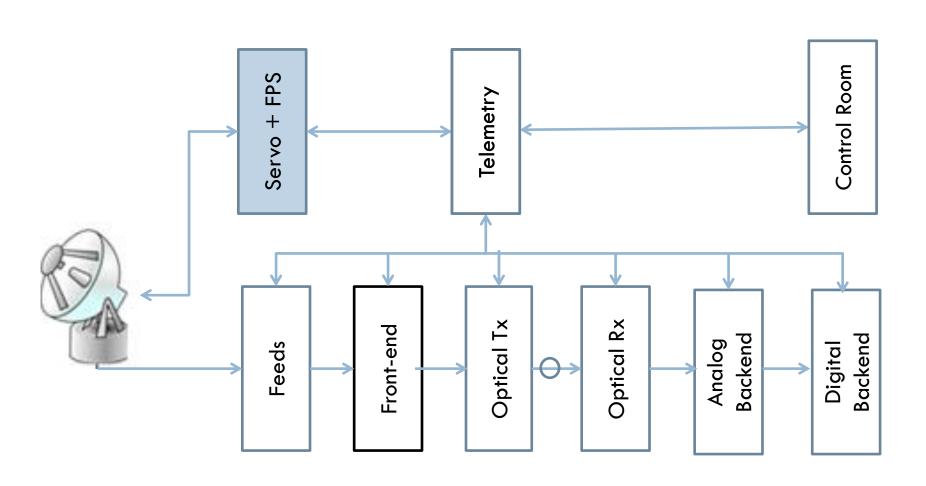
Gmon Tools, Logs

Test Results, Callsheets and Schedules

Useful scripts
Recent Callsheets
GMRT Upgrade Status
Results of Weekly PMQC tests
GDDP, RFI status gray plots
Antenna Beam Width Plots

Schedules and white slot request

# **GMRT Systems**



# Servo System

- Points the antennas to any part of the sky and tracks a source
- •± 270° movement around azimuth axis and 17 to 110° above horizon about elevation axis
- •Slew speed of 30°/ min in Az axis and 20°/ min in El axis
- •RMS tracking and Pointing accuracy: 1 arcmin at 20 kmph wind speed
- Feed rotation and positioning system

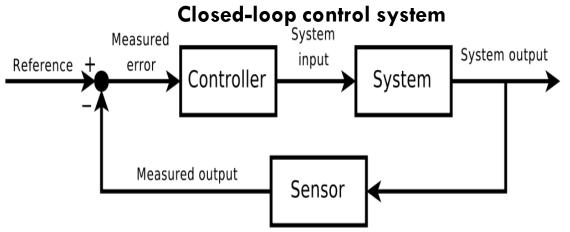






Image Courtesy: Servo Group

# Maintaining and Upkeeping



High Lift Platform for servicing front-end amplifiers, electronics and structural maintenance

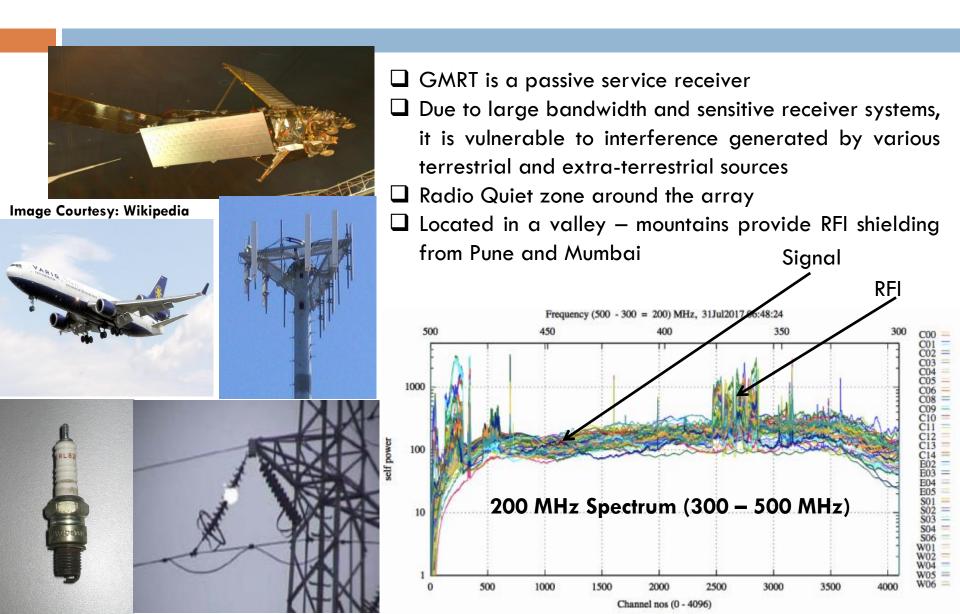
Need a minimum number of antennas (26) for a fruitful scientific observation

Day to day problem solving and longterm maintenance!

Painting: Very important for maintaining the health of the mechanical structure Takes ~3 months to paint one GMRT dish!



### Challenge: Radio Frequency Interference



### RFI at GMRT: Coexistence

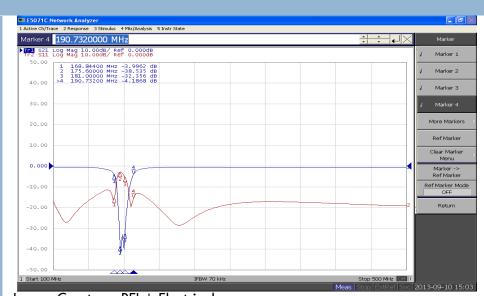


Coexisting with surrounding villages, farmlands and other industries – the potential sources of RFI Image Courtesy: NCRA Archives

# Mitigating Internal & External RFI

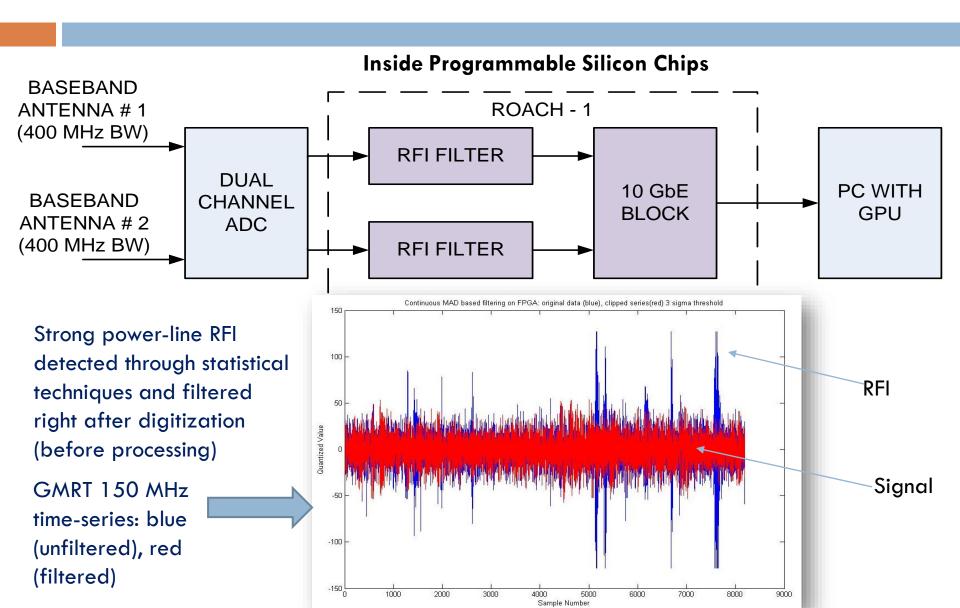




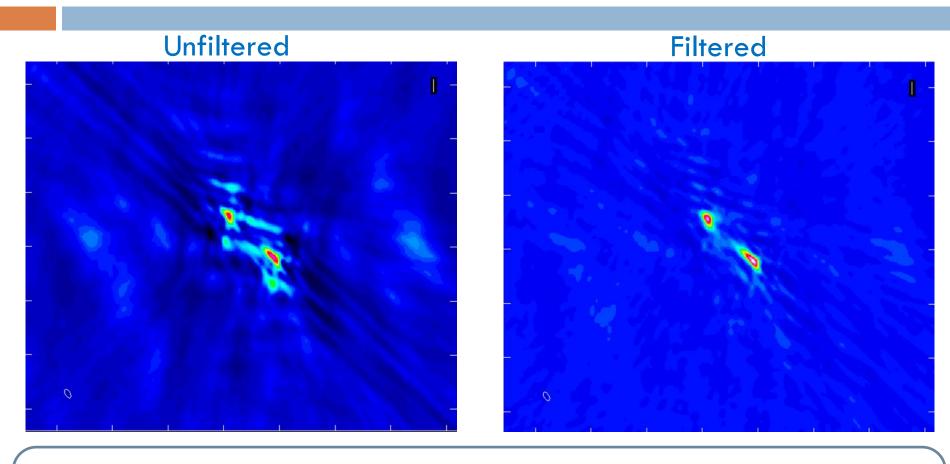




# RFI Mitigation in digital system



# Imaging: Extended Source



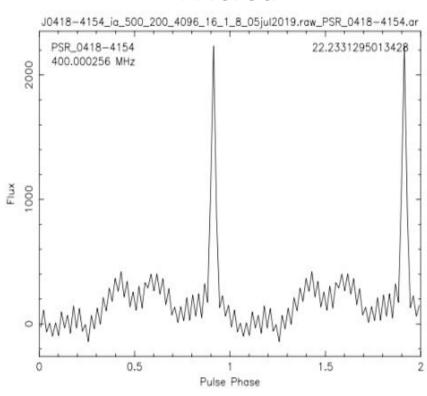
- uGMRT Band-4, 550-850 MHz, 200 MHz RF bandwidth, 2048 spectral channels
- Imaging for baselines < 1 kilolambda ( $\sim$ 0.5 km)
- Noise RMS 1.6 mJy/beam (Unfiltered) 0.52 mJy/beam (Filtered)
- Average Flagging: ~2.5-3%

# Time-domain Astronomy

### Unfiltered

# J0418-4154\_ia\_500\_200\_4096\_16\_1\_8\_05jul2019.raw\_PSR\_0418-4154.ar 8.0193576812744 400.000256 MHz 2000 0.5 1.5 Pulse Phase

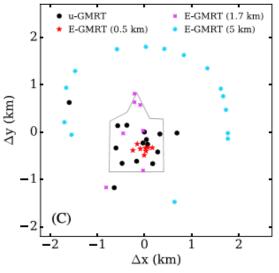
### **Filtered**



- Pulsar (J0418-4154) profile comparison: Incoherent Array beam 4096 spectral channels  $327.68 \mu s$  integration time.
- SNR improvement by factor of 3; Average Flagging  $\sim 3\%$

# Expansions to the existing uGMRT: eGMRT

Adding more antennas for baselines < 5 km



Improved sensitivity

Increase in Field-of-View depends on number of independent beams

The Expanded GMRT (eGMRT)

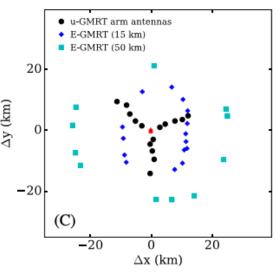
Adding focal plane array on the GMRT antennas



Image Courtesy: K. Hariharan

baselines > 5 km and up to 50 km

Adding more antennas for



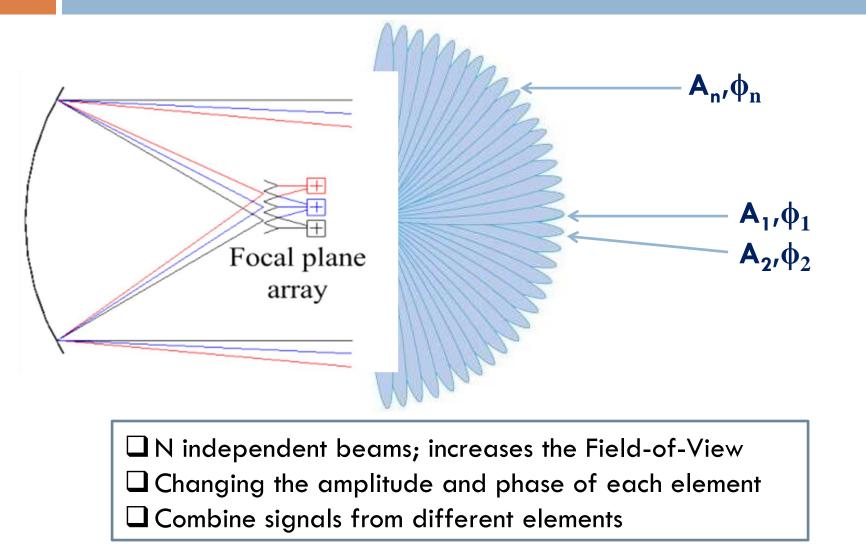
Improved angular resolution, lower confusion limit

Field-of-view is measured in degrees<sup>2</sup>

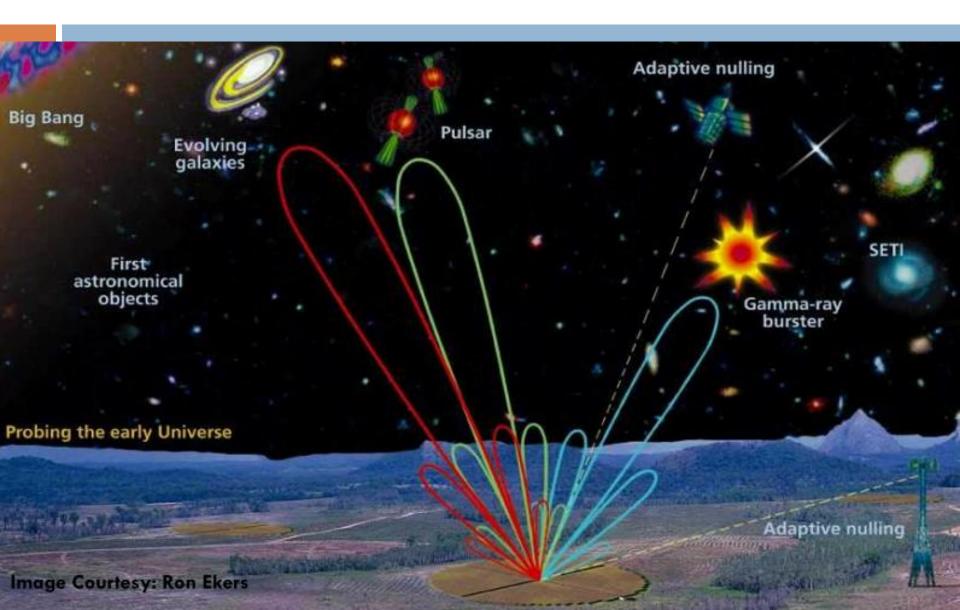
Increased Field-of-View

Source: Patra et al., EGMRT, MNRAS, 2019

# Focal Plane Array Beamforming

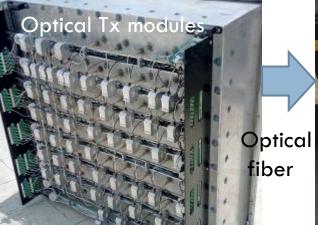


### Forming multiple beams: Advantages



# Experimental eGMRT beamformer





Optical Rx and Analog signal processing modules



144-element L-band Beamformer (1.1 – 1.7 GHz)

32-element, 5-beam, FPGA-based digital beamformer



Acquisition and Control
Computer

### References

- Lecture series on "Techniques of Radio Astronomy and GMRT", February-May 2016 <a href="https://www.gmrt.ncra.tifr.res.in/doc/Lectures/lectures.html">https://www.gmrt.ncra.tifr.res.in/doc/Lectures/lectures.html</a>
- 2. Low Frequency Radio Astronomy, 1997, ttps://www.gmrt.ncra.tifr.res.in/doc/WEBLF/LFRA/i ndex.html
- 3. http://gmrtscienceday.ncra.tifr.res.in/gsd2021/eng ineering\_posters.php